

Structure of a single pseudo-differential equation in a real domain

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We investigate the micro-local structure of a single pseudo-differential equation in a real domain under the assumption that their characteristic variety has singularities of normal crossing type. (Precise conditions are given in the below.)

We note that the micro-local structure of a single pseudo-differential equation of this type has been completely investigated in a complex domain by Kashiwara, Kawai and Oshima [2]. (See Theorem 1 in the below.)

The most interesting phenomenon peculiar to the problem in a real domain is that new invariant (the function h appearing in Theorem 2) appears.

Firstly we recall the theorem which clarifies the structure in a complex domain of a single pseudo-differential equation $\mathcal{M}=\mathcal{P}/\mathcal{G}$ whose characteristic variety V has the singularity of normal crossing type. Precise conditions on \mathcal{M} and V are the following:

- (1) The symbol ideal J of \mathcal{G} is reduced.
- (2) V has the form $V_1 \cup V_2$, where V_1 and V_2 are regular submanifolds of a $(2n-1)$ -dimensional complex contact manifold (X^c, ω) and cross transversally.
- (3) The canonical 1-form ω restricted to $V_1 \cap V_2$ never vanishes.

Then a suitable "quantized" contact transformation will bring micro-locally the generator P of \mathcal{G} to $z_1 D_1 + Q(z', D_{z'})$. Here z' and $D_{z'}$ denote (z_2, \dots, z_n) and $(\frac{\partial}{\partial z_2}, \dots, \frac{\partial}{\partial z_n})$ respectively and $Q(z', D_{z'})$ is a pseudo-differential operator of order at most zero. (Theorem 3 of Kashiwara, Kawai and Oshima [2]). Moreover $\kappa = \sigma_0(Q) / \{\zeta_1, z_1\}|_{V_1 \cap V_2}$ is invariant under contact transformation. Then using this invariant κ we have the following theorem.

THEOREM 1. Assume conditions (1)~(3). Further assume that

- (4) $(d\kappa \wedge \omega)|_{V_1 \cap V_2} \neq 0$.

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Then a suitable "quantized" contact transformation brings micro-locally the generator $P(z, D)$ of \mathcal{G} to $z_1 D_1 + z_2$.

Thus we have seen the micro-local structure of \mathcal{M} satisfying conditions (1)~(4) in a complex domain. So the most important step in the investigation of the structure of the microfunction solutions of \mathcal{M} is to know the micro-local structure of \mathcal{M} in a real domain. Hence in this note we concentrate ourselves to the study of real contact geometry related to the interaction of V_1 and V_2 . As for the investigation of the structure of cohomology groups having microfunction solution sheaves of \mathcal{M} as coefficients, we refer the reader to Kashiwara, Kawai and Oshima [2], [3].

The first case that we are concerned with is the following.

THEOREM 2. *Let $V_j = \{f_j = 0\}$ ($j=1, 2$) be regular hypersurfaces of a complex contact manifold (X^c, ω) , complexification of a purely imaginary contact manifold (X, ω) . Assume following conditions (5) and (6).*

$$(5) \quad \{f_j, f_k^c\} \neq 0 \quad (j, k=1, 2) \quad \text{and} \quad \{f_j, f_k\} \neq 0 \quad (j \neq k).$$

For the definiteness' sake we assume that $\{f_1, f_1^c\} > 0$.

$$(6) \quad V_1 \cap V_1^c = V_2 \cap V_2^c.$$

Then locally we may take f_1 and f_2 so that they satisfy

$$(7) \quad \{f_1, f_1^c\} = 1.$$

$$(8) \quad f_2 = f_1 - h f_2^c, \text{ where } h \text{ is real valued on } X \text{ and} \\ \text{satisfies } \{f_1, h\} = \{f_1^c, h\} = 0.$$

Here $f^c(x, i\eta)$ denotes $\overline{f(\bar{x}, i\bar{\eta})}$ using the canonical coordinate system $(x, i\eta)$ on X .

REMARK. Lemma 2.3.3 in Chapter III of Sato, Kawai and Kashiwara [4] says that we can choose a canonical coordinate system $(x, i\eta)$ on X so that f_1 has the form

$$\frac{\eta_1}{\sqrt{i\eta_n}} + x_1 \sqrt{i\eta_n}$$

near $(x, i\eta) = (0; i(0, \dots, 0, 1))$. Then condition (8) asserts that f_2 has the form

$$\frac{\eta_1}{\sqrt{i\eta_n}} + h x_1 \sqrt{i\eta_n}$$

with $h = h(x_n - \frac{x_1 \eta_1}{2\eta_n}, x_2, \dots, x_n, \eta_2, \dots, \eta_n)$.

PROOF OF THEOREM 2. All the problems in the below are considered in a neighborhood U of x_0 in $V_1 \cap V_1^c = V_2 \cap V_2^c \subset X^c$. Firstly we note that we can find a holomorphic function k so that $f_2 = f_1 - k f_1^c$ with $k \neq 0$ because of conditions (5) and (6). If we define θ_1 so that it satisfies

$$\exp(2i\theta_1) = \frac{k}{\sqrt{kk^c}}$$

and replace f_1 by $\exp(i\theta_1)f_1$, then the corresponding k , denoted by k_1 is real valued on $V_2 \cap V_2^c$. Moreover, by solving the differential equation $\{f_2, k_2\} = 0$ with initial data k_1 on $V_2 \cap V_2^c$ and replacing k_1 by k_2 , we may assume from the beginning that f_2 has the form $f_1 - kf_1^c$ where $k|_{V_1 \cap V_2}$ is real and k is constant along any bicharacteristics of V_2 . In fact, it is sufficient to replace f_1 by $e^{i\theta_2}f_1$ with θ_2 satisfying $\exp(2i\theta_2) = \frac{k_1}{k_2}$.

On the other hand the condition that $\{f_1, f_1^c\} \neq 0$ allows us to find φ which is real valued on X and satisfies $\{\varphi f_1, \varphi f_1^c\} = 1$. (Lemma 2.3.3 in Chapter III of Sato, Kawai and Kashiwara [4]). Therefore we may assume from the beginning that $\{f_1, f_1^c\} = 1$.

Now consider the function $k - k^c$. Since $\{f_2, f_2^c\} \neq 0$, we can find holomorphic functions a and b so that $k - k^c = af_2 + bf_2^c$. Then clearly we have $k - k^c = \frac{a-b^c}{2}f_2 + \frac{b-a^c}{2}f_2^c$, since $k - k^c = -b^c f_2 - a^c f_2^c$.

Let us define h_0 by $k - \frac{a-b^c}{2}f_2$. The function h_0 thus defined clearly coincides with k on $V_2 = \{f_2 = 0\}$ and is real valued on X . It is also clear that $\{f_2, h_0\}|_{V_2} = 0$ because $\{f_2, k\}|_{V_2} = 0$.

Now consider the following first order differential equation (9).

$$(9) \quad \begin{cases} \{f_1^c, h\} = 0 \\ h|_{V_2} = h_0|_{V_2}. \end{cases}$$

Since $\{f_1^c, f_2\} \neq 0$, this constitutes a non-characteristic Cauchy problem for h . Therefore equation (9) admits a unique solution h . By the initial condition given in (9) asserts that $V_2 = \{f_1 - hf_1^c = 0\}$ holds.

Now we want to show that the function h thus defined satisfies condition (8).

In order to see this, we first note the following

$$(10) \quad \{f_1^c, \{f_1, h\}\} = 0.$$

In fact, the Jacobi identity implies that

$$(11) \quad \{f_1^c, \{f_1, h\}\} = \{f_1, \{h, f_1^c\}\} + \{h, \{f_1^c, f_1\}\}.$$

On the other hand equation (9) implies $\{h, f_1^c\} = 0$ and the choice of f_1 explained before asserts $\{f_1^c, f_1\} = -1$. Therefore (11) implies (10).

Moreover we can easily verify that $\{f_1, h\}|_{V_2} = 0$ holds. In fact, $\{f_1, h\}|_{V_2} = \{f_1 - hf_1^c, h\}|_{V_2} + \{hf_1^c, h\}|_{V_2} = 0$ holds, because $\{f_2, h\}|_{V_2} = \{f_2, h_0\}|_{V_2} = 0$ and because $V_2 = \{f_1 - hf_1^c = 0\}$.

Then, using again the fact that $\{f_1^c, f_2\} \neq 0$, we can conclude by the uniqueness of the solution of the non-characteristic Cauchy problem that $\{f_1, h\} = 0$.

Lastly we show that $h = h^c$. As we have proved in the above, $\{f_1, h\} = \{f_1^c, h\} = 0$. Therefore $\{f_1, h - h^c\} = \{f_1^c, h - h^c\} = 0$ holds. On the other hand $(h - h^c)|_{V_2 \cap V_2^c} = (h_0 - h_0^c)|_{V_2 \cap V_2^c} = 0$. Moreover, as we see later in Lemma 3,

$$(12) \quad \det \begin{pmatrix} \{f_1, f_2\} & \{f_1, f_2^c\} \\ \{f_1^c, f_2\} & \{f_1^c, f_2^c\} \end{pmatrix} \neq 0$$

holds.

Therefore the submanifold $V_2 \cap V_2^c$ is non-characteristic with respect to the system of equations $\{f_1, u\} = \{f_1^c, u\} = 0$. This fact implies that $h = h^c$ holds identically because of the uniqueness of solutions for non-characteristic Cauchy problem. This ends the proof of Theorem 2 except for the proof of the relation (12).

LEMMA 3. Assumptions (5) and (6) imply (12).

PROOF. Firstly note that assumptions (5) and (6) allow us to assume that f_1 takes the form $\eta_1 - ix_1 \eta_n$ and that f_2 takes the form $\eta_1 - ix_1 \varphi \eta_n$ with $\varphi = \varphi^c$ near $(x, i\eta) = (0, i(0, \dots, 0, 1))$.

In order to see this, we use the inhomogeneous coordinate system (x, p) , i. e., $p_j = -\eta_j / \eta_n$ ($j=1, \dots, n-1$). Assumptions (5) and (6) then imply that f_2 has the form

$$(p_1 + \phi_1 x_1) \pm i(\phi_2 p_1 + \theta x_1)$$

where $\theta(0) \neq 0$ and ϕ_1, ϕ_2 and θ are real valued on X . Multiplying f_2 by $(1 \pm i\phi_1/\theta)$, we may assume from the beginning that $\phi_1 = 0$.

Now we try to find the required φ by multiplying f_1 and f_2 by $(1 \pm i\alpha_1)$ and $(1 \pm i\alpha_2)$. It is readily verified that α_2/α_1 can be taken to be φ if $\alpha_1(1 - \phi_2 \alpha_2) = \alpha_2 \theta$ and $\alpha_1 \theta = \phi_2 + \alpha_2$ hold for α_1 and α_2 which are real valued on X . Direct calculations will show that it suffices to take

$$\alpha_2 = \frac{1}{\theta} (\phi_2 + \alpha_1)$$

and

$$\alpha_1 = \frac{1 - \phi_2^2 - \theta^2 + \sqrt{(\phi_2^2 + \theta^2 - 1)^2 + 4\phi_2^2}}{2\phi_2}.$$

Note that $\theta(0)^2 - 1 \neq 0$ if $\phi_2(0) = 0$ by assumption (5). So α_1 , hence α_2 , is always well-defined and holomorphic. Clearly α_1 and α_2 are real valued on X . Thus we have verified that f_2 may be chosen to be $\eta_1 - ix_1 \varphi \eta_n$ with $\varphi = \varphi^c$.

Now the direct calculations show that

$$\begin{aligned}
& \det \begin{pmatrix} \{f_1, f_2\} & \{f_1, f_2^c\} \\ \{f_1^c, f_2\} & \{f_1^c, f_2^c\} \end{pmatrix} \\
&= |\{f_1, f_2\}|^2 - |\{f_1^c, f_2\}| \\
&= |(1-\varphi)\eta_n|^2 - |(1+\varphi)\eta_n|^2 + O(|x_1|).
\end{aligned}$$

Since φ is real valued on X , this shows that (12) holds near $(x, i\eta) = (0, i(0, \dots, 0, 1))$.

This ends the proof of Lemma 3 and, at the same time, completes the proof of Theorem 2.

The case treated by Theorem 2 is, so to speak, the case of crossing of two characteristic varieties of Lewy-Mizohata type. The second case we treat in the following Theorem 4 is the case where a characteristic variety of Lewy-Mizohata type and that of de Rham type cross.

Precise statement is the following.

THEOREM 4. *Let V_1 and V_2 be regular hypersurfaces in X^c . Assume that V_1 and V_2 intersect transversally and that $\omega|_{V_1 \cap V_2} \neq 0$. Assume further that $V_1 = \{f_1 = 0\}$ is real and that $V_2 = \{f_2 = 0\}$ is of Lewy-Mizohata type, that is, $f_1 = f_1^c$ and $\{f_2, f_2^c\} \neq 0$. Then we can find a suitable canonical coordinate system on X so that $V_1 = \{x_1 = 0\}$ and $V_2 = \{\eta_1 \pm ix_1 \eta_2 = 0\}$ near $(x; i\eta) = (0; i(0, 1, 0, \dots, 0))$. Here the sign in the defining function of V_2 is chosen according to that of $\{f_2, f_2^c\}$.*

PROOF. Under the assumptions of the theorem the real codimension of $V_2 \cap X$ is 1 in $V_1 \cap X$. This implies the existence of h_1 and h_2 which satisfy the following:

$$(13) \quad h_1 = h_1^c \quad \text{and} \quad h_2 = h_2^c$$

$$(14) \quad V_1 = \{h_1 = 0\} \quad \text{and} \quad V_2 = \{h_1 + ih_2 = 0\}.$$

Since V_2 is of Lewy-Mizohata type, we can find $\varphi \neq 0$ so that $\{\varphi h_1, \varphi h_2\} = \pm 1$ with $\varphi = \varphi^c$. Here the sign is that of $\{h_1, h_2\}$. (Lemma 2.3.3 in Chapter III of Sato, Kawai and Kashiwara [4]). Then $V_1 = \{\varphi h_1 = 0\}$ and $V_2 = \{\varphi h_1 + i\varphi h_2 = 0\}$ with $\{\varphi h_1, \varphi h_2\} = \pm 1$. This immediately implies that a suitable choice of canonical coordinate system of X makes $V_1 = \{x_1 = 0\}$ and $V_2 = \{\eta_1 \pm ix_1 \eta_2 = 0\}$ near $(x, i\eta) = (0; i(0, 1, 0, \dots, 0))$.

Before ending this note we mention the solvability of the pseudo-differential equation $P(x, D_x)u = f$ whose characteristic variety V has the form $V_1 \cup V_2$ where V_j satisfies the conditions posed in Theorem 4. We assume that the symbol ideal J of $\mathcal{G} = \mathcal{L}P$ is reduced.

In this case the most important point that makes the arguments simpler is the following observation:

The generator $P(x, D_x)$ of \mathcal{G} may be chosen to be of the form

$$(15) \quad x_1(D_1 + \alpha x_1 D_2) + \lambda \left(x_2 - \frac{\alpha x_1^2}{2}, x_3, \dots, x_n, D_2, \dots, D_n \right),$$

where $\alpha = \pm i$ and λ is of order at most 0.

This fact is an obvious consequence of Theorem 1, because the lower order term λ of P may be chosen to satisfy $[\lambda, x_1] = [\lambda, D_1 + \alpha x_1 D_2] = 0$.

The expression of P in the form (15) will allow one to construct the fundamental solution for P if the principal symbol $\sigma_0(\lambda)$ of λ restricted to $x_1=0$ does not attain integral values, that is, we can assert that the pseudo-differential equation $P(x, D_x)u=f$ is always solvable micro-locally as long as $\sigma_0(\lambda)(x_2, \dots, x_n, \eta_2, \dots, \eta_n)$ does not attain integral values. In fact, it is possible to give the meaning to $x_1^{\frac{1}{2}}$ as a boundary value of a pseudo-differential operator if λ is of order at most zero and is independent of D_1 (cf. Kashiwara and Kawai [1]). This topic will be discussed elsewhere.

References

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