

Another general inequality for CR -warped products in complex space forms

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(Received February 27, 2002)

Abstract. We prove that every CR -warped product $N_T \times_f N_\perp$ in a complex space form $\tilde{M}^m(4c)$ of constant holomorphic sectional curvature $4c$ satisfies a general inequality: $\|\sigma\|^2 \geq 2p\{\|\nabla(\ln f)\|^2 + \Delta(\ln f)\} + 4hpc$, where $h = \dim_{\mathbf{C}} N_T$, $p = \dim_{\mathbf{R}} N_\perp$, and σ is the second fundamental form. We also completely classify CR -warped products in a complex space form which satisfy the equality case of this inequality.

Key words: CR -submanifold, CR -warped product, squared norm of second fundamental form, warping function, warped product, tensor product.

1. Introduction

A submanifold N of a Kähler manifold is called a CR -submanifold if there exists on N a differentiable holomorphic distribution \mathcal{D} whose orthogonal complementary distribution \mathcal{D}^\perp is a totally real distribution, i.e., $J\mathcal{D}_x^\perp \subset T_x^\perp N$ (cf. [1]). Throughout this paper we denote the complex rank of \mathcal{D} by h and the real rank of \mathcal{D}^\perp by p . The study of CR -submanifolds has been a very active field of research during the last two decades (see, for instance, [1–4, 6–9, 11, 13, 14]).

A CR -submanifold is called a CR -product if it is the direct product $N_T \times N_\perp$ of a holomorphic submanifold N_T and a totally real submanifold N_\perp . It was proved in [3] that a CR -product in a complex Euclidean space is a direct product of a holomorphic submanifold and a totally real submanifold of complex linear subspaces. It was also proved in [3] that there do not exist non-proper CR -products in complex hyperbolic spaces. Moreover, CR -products in the complex projective space CP^{h+p+hp} are obtained from the Segre imbedding in a natural way.

Let B and F be two Riemannian manifolds with Riemannian metrics g_B and g_F , respectively, and f be a positive differentiable function on B . The warped product $B \times_f F$ is the product manifold $B \times F$ equipped with the Riemannian metric $g = g_B + f^2 g_F$. The function f is called the *warping*

function. A warped product is said to be *proper* if its warping function is non-constant. The warping function is the main structure of a warped product manifold. It is well-known that warped products play some important roles in differential geometry as well as in mathematical physics (cf. [12]).

It was shown in [4] that there do not exist warped products of the form: $N_\perp \times_f N_T$ in a Kähler manifold beside *CR*-products, where N_\perp is a totally real submanifold and N_T is a holomorphic submanifold. By contrast, it was also shown that there exist many *CR*-submanifolds which are warped products of the form $N_T \times_f N_\perp$ *by reversing the two factors N_T and N_\perp* . Such a warped product *CR*-submanifold is simply called a *CR-warped product*.

It was known in [4] that every *CR*-warped product satisfies a general inequality: $\|\sigma\|^2 \geq 2p\|\nabla(\ln f)\|^2$, where $\nabla(\ln f)$ is the gradient of $\ln f$ and σ is the second fundamental form. *CR*-warped products in complex space forms satisfying the equality case of this inequality have been completely classified in [4].

In this paper we prove that every *CR*-warped product $N_T \times_f N_\perp$ in a complex space form $\tilde{M}^m(4c)$ satisfies another general inequality:

$$\|\sigma\|^2 \geq 2p\{\|\nabla \ln f\|^2 + \Delta(\ln f)\} + 4hpc, \quad (1.1)$$

where Δ denotes the Laplacian operator of the *CR*-warped product.

For any three natural numbers h, p, α satisfying $\alpha \leq h$, we introduce a map $\phi_\alpha^{hp} : \mathbf{C}_*^h \times S^p \rightarrow \mathbf{C}^{\alpha p+h}$, $\mathbf{C}_*^h = \mathbf{C}^h - \{0\}$, in a way similar to Segre imbedding. We show that each ϕ_α^{hp} is a *CR*-warped product in the complex Euclidean space $\mathbf{C}^{\alpha p+h}$ (Theorem 3.1). We also prove that, up to rigid motions, every *CR*-warped product in a complex Euclidean space satisfying the equality case of inequality (1.1) is one of the ϕ_α^{hp} (Theorem 4.1). Finally, we prove that every *CR*-warped product satisfying the equality in a complex projective space or a complex hyperbolic space is obtained from a ϕ_α^{hp} via the Hopf fibration (Theorems 5.1 and 6.1).

2. Preliminaries

Let M be a Riemannian n -manifold with inner product $\langle \cdot, \cdot \rangle$ and e_1, \dots, e_n be an orthonormal frame fields on M . For differentiable function φ on M , the gradient $\nabla\varphi$ and the Laplacian $\Delta\varphi$ of φ are defined respectively by

$$\langle \nabla\varphi, X \rangle = X\varphi, \quad (2.1)$$

$$\Delta\varphi = \sum_{j=1}^n \{e_j e_j \varphi - (\nabla_{e_j} e_j) \varphi\} \quad (2.2)$$

for vector field X tangent to M , where ∇ is the Riemannian connection on M . If M is isometrically immersed in a Riemannian manifold \tilde{M} . Then the formulas of Gauss and Weingarten for M in \tilde{M} are given respectively by

$$\tilde{\nabla}_X Y = \nabla_X Y + \sigma(X, Y), \quad (2.3)$$

$$\tilde{\nabla}_X \xi = -A_\xi X + D_X \xi \quad (2.4)$$

for vector fields X, Y tangent to N and ξ normal to M , where $\tilde{\nabla}$ denotes the Levi-Civita connection on \tilde{M} , σ the second fundamental form, D the normal connection, and A the shape operator of M in \tilde{M} . The second fundamental form and the shape operator are related by $\langle A_\xi X, Y \rangle = \langle \sigma(X, Y), \xi \rangle$, where $\langle \cdot, \cdot \rangle$ denotes the inner product on M as well as on \tilde{M} .

The *equation of Gauss* is given by

$$\begin{aligned} \tilde{R}(X, Y; Z, W) &= R(X, Y; Z, W) + \langle \sigma(X, Z), \sigma(Y, W) \rangle \\ &\quad - \langle \sigma(X, W), \sigma(Y, Z) \rangle, \end{aligned} \quad (2.5)$$

for X, Y, Z, W tangent to M , where R and \tilde{R} denote the curvature tensors of M and \tilde{M} , respectively.

For the second fundamental form σ , we define its covariant derivative $\bar{\nabla}\sigma$ with respect to the connection on $TM \oplus T^\perp M$ by

$$(\bar{\nabla}_X \sigma)(Y, Z) = D_X(\sigma(Y, Z)) - \sigma(\nabla_X Y, Z) - \sigma(Y, \nabla_X Z). \quad (2.6)$$

The *equation of Codazzi* is

$$(\tilde{R}(X, Y)Z)^\perp = (\bar{\nabla}_X \sigma)(Y, Z) - (\bar{\nabla}_Y \sigma)(X, Z), \quad (2.7)$$

where $(\tilde{R}(X, Y)Z)^\perp$ denotes the normal component of $\tilde{R}(X, Y)Z$.

For a CR -submanifold M in a Kähler manifold \tilde{M} with complex structure J , we denote by ν the complementary orthogonal subbundle of $J\mathcal{D}^\perp$ in the normal bundle $T^\perp M$. Hence we have the following orthogonal direct sum decomposition:

$$T^\perp M = J\mathcal{D}^\perp \oplus \nu, \quad J\mathcal{D}^\perp \perp \nu. \quad (2.8)$$

We recall the following lemma from [3] for later use.

Lemma 2.1 *Let M be a CR-submanifold in a Kähler manifold \tilde{M} . Then we have*

- (1) $\langle \nabla_U Z, X \rangle = \langle JA_{JZ}U, X \rangle,$
- (2) $A_{JZ}W = A_{JW}Z,$ and
- (3) $A_{J\xi}X = -A_\xi JX,$

for any vectors U tangent to M , X, Y in \mathcal{D} , Z, W in \mathcal{D}^\perp , and ξ in ν .

Let (x, u) be a point in a CR-warped product $N_T \times_f N_\perp$. Then, for each $X \in T_x(N_T)$, there is a unique vector in \mathcal{D} at (x, u) whose projection under $\pi_T : N_T \times_f N_\perp \rightarrow N_T$ is the vector X . In this way, one may regard a vector field U on N_T as a vector field U lying in the holomorphic distribution \mathcal{D} in a natural way. Similarly, one may also regard a vector field Z on N_\perp as a vector field in the totally real distribution \mathcal{D}^\perp .

For CR-warped products in Kähler manifolds we have the following [4].

Lemma 2.2 *If $N_T \times_f N_\perp$ is a CR-warped product in a Kähler manifold \tilde{M} , then we have*

- (1) $\langle \sigma(\mathcal{D}, \mathcal{D}), J\mathcal{D}^\perp \rangle = 0;$
- (2) $\nabla_X Z = \nabla_Z X = (X \ln f)Z;$
- (3) $\langle \sigma(JX, Z), JW \rangle = (X \ln f) \langle Z, W \rangle$

for any vector fields X on N_T and Z, W in N_\perp .

Recall that the Riemann curvature tensor of a complex space form $\tilde{M}^m(4c)$ of constant holomorphic sectional curvature $4c$ is given by

$$\begin{aligned} \tilde{R}(X, Y; Z, W) \\ = c \{ \langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle + \langle JX, W \rangle \langle JY, Z \rangle \\ - \langle JX, Z \rangle \langle JY, W \rangle + 2 \langle X, JY \rangle \langle JZ, W \rangle \}. \end{aligned} \quad (2.9)$$

3. A class of CR-warped products in complex Euclidean space

Let $\mathbf{C}_*^h = \mathbf{C}^h - \{0\}$ and $j : S^p \rightarrow \mathbf{E}^{p+1}$ be the inclusion of the unit hypersphere S^p centered at the origin into \mathbf{E}^{p+1} . For a natural number $\alpha \leq h$ and a vector X tangent to \mathbf{C}_*^α at a point $z \in \mathbf{C}_*^\alpha$, we decompose X as $X = X_z^\parallel + X_z^\perp$, where X_z^\parallel is parallel to z and X_z^\perp is perpendicular to z .

For any given three natural numbers h, p, α satisfying $\alpha \leq h$, we introduce a map $\phi_\alpha^{hp} : \mathbf{C}_*^h \times S^p \rightarrow \mathbf{C}^{\alpha p + h}$ by

$$\phi(z, w) = (w_0 z_1, \dots, w_p z_1, \dots, w_0 z_\alpha, \dots, w_p z_\alpha, z_{\alpha+1}, \dots, z_h) \quad (3.1)$$

for $z = (z_1, \dots, z_h) \in \mathbf{C}_*^h$ and $w = (w_0, \dots, w_p) \in S^p \subset \mathbf{E}^{p+1}$ with $\sum_{t=0}^p w_t^2 = 1$.

Theorem 3.1 For $1 \leq \alpha \leq h$ and $p \geq 1$, the map $\phi_\alpha^{hp} : \mathbf{C}_*^h \times S^p \rightarrow \mathbf{C}^{\alpha p+h}$ defined by (3.1) satisfies the following properties:

(1) $\phi_\alpha^{hp} : \mathbf{C}_*^h \times_f S^p \rightarrow \mathbf{C}^{\alpha p+h}$ is an isometric immersion with warping function: $f = \sqrt{\sum_{j=1}^\alpha z_j \bar{z}_j}$.

(2) ϕ_α^{hp} is a CR-warped product.

(3) The second fundamental form σ of ϕ_α^{hp} satisfies the equality:

$$\|\sigma\|^2 = 2p\{\|\nabla(\ln f)\|^2 + \Delta(\ln f)\}. \quad (3.2)$$

Proof. For tangent vector fields X of \mathbf{C}_*^h and Z of S^p , we obtain from (3.1) that

$$X\phi_\alpha^{hp} = (X^{(1)} \otimes j, X_{\alpha+1}, \dots, X_h), \quad (3.3)$$

$$Z\phi_\alpha^{hp} = (z^{(1)} \otimes Z, 0, \dots, 0), \quad (3.4)$$

where

$$X^{(1)} \otimes j = (w_0 X_1, \dots, w_p X_1, \dots, w_0 X_\alpha, \dots, w_p X_\alpha), \quad (3.5)$$

$$z^{(1)} \otimes Z = (Z_0 z_1, \dots, Z_p z_1, \dots, Z_0 z_\alpha, \dots, Z_p z_\alpha), \quad (3.6)$$

$$X^{(1)} = (X_1, \dots, X_\alpha), \quad X^{(2)} = (X_{\alpha+1}, \dots, X_h), \quad (3.7)$$

$$X = (X^{(1)}, X^{(2)}), \quad Z = (Z_0, \dots, Z_p), \quad z^{(1)} = (z_1, \dots, z_\alpha). \quad (3.8)$$

From (3.3) and (3.4) we know that the tangent space of $\mathbf{C}_*^h \times S^p$ at a point (z, w) is spanned by vectors given by (3.3) and (3.4). Since S^p is the unit hypersphere centered at the origin, it follows from (3.3) and (3.4) that the induced metric on $\mathbf{C}_*^h \times S^p$ via ϕ_α^{hp} is the warped product metric $g = g_0 + f^2 g_1$ with warping function $f = \sqrt{\sum_{j=1}^\alpha z_j \bar{z}_j}$, where g_0 and g_1 denote the metrics of \mathbf{C}_*^h and S^p , respectively. This proves statement (1).

It follows from (3.3) that \mathbf{C}_*^h is immersed as a holomorphic submanifold of $\mathbf{C}^{\alpha p+h}$. From (3.3) and (3.4) we also know that S^p is immersed as a totally real submanifold of $\mathbf{C}^{\alpha p+h}$. Hence we have statement (2).

Applying (3.1) and (3.3)–(3.8) yields

$$XY\phi_\alpha^{hp} = (\tilde{\nabla}_{X^{(1)}} Y^{(1)} \otimes j, \tilde{\nabla}_{X^{(2)}} Y^{(2)}), \quad (3.9)$$

$$ZW\phi_\alpha^{hp} = (z^{(1)} \otimes \tilde{\nabla}_Z W, 0, \dots, 0), \quad (3.10)$$

$$XZ\phi_\alpha^{hp} = (X^{(1)} \otimes Z, 0, \dots, 0), \quad (3.11)$$

for vector fields X, Y tangent to \mathbf{C}_*^h and Z, W tangent to S^p , where $\tilde{\nabla}$ denotes the Levi-Civita connection for Euclidean space as well as for complex Euclidean space.

From (3.3)–(3.4) and (3.9)–(3.11), we find

$$\sigma(X, Y) = \sigma(Z, W) = 0, \quad \sigma(X, Z) = (X_{z^{(1)}}^{(1)\perp} \otimes Z, 0, \dots, 0) \quad (3.12)$$

for vector fields X, Y tangent to \mathbf{C}_*^h and Z, W tangent to S^p . Therefore, the squared norm of the second fundamental form is given by

$$\|\sigma\|^2 = \frac{2p(2\alpha - 1)}{f^2}, \quad f^2 = \sum_{j=1}^{\alpha} z_j \bar{z}_j. \quad (3.13)$$

On the other hand, it is straightforward to verify that

$$\|\nabla(\ln f)\|^2 = \frac{1}{f^2}, \quad \Delta(\ln f) = \frac{2(\alpha - 1)}{f^2}. \quad (3.14)$$

By combining (3.13) and (3.14) we obtain statement (3). \square

4. CR-warped products in complex Euclidean space

The purpose of this section is to prove the following.

Theorem 4.1 *Let $\phi : N_T \times_f N_\perp \rightarrow \mathbf{C}^m$ be a CR-warped product in complex Euclidean m -space \mathbf{C}^m . Then we have*

(1) *The squared norm of the second fundamental form of ϕ satisfies*

$$\|\sigma\|^2 \geq 2p\{\|\nabla(\ln f)\|^2 + \Delta(\ln f)\}. \quad (4.1)$$

(2) *If the CR-warped product satisfies the equality case of (4.1), then we have*

(2.a) *N_T is an open portion of \mathbf{C}_*^h ;*

(2.b) *N_\perp is an open portion of S^p ;*

(2.c) *There exists a natural number $\alpha \leq h$ and a complex coordinate system $\{z_1, \dots, z_h\}$ on \mathbf{C}_*^h such that the warping function f is given by $f = \sqrt{\sum_{j=1}^{\alpha} z_j \bar{z}_j}$;*

(2.d) Up to rigid motions of \mathbf{C}^m , the immersion ϕ is given by ϕ_α^{hp} in a natural way; namely, we have

$$\phi(z, w) = (w_0 z_1, \dots, w_p z_1, \dots, w_0 z_\alpha, \dots, w_p z_\alpha, z_{\alpha+1}, \dots, z_h, 0, \dots, 0) \quad (4.2)$$

for $z = (z_1, \dots, z_h) \in \mathbf{C}_*^h$ and $w = (w_0, \dots, w_p) \in S^p \subset \mathbf{E}^{p+1}$.

Proof. Let $N_T \times_f N_\perp$ be a CR-warped product in a complex space form $\tilde{M}^m(4c)$ of constant holomorphic sectional curvature $4c$. Then the equation of Codazzi implies

$$\begin{aligned} \tilde{R}(X, JX, JZ, Z) \\ = \langle D_{JX}\sigma(X, Z) - \sigma(\nabla_{JX}X, Z) - \sigma(X, \nabla_{JX}Z), JZ \rangle \\ - \langle D_X\sigma(JX, Z) - \sigma(\nabla_X JX, Z) - \sigma(JX, \nabla_X Z), JZ \rangle, \end{aligned} \quad (4.3)$$

for vector fields X on N_T and Z on N_\perp . Since N_T is totally geodesic in $N_T \times_f N_\perp$, $\nabla_X Z$ and $\nabla_{JX} Z$ lie in \mathcal{D}^\perp and $\nabla_X JX$ and $\nabla_{JX} X$ lie in \mathcal{D} . Hence, by applying statements (2) and (3) of Lemma 2.2, we get

$$\begin{aligned} 2 \langle X, X \rangle \langle Z, Z \rangle c &= -JX(\langle Z, Z \rangle JX \ln f) - \langle \sigma(X, Z), D_{JX} JZ \rangle \\ &\quad - X(\langle Z, Z \rangle X \ln f) + \langle \sigma(JX, Z), D_X JZ \rangle \\ &\quad + \{(J\nabla_{JX} X) \ln f - (J\nabla_X JX) \ln f\} \langle Z, Z \rangle \\ &\quad + \{(X \ln f)^2 + ((JX \ln f))^2\} \langle Z, Z \rangle. \end{aligned} \quad (4.4)$$

Applying Lemma 2.2 we find

$$\begin{aligned} JX(\langle Z, Z \rangle JX \ln f) + X(\langle Z, Z \rangle X \ln f) \\ = \{(JX)^2 \ln f + X^2 \ln f + 2(JX \ln f)^2 + 2(X \ln f)^2\} \langle Z, Z \rangle. \end{aligned} \quad (4.5)$$

Since $\tilde{M}^m(4c)$ is Kählerian, we have

$$J\nabla_X Z = J\sigma(X, Z) = -A_{JZ}X + D_X JZ. \quad (4.6)$$

Applying (4.6) and statements (1), (2) and (3) of Lemma 2.2, we find

$$\begin{aligned} \langle \sigma(JX, Z), D_X JZ \rangle &= \langle \sigma(JX, Z), J\nabla_X Z \rangle + \langle \sigma(JX, Z), J\sigma(X, Z) \rangle \\ &= (X \ln f)^2 \langle Z, Z \rangle + \langle \sigma(JX, Z), J\sigma(X, Z) \rangle \end{aligned} \quad (4.7)$$

for vector fields X in \mathcal{D} and Z in \mathcal{D}^\perp .

On the other hand, if we denote by $\sigma_\nu(X, Z)$ the ν -component of

$\sigma(X, Z)$, then, by applying statement (3) of Lemma 2.1, we also have

$$\begin{aligned} \langle \sigma(JX, Z), J\sigma(X, Z) \rangle &= \langle \sigma(JX, Z), J\sigma_\nu(X, Z) \rangle \\ &= \langle A_{J\sigma_\nu(X, Z)} JX, Z \rangle = \langle A_{\sigma_\nu(X, Z)} X, Z \rangle = \|\sigma_\nu(X, Z)\|^2. \end{aligned} \quad (4.8)$$

Combining (4.7) and (4.8) yields

$$\langle \sigma(JX, Z), D_X JZ \rangle = (X \ln f)^2 \langle Z, Z \rangle + \|\sigma_\nu(X, Z)\|^2. \quad (4.9)$$

Similarly, we also have

$$\langle \sigma(X, Z), D_{JX} JZ \rangle = -(JX \ln f)^2 \langle Z, Z \rangle - \|\sigma_\nu(X, Z)\|^2. \quad (4.10)$$

Because N_T is a holomorphic submanifold of a Kähler manifold and N_T is totally geodesic in $N_T \times_f N_\perp$, we find

$$J\nabla_{JX} X = \nabla_{JX} JX, \quad J\nabla_X JX = -\nabla_X X. \quad (4.11)$$

Combining (4.4), (4.5) and (4.9)–(4.11) we obtain

$$\begin{aligned} 2 \langle X, X \rangle \langle Z, Z \rangle c &= \{(\nabla_X X + \nabla_{JX} JX) \ln f - X^2 \ln f \\ &\quad - (JX)^2 \ln f\} \langle Z, Z \rangle + 2 \|\sigma_\nu(X, Z)\|^2. \end{aligned} \quad (4.12)$$

Assume that $\{X_1, \dots, X_{2h}\}$ is an orthonormal frame of N_T and $\{Z_1, \dots, Z_p\}$ an orthonormal frame on N_\perp . Then (4.12) implies

$$2 \sum_{j=1}^{2h} \sum_{t=1}^p \|\sigma_\nu(X_j, Z_t)\|^2 = 4hpc - 2p \Delta(\ln f). \quad (4.13)$$

On the other hand, statement (3) of Lemma 2.2 implies

$$\sum_{j=1}^{2h} \sum_{t=1}^p \|\sigma_{J\mathcal{D}^\perp}(X_j, Z_t)\|^2 = p \|\nabla \ln f\|^2, \quad (4.14)$$

where $\sigma_{J\mathcal{D}^\perp}(X_j, Z_t)$ denotes the $J\mathcal{D}^\perp$ -component of $\sigma(X_j, Z_t)$. Combining (4.13) and (4.14) gives

$$2 \|\sigma(\mathcal{D}, \mathcal{D}^\perp)\|^2 = 2p \{\|\nabla \ln f\|^2 + \Delta(\ln f) + 2hc\}, \quad (4.15)$$

where $\|\sigma(\mathcal{D}, \mathcal{D}^\perp)\|^2 = \sum_{j=1}^{2h} \sum_{t=1}^p \|\sigma(X_j, Z_t)\|^2$. Equation (4.15) implies

$$\|\sigma\|^2 \geq 2p \{\|\nabla(\ln f)\|^2 + \Delta(\ln f)\} + 4hpc. \quad (4.16)$$

In particular, if $\tilde{M}^m(4c)$ is the complex Euclidean m -space, inequality (4.16) reduces to inequality (4.1).

Now, let us assume that $\phi : N_T \times_f N_\perp \rightarrow \mathbf{C}^m$ is a CR-warped product satisfying the equality case of (4.1). Then (4.15) and the equality case of (4.1) imply

$$\sigma(\mathcal{D}, \mathcal{D}) = 0, \quad \sigma(\mathcal{D}^\perp, \mathcal{D}^\perp) = 0. \quad (4.17)$$

Since N_T is totally geodesic in $N_T \times_f N_\perp$, the first equation in (4.17) and the totally geodesy of N_T in $N_T \times_f N_\perp$ imply that N_T is isometrically immersed as a totally geodesic holomorphic submanifold of \mathbf{C}^m . Hence, N_T is a open portion of a complex Euclidean h -space \mathbf{C}^h .

For vector fields X in \mathcal{D} and Z, W in \mathcal{D}^\perp , Lemma 2.1 implies

$$\langle \nabla_W Z, X \rangle = \langle JA_{JZ}W, X \rangle = -\langle \sigma(JX, W), JZ \rangle. \quad (4.18)$$

Hence, by applying statement (2) of Lemma 2.2 and (4.18), we find

$$\langle \nabla_W Z, X \rangle = -(X \ln f) \langle Z, W \rangle. \quad (4.19)$$

On the other hand, if we denote by σ^\perp the second fundamental form of N_\perp in $M = N_T \times_f N_\perp$, we get $\langle \sigma^\perp(Z, W), X \rangle = \langle \nabla_W Z, X \rangle$. Combining this with (4.19) yields

$$\sigma^\perp(Z, W) = -\langle Z, W \rangle \nabla \ln f \quad (4.20)$$

Hence, by applying (4.20) and the second equation of (4.17), we see that N_\perp is immersed as a totally umbilical submanifold of \mathbf{C}^m . Hence, N_\perp is an open portion of an ordinary p -sphere S^p (or \mathbf{R} when $p = 1$).

If $p \geq 2$, we may assume that S^p is of radius one, by rescaling the warping function f if necessary. Consequently, $N_T \times_f N_\perp$ is an open portion of $\mathbf{C}^h \times_f S^p$ (or $\mathbf{C}^h \times_f \mathbf{R}$ when $p = 1$). Hence, we may choose a complex Euclidean coordinate system $\{z_1, \dots, z_h\}$ on \mathbf{C}^h and a coordinate system $\{u_1, \dots, u_p\}$ on S^p (or on \mathbf{R} if $p = 1$) so that the metric tensor on $N_T \times_f N_\perp$ is given by

$$g = \sum_{j=1}^h dz_j d\bar{z}_j + f^2 \{ du_1^2 + \cos^2 u_1 du_2^2 + \dots + \cos^2 u_1 \dots \cos^2 u_{p-1} du_p^2 \}, \quad (4.21)$$

where $z_j = x_j + iy_j$, $i = \sqrt{-1}$.

Equation (4.21) and a straightforward computation imply that the Levi-Civita connection on $N_T \times_f N_\perp$ satisfies

$$\nabla_{\frac{\partial}{\partial x_j}} \frac{\partial}{\partial x_k} = \nabla_{\frac{\partial}{\partial x_j}} \frac{\partial}{\partial y_k} = \nabla_{\frac{\partial}{\partial y_j}} \frac{\partial}{\partial y_k} = 0, \quad j, k = 1, \dots, h, \quad (4.22)$$

$$\nabla_{\frac{\partial}{\partial x_j}} \frac{\partial}{\partial u_t} = \frac{f_{x_j}}{f} \frac{\partial}{\partial u_t}, \quad j = 1, \dots, h; \quad t = 1, \dots, p, \quad (4.23)$$

$$\nabla_{\frac{\partial}{\partial y_j}} \frac{\partial}{\partial u_t} = \frac{f_{y_j}}{f} \frac{\partial}{\partial u_t}, \quad j = 1, \dots, h; \quad t = 1, \dots, p, \quad (4.24)$$

$$\nabla_{\frac{\partial}{\partial u_s}} \frac{\partial}{\partial u_t} = -\tan u_s \frac{\partial}{\partial u_t}, \quad 1 \leq s < t \leq p, \quad (4.25)$$

$$\begin{aligned} \nabla_{\frac{\partial}{\partial u_t}} \frac{\partial}{\partial u_t} = & - \prod_{s=1}^{t-1} \cos^2 u_s \sum_{k=1}^h \left(f f_{x_k} \frac{\partial}{\partial x_k} + f f_{y_k} \frac{\partial}{\partial y_k} \right) \\ & + \sum_{q=1}^{t-1} \left(\frac{\sin 2u_q}{2} \prod_{s=q+1}^{t-1} \cos^2 u_s \right) \frac{\partial}{\partial u_q}, \quad t = 1, \dots, p. \end{aligned} \quad (4.26)$$

From equations (4.17), (4.22), (4.25) and (4.26), we know that the immersion ϕ satisfies

$$\phi_{z_j z_k} = \phi_{z_j \bar{z}_k} = \phi_{\bar{z}_j \bar{z}_k} = 0, \quad j, k = 1, \dots, h, \quad (4.27)$$

$$\phi_{u_s u_t} = -\tan u_s \phi_{u_t}, \quad 1 \leq s < t \leq p, \quad (4.28)$$

$$\begin{aligned} \phi_{u_t u_t} = & - \prod_{s=1}^{t-1} \cos^2 u_s \sum_{k=1}^h \left(f f_{x_k} \phi_{x_k} + f f_{y_k} \phi_{y_k} \right) \\ & + \sum_{q=1}^{t-1} \left(\frac{\sin 2u_q}{2} \prod_{s=q+1}^{t-1} \cos^2 u_s \right) \phi_{u_q}, \quad t = 1, \dots, p, \end{aligned} \quad (4.29)$$

where $\phi_{z_j \bar{z}_k} = \partial\phi/\partial z_j \partial \bar{z}_k, \dots$, etc., and

$$\frac{\partial}{\partial z_j} = \frac{1}{2} \left(\frac{\partial}{\partial x_j} - i \frac{\partial}{\partial y_j} \right), \quad \frac{\partial}{\partial \bar{z}_j} = \frac{1}{2} \left(\frac{\partial}{\partial x_j} + i \frac{\partial}{\partial y_j} \right). \quad (4.30)$$

Solving (4.27) gives

$$\phi(z_1, \dots, z_h, u_1, \dots, u_p) = \sum_{j=1}^h A_j(u_1, \dots, u_p) z_j + B(u_1, \dots, u_p) \quad (4.31)$$

for some \mathbf{C}^m -valued functions A_1, \dots, A_h, B . From (4.29) with $t = 1$, we find

$$\phi_{u_1 u_1} = -\frac{1}{2} \sum_{k=1}^h \left(\frac{\partial f^2}{\partial x_k} \phi_{x_k} + \frac{\partial f^2}{\partial y_k} \phi_{y_k} \right) \quad (4.32)$$

Substituting (4.31) into (4.32) yields

$$\sum_{j=1}^h \frac{\partial^2 A_j}{\partial u_1^2} z_j + \frac{\partial^2 B}{\partial u_1^2} = - \sum_{j=1}^h \frac{\partial f^2}{\partial \bar{z}_j} A_j. \quad (4.33)$$

Case (1): $\sum_{j=1}^h (\partial f^2 / \partial \bar{z}_j) A_j$ is independent of z_1, \dots, z_h .

In this case, (4.33) implies

$$\frac{\partial^2 A_j}{\partial u_1^2} = 0, \quad j = 1, \dots, h, \quad (4.34)$$

$$\frac{\partial^2 B}{\partial u_1^2} = - \sum_{j=1}^h \frac{\partial f^2}{\partial \bar{z}_j} A_j. \quad (4.35)$$

Solving (4.34) gives

$$\begin{aligned} A_j(u_1, \dots, u_p) &= D_j(u_2, \dots, u_p) u_1 + E_j(u_2, \dots, u_p), \\ j &= 1, \dots, h, \end{aligned} \quad (4.36)$$

for some vector functions $D_j(u_2, \dots, u_p), E_j(u_2, \dots, u_p)$. Applying (4.31) and (4.36) yields $\langle \phi_{z_j}, \phi_{z_j} \rangle = |D_j|^2 u_1^2 + 2 \langle D_j, E_j \rangle u_1 + |E_j|^2$, where $\langle \cdot, \cdot \rangle$ denotes the standard Euclidean inner product on \mathbf{C}^h . On the other hand, (4.21) gives $\langle \phi_{z_j}, \phi_{z_j} \rangle = 1$ which is independent of u_1 . Thus, we obtain $D_1 = \dots = D_h = 0$. Hence, (4.36) reduces to

$$A_j(u_1, \dots, u_p) = E_j(u_2, \dots, u_p), \quad j = 1, \dots, h, \quad (4.37)$$

From (4.35) and (4.37), we find

$$B = -\frac{1}{2} \sum_{j=1}^h \frac{\partial f^2}{\partial \bar{z}_j} E_j(u_2, \dots, u_p) u_1^2 + F(u_2, \dots, u_p) u_1 + G(u_2, \dots, u_p) \quad (4.38)$$

for some vector functions F, G . Thus, we obtain from (4.31), (4.37) and (4.38) that

$$\phi = \sum_{j=1}^h E_j \left(z_j - \frac{1}{2} \frac{\partial f^2}{\partial \bar{z}_j} u_1^2 \right) + F u_1 + G. \quad (4.39)$$

Substituting (4.39) into (4.28) with $s = 1$ and $1 < t \leq p$ gives

$$\begin{aligned} & \frac{1}{2} \sum_{j=1}^h \frac{\partial f^2}{\partial \bar{z}_j} \frac{\partial E_j}{\partial u_t} u_1 - \frac{\partial F}{\partial u_t} \\ &= \tan u_1 \left\{ \sum_{j=1}^h \frac{\partial E_j}{\partial u_t} z_j - \frac{1}{2} \sum_{j=1}^h \frac{\partial f^2}{\partial \bar{z}_j} \frac{\partial E_j}{\partial u_t} u_1^2 + \frac{\partial F}{\partial u_t} u_1 + \frac{\partial G}{\partial u_t} \right\}. \end{aligned} \quad (4.40)$$

Since E_j, F, G and $\partial f^2 / \partial \bar{z}_j$ are independent on the variable u_1 , equation (4.40) implies $\partial E_j / \partial u_t = \partial F / \partial u_t = \partial G / \partial u_t = 0$ for $j = 1, \dots, h$ and $t = 2, \dots, p$. Thus, E_1, \dots, E_h, F, G are constant vectors in \mathbf{C}^m .

From (4.39) we also have

$$\phi_{u_1} = - \sum_{j=1}^h \frac{\partial f^2}{\partial \bar{z}_j} E_j u_1 + F. \quad (4.41)$$

On the other hand, using (4.21) we find $\langle \phi_{u_1} \phi_{u_1} \rangle = f^2$ which is a non-constant function independent of u_1 . Hence, (4.41) implies

$$\sum_{j=1}^h (\partial f^2 / \partial \bar{z}_j) E_j = 0.$$

Thus, $f^2 = |F|^2$ is constant which contradicts to properness of the CR -warped product.

Case (2): $\sum_{j=1}^h (\partial^2 f^2 / \partial \bar{z}_j) A_j$ depends on z_1, \dots, z_h .

In this case, by taking the derivative of (4.33) with respect to $\partial / \partial z_j$, we find

$$\frac{\partial^2 A_j}{\partial u_1^2} = - \sum_{k=1}^h \frac{\partial^2 f^2}{\partial z_j \partial \bar{z}_k} A_k, \quad j = 1, \dots, h. \quad (4.42)$$

On the other hand, by applying (4.31), we find $\phi_{z_j} = A_j(u_1, \dots, u_p)$. Thus, A_1, \dots, A_h form an orthonormal frame according to (4.21). There-

fore, by using the fact that $\partial^2 A_j / \partial u_1^2$ and A_1, \dots, A_h are independent of z_1, \dots, z_h , we know from (4.42) that $\partial^2 f^2 / \partial z_k \partial \bar{z}_j$, $j, k = 1, \dots, h$, are constant. Thus, we may put

$$\frac{\partial^2 f^2}{\partial z_j \partial \bar{z}_k} = \gamma_{j\bar{k}}, \quad j, k = 1, \dots, h \quad (4.43)$$

for some constants $\gamma_{j\bar{k}}$.

Solving (4.43) yields

$$f^2(z_1, \dots, z_h) = \sum_{j,k=1}^h \gamma_{j\bar{k}} z_j \bar{z}_k + H + K \quad (4.44)$$

for some functions H, K satisfying

$$\frac{\partial H}{\partial \bar{z}_j} = \frac{\partial K}{\partial z_j} = 0, \quad j = 1, \dots, h. \quad (4.45)$$

Equation (4.43) implies that $(\gamma_{j\bar{k}})$ is a Hermitian matrix, that is $\bar{\gamma}_{j\bar{k}} = \gamma_{k\bar{j}}$. Therefore, the Spectral Theorem in matrix theory implies that there is a unitary matrix which diagonalizes $(\gamma_{j\bar{k}})$. Hence, there exists a suitable complex Euclidean coordinate system $\{z_1, \dots, z_h\}$ on \mathbf{C}^h such that (4.44) reduces to the form:

$$f^2 = \sum_{j=1}^h b_j z_j \bar{z}_j + H(z_1, \dots, z_h) + K(z_1, \dots, z_h). \quad (4.46)$$

Since f is a real-valued function, we may put

$$H = X + iY, \quad K = U - iY, \quad (4.47)$$

for some real-valued functions X, Y, U . From (4.45) and (4.47), we obtain the following Cauchy-Riemann equations:

$$\frac{\partial X}{\partial x_j} = -\frac{\partial Y}{\partial y_j}, \quad \frac{\partial Y}{\partial x_j} = \frac{\partial X}{\partial y_j}, \quad \frac{\partial U}{\partial x_j} = \frac{\partial Y}{\partial y_j}, \quad \frac{\partial Y}{\partial x_j} = -\frac{\partial U}{\partial y_j}. \quad (4.48)$$

From (4.48) we find that $H + K = X + U$ is constant, say δ . Hence, (4.46) becomes $f^2 = \sum_{j=1}^h b_j z_j \bar{z}_j + \delta$. We may assume $\delta = 0$ by applying a suitable translation on \mathbf{C}^m if necessary. Thus, we have

$$f^2 = \sum_{j=1}^h a_j^2 z_j \bar{z}_j, \quad (4.49)$$

for some real numbers $a_1, \dots, a_h \geq 0$, since $f > 0$. Combining (4.33) and (4.49) yields

$$\frac{\partial^2 A_j}{\partial u_1^2} = -a_j^2 A_j, \quad j = 1, \dots, h, \quad (4.50)$$

$$\frac{\partial^2 B}{\partial u_1^2} = 0. \quad (4.51)$$

Since $f > 0$, there exists at least one a_j greater than zero. Without loss of generality, we may assume

$$a_1, \dots, a_\alpha > 0, \quad a_{\alpha+1} = \dots = a_h = 0. \quad (4.52)$$

for some natural number $\alpha \leq h$. From (4.50), (4.51) and (4.53), we obtain

$$A_j = D_j(u_2, \dots, u_p) \cos(a_j u_1) + E_j(u_2, \dots, u_p) \sin(a_j u_1), \quad (4.53)$$

$$A_k = D_k(u_2, \dots, u_p) u_1 + E_k(u_2, \dots, u_p), \quad (4.54)$$

$$B = F(u_2, \dots, u_p) u_1 + G(u_2, \dots, u_p) \quad (4.55)$$

for $j = 1, \dots, \alpha$, and $k = \alpha + 1, \dots, h$.

Substituting (4.53), (4.54) and (4.55) into (4.31) gives

$$\begin{aligned} \phi &= \sum_{j=1}^{\alpha} (D_j(u_2, \dots, u_p) \cos(a_j u_1) + E_j(u_2, \dots, u_p) \sin(a_j u_1)) z_j \\ &\quad + \sum_{k=\alpha+1}^h (D_k(u_2, \dots, u_p) u_1 + E_k(u_2, \dots, u_p)) z_k \\ &\quad + F(u_2, \dots, u_p) u_1 + G(u_2, \dots, u_p). \end{aligned} \quad (4.56)$$

By differentiating (4.56) with respect to z_k , we obtain $\phi_{z_k} = D_k u_1 + E_k$ for $k = \alpha + 1, \dots, h$. Thus, $\langle \phi_{z_k}, \phi_{z_k} \rangle = |D_k|^2 u_1^2 + 2 \langle D_k, E_k \rangle + |E_k|^2$. Comparing this with (4.21) yields $D_{\alpha+1} = \dots = D_h = 0$. Therefore, (4.56) becomes

$$\begin{aligned} \phi &= \sum_{j=1}^{\alpha} (D_j(u_2, \dots, u_p) \cos(a_j u_1) + E_j(u_2, \dots, u_p) \sin(a_j u_1)) z_j \\ &\quad + \sum_{k=\alpha+1}^h E_k(u_2, \dots, u_p) z_k + F(u_2, \dots, u_p) u_1 + G(u_2, \dots, u_p). \end{aligned} \quad (4.57)$$

From (4.28) with $s = 1$, $t > 1$ and (4.57), we find

$$\begin{aligned} & \sum_{j=1}^{\alpha} a_j \left(\frac{\partial D_j}{\partial u_t} \sin(a_j u_1) - \frac{\partial E_j}{\partial u_t} \cos(a_j u_1) \right) z_j + \frac{\partial F}{\partial u_t} \\ &= \tan u_1 \left\{ \sum_{j=1}^{\alpha} \left(\frac{\partial D_j}{\partial u_t} \cos(a_j u_1) + \frac{\partial E_j}{\partial u_t} \sin(a_j u_1) \right) z_j \right. \\ & \quad \left. + \sum_{k=\alpha+1}^h \frac{\partial E_k}{\partial u_t} z_k + \frac{\partial F}{\partial u_t} u_1 + \frac{\partial G}{\partial u_t} \right\} \quad (4.58) \end{aligned}$$

which implies $\partial E_k / \partial u_t = \partial F / \partial u_t = \partial G / \partial u_t = 0$, $k = \alpha + 1, \dots, h$, $t = 2, \dots, p$. Hence, $E_{\alpha+1}, \dots, E_h, F$ and G are constant vectors. Equation (4.58) also implies

$$\begin{aligned} & a_j \frac{\partial D_j}{\partial u_t} \sin(a_j u_1) - a_j \frac{\partial E_j}{\partial u_t} \cos(a_j u_1) \\ &= \tan u_1 \left\{ \frac{\partial D_j}{\partial u_t} \cos(a_j u_1) + \frac{\partial E_j}{\partial u_t} \sin(a_j u_1) \right\}, \quad j = 1, \dots, \alpha, \quad (4.59) \end{aligned}$$

which are equivalent to

$$\begin{aligned} & \frac{\partial D_j}{\partial u_t} \{ (a_j - 1) \sin((a_j + 1)u_1) - (a_j + 1) \sin((a_j - 1)u_1) \} \\ &= \frac{\partial E_j}{\partial u_t} \{ (a_j - 1) \cos((a_j + 1)u_1) + (a_j + 1) \cos((a_j - 1)u_1) \} \quad (4.60) \end{aligned}$$

for $j = 1, \dots, \alpha$. By letting $u_1 = 0$, we get $\partial E_j / \partial u_t = 0$. Thus, E_1, \dots, E_{α} are constant vectors. Consequently, we obtain from (4.57) that

$$\begin{aligned} \phi &= \sum_{j=1}^{\alpha} (D_j(u_2, \dots, u_p) \cos(a_j u_1) + E_j \sin(a_j u_1)) z_j \\ & \quad + \sum_{k=\alpha+1}^h E_k z_k + F u_1 + G \quad (4.61) \end{aligned}$$

where E_1, \dots, E_h, F, G are constant vectors. From (4.61) we obtain

$$\phi_{x_j} = D_j \cos(a_j u_1) + E_j \sin(a_j u_1), \quad j = 1, \dots, \alpha, \quad (4.62)$$

$$\phi_{y_j} = i D_j \cos(a_j u_1) + i E_j \sin(a_j u_1), \quad j = 1, \dots, \alpha, \quad (4.63)$$

$$\phi_{x_k} = E_k, \quad k = \alpha + 1, \dots, h, \quad (4.64)$$

$$\phi_{y_k} = iE_k, \quad k = \alpha + 1, \dots, h, \quad (4.65)$$

$$\phi_{u_1} = \sum_{j=1}^{\alpha} a_j (E_j \cos(a_j u_1) - D_j \sin(a_j u_1)) z_j + F. \quad (4.66)$$

By applying (4.21) and (4.62), we find

$$\begin{aligned} 2\delta_{j\ell} = & \langle D_j, D_\ell \rangle (\cos((a_j + a_\ell)u_1) + \cos((a_j - a_\ell)u_1)) \\ & + \langle E_j, E_\ell \rangle (\cos((a_j - a_\ell)u_1) - \cos((a_j + a_\ell)u_1)) \\ & + \langle D_j, E_\ell \rangle (\sin((a_j + a_\ell)u_1) - \sin((a_j - a_\ell)u_1)) \\ & + \langle D_\ell, E_j \rangle (\sin((a_j + a_\ell)u_1) + \sin((a_j - a_\ell)u_1)) \end{aligned} \quad (4.67)$$

for $j, \ell = 1, \dots, \alpha$.

Since $\cos((a_j - a_\ell)u_1)$, $\cos((a_j + a_\ell)u_1)$ and $\sin((a_j + a_\ell)u_1)$ are independent functions, (4.67) implies $\langle D_j, E_\ell \rangle + \langle D_\ell, E_j \rangle = 0$ for $j, \ell = 1, \dots, \alpha$. By setting $u_1 = 0$, (4.67) also yields $\langle D_j, D_\ell \rangle = \delta_{j\ell}$. Thus, by combining these with (4.67), we have $\langle E_j, E_\ell \rangle = \delta_{j\ell}$. Consequently, we obtain

$$\begin{aligned} \langle D_j, D_\ell \rangle = \langle E_j, E_\ell \rangle = \delta_{j\ell}, \quad \langle D_j, E_\ell \rangle + \langle E_j, D_\ell \rangle = 0, \\ 1 \leq j, \ell \leq \alpha. \end{aligned} \quad (4.68)$$

Similarly, by differentiating (4.67) with respect to u_1 , we find

$$a_\ell \langle D_j, E_\ell \rangle + a_j \langle D_\ell, E_j \rangle = 0, \quad j, \ell = 1, \dots, \alpha. \quad (4.69)$$

Also, from (4.21), (4.62) and (4.63), we find

$$\langle D_j, iD_\ell \rangle = \langle E_j, iE_\ell \rangle = \delta_{j\ell}, \quad \langle D_j, iE_\ell \rangle + \langle E_j, iD_\ell \rangle = 0, \quad (4.70)$$

$$a_\ell \langle D_j, iE_\ell \rangle + a_j \langle D_\ell, iE_j \rangle = 0, \quad j, \ell = 1, \dots, \alpha. \quad (4.71)$$

From (4.21) and (4.62)–(4.65), we also have

$$\langle E_k, D_j \rangle = \langle E_k, E_j \rangle = \langle E_k, iD_j \rangle = \langle E_k, iE_j \rangle = 0 \quad (4.72)$$

for $j = 1, \dots, \alpha$; $k = \alpha + 1, \dots, h$.

Equations (4.21), (4.49), (4.66), (4.68) and (4.70) imply

$$\begin{aligned} \sum_{j=1}^{\alpha} a_j^2 z_j \bar{z}_j &= \sum_{j=1}^{\alpha} a_j^2 z_j \bar{z}_j \\ &+ 2 \sum_{j=1}^{\alpha} a_j \langle (E_j \cos(a_j u_1) - D_j \sin(a_j u_1)) z_j, F \rangle + |F|^2. \end{aligned}$$

Thus, we obtain $F = 0$. Therefore, (4.61) reduces to

$$\phi = \sum_{j=1}^{\alpha} (D_j(u_2, \dots, u_p) \cos(a_j u_1) + E_j \sin(a_j u_1)) z_j + \sum_{k=\alpha+1}^h E_k z_k + G, \quad (4.73)$$

where E_1, \dots, E_h, G are constant vectors.

Using (4.60) we know that either D_j is a constant vector or $a_j = 1$. Without loss of generality, we may assume that $a_1, \dots, a_r \neq 1$ and $a_{r+1} = \dots = a_{\alpha} = 1$. Then, D_1, \dots, D_r are constant vectors; hence (4.73) reduces to

$$\begin{aligned} \phi = & \sum_{j=1}^r (D_j \cos(a_j u_1) + E_j \sin(a_j u_1)) z_j \\ & + \sum_{j=r+1}^{\alpha} (D_j(u_2, \dots, u_p) \cos u_1 + E_j \sin u_1) z_j \\ & + \sum_{k=\alpha+1}^h E_k z_k + G, \end{aligned} \quad (4.74)$$

where $D_1, \dots, D_r, E_1, \dots, E_h, G$ are constant vectors satisfying (4.68)–(4.72).

Substituting (4.49) and (4.74) into (4.29) with $t = 2$ yields

$$\begin{aligned} \sum_{j=r+1}^{\alpha} \cos u_1 \frac{\partial^2 D_j}{\partial u_2^2} z_j = & -\cos^2 u_1 \sum_{j=1}^{\alpha} a_j (D_j \cos(a_j u_1) + E_j \sin(a_j u_1)) z_j \\ & - \sin u_1 \cos u_1 \sum_{j=1}^{\alpha} a_j (D_j \sin(a_j u_1) - E_j \cos(a_j u_1)) z_j, \end{aligned} \quad (4.75)$$

where $a_{r+1} = \dots = a_{\alpha} = 1$.

If $r > 1$, then (4.75) implies

$$\begin{aligned} & \cos u_1 (D_j \cos(a_j u_1) + E_j \sin(a_j u_1)) \\ & + \sin u_1 (D_j \sin(a_j u_1) - E_j \cos(a_j u_1)) = 0, \quad j = 1, \dots, r. \end{aligned} \quad (4.76)$$

Since $a_1, \dots, a_r \neq 1$, equation (4.76) implies $D_1 = \dots = D_r = E_1 = \dots = E_r = 0$ which is a contradiction. Therefore, $a_1 = \dots = a_{\alpha} = 1$. Hence, (4.75) implies $\partial^2 D_j / \partial u_2^2 = -D_j$ for $j = 1, \dots, \alpha$. Solving these equations

gives

$$D_j = F_j(u_3, \dots, u_p) \cos u_2 + G_j(u_3, \dots, u_p) \sin u_2.$$

Consequently, (4.73) becomes

$$\begin{aligned} \phi = \sum_{j=1}^{\alpha} \{ & F_j(u_3, \dots, u_p) \cos u_1 \cos u_2 + G_j(u_3, \dots, u_p) \cos u_1 \sin u_2 \\ & + E_j \sin u_1 \} z_j + \sum_{k=\alpha+1}^h E_k z_k + G. \end{aligned} \quad (4.77)$$

By substituting (4.77) into (4.28) with $s = 2$ and $t > 2$, we know that G_j are constant vectors. Continuing these procedures sufficiently many times, we obtain

$$\begin{aligned} & \phi(z_1, \dots, z_h, u_1, \dots, u_p) \\ &= \sum_{j=1}^{\alpha} \left\{ c_1^j \prod_{t=1}^p \cos u_t + c_2^j \sin u_1 + c_3^j \sin u_2 \cos u_1 + \dots \right. \\ & \quad \left. + c_{p+1}^j \sin u_p \prod_{t=1}^{p-1} \cos u_t \right\} z_j + \sum_{k=\alpha+1}^h E_k z_k + G, \end{aligned} \quad (4.78)$$

where c_t^j , E_k , G are constant vectors in \mathbf{C}^m .

Because $N_T \times_f N_{\perp}$ is a CR -warped product in \mathbf{C}^m , we may choose the following initial conditions:

$$\begin{aligned} \phi(1, 0, \dots, 0) &= (1, 0, \dots, 0, \dots, 0), \\ \phi_{z_1}(1, 0, \dots, 0) &= (1, 0, \dots, 0, \dots, 0), \\ \phi_{z_2}(1, 0, \dots, 0) &= (0, 0, \dots, 0, \overbrace{1}^{p+2\text{-th}}, 0, \dots, 0), \\ &\dots\dots\dots \\ \phi_{z_{\alpha}}(1, 0, \dots, 0) &= (0, \dots, 0, \overbrace{1}^{\alpha p - p + \alpha\text{-th}}, 0, \dots, 0), \\ \phi_{z_{\alpha+1}}(1, 0, \dots, 0) &= (0, \dots, 0, \overbrace{1}^{1 + \alpha p + \alpha\text{-th}}, 0, \dots, 0), \\ &\dots\dots\dots \end{aligned}$$

$$\begin{aligned}
\phi_{z_h}(1, 0, \dots, 0) &= (0, \dots, 0, \overbrace{1}^{\alpha p + h\text{-th}}, 0, \dots, 0), \\
\phi_{u_1}(1, 0, \dots, 0) &= (0, 1, \dots, 0, \overbrace{1}^{p+3\text{-th}}, 0, \dots, 0, \overbrace{1}^{1+\alpha p - p + \alpha\text{-th}}, 0, \dots, 0), \\
&\dots\dots\dots \\
\phi_{u_p}(1, 0, \dots, 0) &= (0, \dots, 0, \overbrace{1}^{p+1\text{-th}}, 0, \dots, 0, \overbrace{1}^{\alpha(p+1)\text{-th}}, 0, \dots, 0). \quad (4.79)
\end{aligned}$$

Applying (4.78) and (4.79) gives

$$\phi = (w_0 z_1, \dots, w_p z_1, \dots, w_0 z_\alpha, \dots, w_p z_\alpha, z_{\alpha+1}, \dots, z_h, 0, \dots, 0), \quad (4.80)$$

where

$$\begin{aligned}
w_0 &= \prod_{t=1}^p \cos u_t, \quad w_1 = \sin u_1, \\
w_2 &= \sin u_2 \cos u_1, \dots, w_{p+1} = \sin u_p \prod_{t=1}^{p-1} \cos u_t.
\end{aligned}$$

Since ϕ is an immersion, (4.80) implies that N_T is contained in \mathbf{C}_*^h . \square

5. CR-warped products in CP^m satisfying the equality

In this section we determine CR-warped products in complex projectable spaces which satisfy the equality case of (4.16). In order to do so, we recall briefly a procedure via Hopf fibration to obtain the desired submanifolds of complex projective spaces.

Let $\mathbf{C}^* = \mathbf{C} - \{0\}$. Consider the \mathbf{C}^* -action on \mathbf{C}_*^{m+1} defined by $\lambda \cdot (z_0, \dots, z_m) = (\lambda z_0, \dots, \lambda z_m)$. The set of equivalent classes obtained from this action is denoted by CP^m . Let $\pi(z)$ denote the equivalent class contains z . Then $\pi : \mathbf{C}_*^{m+1} \rightarrow CP^m$ is a surjection. It is well-known that the CP^m admits a complex structure induced from the complex structure on \mathbf{C}^{m+1} and a Kähler metric g with constant holomorphic sectional curvature 4.

Assume $\psi : M \rightarrow CP^m(4)$ is an isometric immersion. Then $\check{M} = \pi^{-1}(M)$ is a \mathbf{C}^* -bundle over M and the lift $\check{\psi} : \pi^{-1}(M) \rightarrow \mathbf{C}_*^{m+1}$ of ψ is an isometric immersion satisfying $\pi \circ \check{\psi} = \psi \circ \pi$. Conversely, if $\check{\psi} : Q \rightarrow \mathbf{C}_*^{m+1}$ is an isometric immersion invariant under the \mathbf{C}^* -action, then there is a unique isometric immersion $\psi : \pi(Q) \rightarrow CP^m(4)$ satisfying $\pi \circ \check{\psi} = \psi \circ \pi$.

There is an alternate way to view the lift $\check{\psi} : \pi^{-1}(N) \rightarrow \mathbf{C}_*^{m+1}$ via the Hopf fibration as follows: Let S^{2m+1} denote the unit hypersphere of \mathbf{C}^{m+1} centered at the origin and let $U(1) = \{\lambda \in \mathbf{C} : \lambda\bar{\lambda} = 1\}$. Then we have a $U(1)$ -action on S^{2m+1} defined by $z \mapsto \lambda z$. At $z \in S^{2m+1} \subset \mathbf{C}^{m+1}$, the vector $V = iz$ is tangent to the flow of this action. The quotient space S^{2m+1}/\sim obtained from this $U(1)$ -action is exactly the $CP^m(4)$. Let $\varphi : S^{2m+1} \rightarrow CP^m(4)$ denote the projection via the $U(1)$ -action. The projection φ is known as the *Hopf fibration*.

When $\psi : M \rightarrow CP^m(4)$ is an isometric immersion, $\hat{M} = \varphi^{-1}(M)$ is a principal circle bundle over M with totally geodesic fibers. The lift $\hat{\psi} : \hat{M} \rightarrow S^{2m+1}$ of ψ is an isometric immersion satisfying $\varphi \circ \hat{\psi} = \psi \circ \varphi$. Conversely, if $\psi : U \rightarrow S^{2m+1}$ is an isometric immersion which is invariant under $U(1)$ -action, there is a unique isometric immersion $\psi_\varphi : \varphi(U) \rightarrow CP^m(4)$ satisfying $\varphi \circ \hat{\psi}_\varphi = \psi_\varphi \circ \varphi$.

For each vector X tangent to $CP^m(4)$, we denote by X^* a horizontal lift of X via the Hopf fibration φ . The horizontal lift X^* and X have the same length, since the Hopf fibration is a Riemannian submersion. Since $V = iz$ generates the vertical subspaces of the Hopf fibration, we have an orthogonal decomposition:

$$T_z S^{2m+1} = (T_{\varphi(z)} CP^m)^* \oplus \text{Span}\{V\}, \quad (5.1)$$

where $(T_{\varphi(z)} CP^m)^*$ is the set consisting of all horizontal lifts of $T_{\varphi(z)} CP^m$ via φ .

For an isometric immersion $\psi : M \rightarrow CP^m(4)$, $\check{M} = \pi^{-1}(M)$ is diffeomorphic to $\mathbf{R}^* \times \hat{M}$ where $\mathbf{R}^* = \mathbf{R} - \{0\}$ and $\hat{M} = \varphi^{-1}(M)$. The immersion $\check{\psi} : \check{M} \rightarrow \mathbf{C}_*^{m+1}$ is related to the immersion $\hat{\psi} : \hat{M} \rightarrow S^{2m+1}$ by

$$\check{\psi}(t, q) = t\hat{\psi}(q), \quad t \in \mathbf{R}^*, \quad q \in \hat{M}. \quad (5.2)$$

Clearly, \check{M} is the *cone over* \hat{M} with the vertex at the origin of \mathbf{C}^{m+1} . The metric \check{g} of \check{M} and the metric \hat{g} of \hat{M} are related by

$$\check{g} = t^2 \hat{g} + dt^2. \quad (5.3)$$

The purpose of this section is to prove the following.

Theorem 5.1 *Let $\phi : N_T \times_f N_\perp \rightarrow CP^m(4)$ be a CR-warped product. Then*

(1) The squared norm of the second fundamental form of ϕ satisfies

$$\|\sigma\|^2 \geq 2p\{\|\nabla(\ln f)\|^2 + \Delta(\ln f)\} + 4hp. \quad (5.4)$$

(2) The CR-warped product satisfies the equality case of (5.4) if and only if

(2.i) N_T is an open portion of complex projective h -space $CP^h(4)$;

(2.ii) N_\perp is an open portion of unit p -sphere S^p ; and

(2.iii) There exists a natural number $\alpha \leq h$ such that, up to rigid motions, ϕ is the composition $\pi \circ \check{\phi}$, where

$$\check{\phi}(z, w) = (w_0 z_0, \dots, w_p z_0, \dots, w_0 z_\alpha, \dots, w_p z_\alpha, z_{\alpha+1}, \dots, z_h, 0, \dots, 0) \quad (5.5)$$

for $z = (z_0, \dots, z_h) \in \mathbf{C}_*^{h+1}$ and $w = (w_0, \dots, w_p) \in S^p \subset \mathbf{E}^{p+1}$, and π being the projection $\pi : \mathbf{C}_*^{m+1} \rightarrow CP^m(4)$.

Proof. Inequality (5.4) is a special case of (4.16).

Let $\phi : M \rightarrow CP^m(4)$ be an isometric immersion and let $\check{\nabla}$, $\hat{\nabla}$ and ∇ denote the Levi-Civita connections on \check{M} , \hat{M} and M respectively. Denote by $\hat{\sigma}$ the second fundamental form of the lift $\hat{\phi} : \hat{M} \rightarrow S^{2m+1}$ of ϕ via Hopf's fibration. Then we have

$$\hat{\nabla}_{X^*} Y^* = (\nabla_X Y)^* - \langle PX, Y \rangle V, \quad (5.6)$$

$$\hat{\nabla}_V X^* = \hat{\nabla}_{X^*} V = (PX)^*, \quad (5.7)$$

$$\hat{\nabla}_V V = 0, \quad (5.8)$$

$$\hat{\sigma}(X^*, Y^*) = (\sigma(X, Y))^*, \quad \hat{\sigma}(X^*, V) = (FX)^*, \quad \hat{\sigma}(V, V) = 0, \quad (5.9)$$

for vector fields X, Y tangent to M , where PX and FX are the tangential and the normal components of JX , respectively.

For a vector U tangent to $\hat{M} \subset S^{2m+1} \subset \mathbf{C}_*^{m+1}$, we extend U to a vector field, also denoted by U , in \mathbf{C}_*^{m+1} by parallel translation along the rays of the cone \check{M} over \hat{M} . We obtain from (5.2) that

$$\check{\sigma}(U, W)(t, q) = \frac{1}{t} \hat{\sigma}(U, W)(q), \quad t \in \mathbf{R}^*, \quad q \in \hat{M}, \quad (5.10)$$

$$\check{\sigma}\left(U, \frac{\partial}{\partial t}\right) = \check{\sigma}\left(\frac{\partial}{\partial t}, \frac{\partial}{\partial t}\right) = 0, \quad (5.11)$$

for U, W tangent to \hat{M} , where $\check{\sigma}$ denotes the second fundamental form of

the lift $\check{\phi} : \check{M} \rightarrow \mathbf{C}_*^{m+1}$ of ϕ via π .

Now suppose that $\phi : M = N_T \times_f N_\perp \rightarrow CP^m(4)$ is a *CR*-warped product in $CP^m(4)$. As before, we denote by \mathcal{D} and \mathcal{D}^\perp the holomorphic and the totally real distributions of $N_T \times_f N_\perp$, respectively. Let $\hat{\mathcal{D}}$ denote the distribution on $\hat{M} = \varphi^{-1}(M)$ spanned by $\mathcal{D}^* = \{X^*, X \in \mathcal{D}\}$ and $V = iz$, where X^* is a horizontal lift of X via φ . Since \mathcal{D} is integrable, (5.6)–(5.8) implies that the distribution $\hat{\mathcal{D}}$ is also integrable. From (5.6)–(5.8), we also know that each leaf of $\hat{\mathcal{D}}$ is a totally geodesic submanifold of \hat{M} .

Let $\hat{\mathcal{D}}^\perp = \{Z^* \in T\hat{M} : Z \in \mathcal{D}^\perp\}$. Then $\hat{\mathcal{D}}^\perp$ is the orthogonal complementary distribution of $\hat{\mathcal{D}}$ in $T\hat{M}$. For vector fields Z, W in \mathcal{D}^\perp , (5.6) implies

$$\hat{\nabla}_{Z^*} W^* = (\nabla_Z W)^*. \quad (5.12)$$

Since \mathcal{D}^\perp is integrable, (5.12) implies that $\hat{\mathcal{D}}^\perp$ is also an integrable distribution.

On the other hand, (4.19) gives

$$\langle \nabla_W Z, X \rangle = -(X \ln f) \langle Z, W \rangle \quad (5.13)$$

for vector field X in \mathcal{D} and Z, W in \mathcal{D}^\perp . Thus, by (5.12), (5.13), $\langle (\nabla_Z W)^*, V \rangle = 0$, and the fact that the Hopf fibration is a Riemannian submersion, we obtain

$$\langle \hat{\nabla}_{Z^*} W^*, X^* \rangle = -(X \ln f) \langle Z^*, W^* \rangle, \quad \langle \hat{\nabla}_{Z^*} W^*, V \rangle = 0. \quad (5.14)$$

Thus, each leaf of $\hat{\mathcal{D}}^\perp$ is an extrinsic sphere in \hat{M} , that is, a totally umbilical submanifold with parallel mean curvature vector. Therefore, by applying a result of Hiepko [10], we know that \hat{M} is also a warped product $\hat{N}_T \times_{\hat{f}} N_\perp^*$, where \hat{N}_T is a leaf of $\hat{\mathcal{D}}$, N_\perp^* a horizontal lift of N_\perp and \hat{f} the warping function. From the definitions of $\hat{\mathcal{D}}$, \hat{N}_T and φ , we may choose \hat{N}_T to be $\varphi^{-1}(N_T)$. Because the Hopf fibration $\varphi : S^{2m+1} \rightarrow CP^m(4)$ is a Riemannian submersion, $d\varphi$ preserves the length of vectors normal to fibres. Therefore, the warping function \hat{f} of $\hat{N}_T \times_{\hat{f}} N_\perp^*$ is given by $f \circ \varphi$. Since \check{M} is the punctured cone over \hat{M} with 0 as its vertex, \check{M} is nothing but $\check{N}_T \times_{\check{f}} \check{N}_\perp$, where $\check{N}_T = \pi^{-1}(N_T)$, $\check{f} = f \circ \pi$, and \check{N}_\perp is a horizontal lift of N_\perp via π . Because \check{N}_\perp is isometric to N_\perp , \check{M} is thus isometric to $\check{N}_T \times_{\check{f}} \check{N}_\perp$. It follows from our constructions that $\check{N}_T = \pi^{-1}(N_T)$ is a holomorphic submanifold of \mathbf{C}_*^{m+1} and \check{N}_\perp is a totally real submanifold in \mathbf{C}_*^{m+1} . Therefore, \check{M} is

isometrically immersed in \mathbf{C}_*^{m+1} as a *CR-warped product*.

Now, suppose that $\phi : M = N_T \times_f N_\perp \rightarrow CP^m(4)$ satisfies the equality case of (5.4). Then we obtain from (4.15) and (4.16) that

$$\sigma(\mathcal{D}, \mathcal{D}) = 0, \quad \sigma(\mathcal{D}^\perp, \mathcal{D}^\perp) = 0. \quad (5.15)$$

Let $\check{\mathcal{D}}$ be the distribution on \check{M} spanned by $\hat{\mathcal{D}}$ and $\partial/\partial t$ and $\check{\mathcal{D}}^\perp$ the orthogonal distribution of $\check{\mathcal{D}}$ in $T\check{M}$. Then $\check{\mathcal{D}}^\perp$ is spanned by vectors in \mathbf{C}_*^{m+1} obtained from $\hat{\mathcal{D}}^\perp$ by parallel translation along rays of the cone \check{M} over \hat{M} . Thus, from (5.9), (5.10) and the second equation of (5.15), we obtain

$$\check{\sigma}(\check{\mathcal{D}}^\perp, \check{\mathcal{D}}^\perp) = 0. \quad (5.16)$$

Also, from (5.9)–(5.11) and the first equation in (5.15), we find

$$\check{\sigma}(\check{\mathcal{D}}, \check{\mathcal{D}}) = 0. \quad (5.17)$$

Therefore, by (4.15), $\pi^{-1}(M) = \check{N}_T \times_{t\check{f}} N_\perp$ satisfies the corresponding equality: $\|\check{\sigma}\|^2 = 2p\{\|\check{\nabla}(\ln t\check{f})\|^2 + \check{\Delta}(\ln t\check{f})\}$ in \mathbf{C}_*^{m+1} . Hence, Theorem 4.1 implies that, up to rigid motions, the immersion of \check{M} is the $\check{\phi}$ defined by (5.5) for some natural number $\alpha \leq h$. Thus, up to rigid motions, ϕ is the composition $\pi \circ \check{\phi}$.

Conversely, it is easy to see that the immersion $\check{\phi}$ defined by (5.5) is a *CR-warped product* $\mathbf{C}_*^{h+1} \times_f S^p$ in \mathbf{C}^{m+1} which is invariant under the \mathbf{C}^* -action. Thus, the projection $\pi \circ \check{\phi}$ of $\check{\phi}$ under $\pi : \mathbf{C}_*^{m+1} \rightarrow CP^m(4)$ defines a submanifold M in $CP^m(4)$. It is easy to verify that M is indeed a *CR-warped product* $CP^h(4) \times_{\tilde{f}} S^p$ in $CP^m(4)$ for some suitable warping function \tilde{f} . Moreover, it follows from (5.9) that the *CR-warped product* M satisfies condition (5.15). Hence, by applying (4.15), we know that $M = \pi(\mathbf{C}_*^{h+1} \times_f S^p)$ satisfies the equality case of (5.4). \square

6. *CR-warped products in complex hyperbolic space*

Let \mathbf{C}_1^{m+1} denote a complex number space endowed with pseudo-Euclidean metric $g_0 = -dz_0 d\bar{z}_0 + \sum_{j=1}^m dz_j d\bar{z}_j$. Put $\mathbf{C}_{*1}^{m+1} = \mathbf{C}_1^{m+1} - \{0\}$. Consider the \mathbf{C}^* -action on \mathbf{C}_{*1}^{m+1} by $\lambda \cdot (z_0, \dots, z_m) = (\lambda z_0, \dots, \lambda z_m)$. The set of equivalent classes obtained from this action is denoted by CH^m . The CH^m admits a natural Kähler structure (J, g) with constant holomorphic sectional curvature -4 . Let $\pi : \mathbf{C}_{*1}^{m+1} \rightarrow CH^m(-4)$ denote the projection

obtained from the \mathbf{C}^* -action.

Just like CP^m , there is an alternate way to view CH^m as follows: Let

$$H_1^{2m+1} = \{z = (z_1, z_2, \dots, z_{m+1}) \in \mathbf{C}_1^{m+1} : \langle z, z \rangle = -1\}, \quad (6.1)$$

where $\langle \cdot, \cdot \rangle$ is the inner product on \mathbf{C}_1^{m+1} induced from the pseudo-Euclidean metric g_0 . H_1^{2m+1} is known as the anti-de Sitter space-time.

We have an $U(1)$ -action on H_1^{2m+1} defined by $z \mapsto \lambda z$. At each point $z \in H_1^{2m+1}$, the vector $V = iz$ is tangent to the flow of the action. The orbit lies in the negative definite plane spanned by z and iz . The quotient space H_1^{2m+1} / \sim under the $U(1)$ -action is exactly the complex hyperbolic space CH^m with constant holomorphic sectional curvature -4 . The complex structure J on CH^m is induced from the canonical complex structure J on \mathbf{C}_1^{m+1} via the Riemannian submersion:

$$\varphi: H_1^{2m+1} \rightarrow CH^m(-4), \quad (6.2)$$

which has totally geodesic fibers. The submersion (6.2) is called the hyperbolic Hopf fibration.

Assume $\psi: M \rightarrow CH^m(-4)$ is an isometric immersion. Then $\check{M} = \pi^{-1}(M)$ is a \mathbf{C}^* -bundle over M and the lift $\check{\psi}: \check{M} \rightarrow \mathbf{C}_{*1}^{m+1}$ of ψ is an isometric immersion satisfying $\pi \circ \check{\psi} = \psi \circ \pi$. Conversely, if $\check{\psi}: \check{M} \rightarrow \mathbf{C}_{*1}^{m+1}$ is an isometric immersion which is invariant under the \mathbf{C}^* -action, then there is an isometric immersion $\psi: \pi(\check{M}) \rightarrow CH^m(-4)$ satisfying $\pi \circ \check{\psi} = \psi \circ \pi$.

For an isometric immersion $\psi: M \rightarrow CH^m(-4)$, $\check{M} = \pi^{-1}(M)$ is diffeomorphic to $\mathbf{R}^* \times \hat{M}$, where $\hat{M} = \varphi^{-1}(M)$. The immersion $\check{\psi}: \check{M} \rightarrow \mathbf{C}_{*1}^{m+1}$ is related to $\hat{\psi}: \hat{M} \rightarrow H_1^{2m+1}$ by

$$\check{\psi}(t, q) = t\hat{\psi}(q), \quad t \in \mathbf{R}^*, \quad q \in \hat{M}. \quad (6.3)$$

The purpose of this section is to prove the following.

Theorem 6.1 *Let $\phi: N_T \times_f N_\perp \rightarrow CH^m(-4)$ be a CR-warped product. Then*

(1) *The squared norm of the second fundamental form of ϕ satisfies*

$$\|\sigma\|^2 \geq 2p\{\|\nabla(\ln f)\|^2 + \Delta(\ln f)\} - 4hp. \quad (6.4)$$

(2) *The CR-warped product satisfies the equality case of (6.4) if and only if*

(2.a) *N_T is an open portion of complex hyperbolic h -space $CH^h(-4)$;*

(2.b) N_\perp is an open portion of unit p -sphere S^p (or \mathbf{R} , when $p = 1$); and

(2.c) up to rigid motions, ϕ is the composition $\pi \circ \check{\phi}$, where either $\check{\phi}$ is given by

$$\check{\phi}(z, w) = (z_0, \dots, z_\beta, w_0 z_{\beta+1}, \dots, w_p z_{\beta+1}, \dots, w_0 z_h, \dots, w_p z_h, 0, \dots, 0) \quad (6.5)$$

for $0 < \beta \leq h$, $z = (z_0, \dots, z_h) \in \mathbf{C}_{*1}^{h+1}$ and $w = (w_0, \dots, w_p) \in S^p$, or $\check{\phi}$ is given by

$$\check{\phi}(z, u) = (z_0 \cosh u, z_0 \sinh u, z_1 \cos u, z_1 \sin u, \dots, \dots, z_\alpha \cos u, z_\alpha \sin u, z_{\alpha+1}, \dots, z_h, 0, \dots, 0) \quad (6.6)$$

for $z = (z_0, \dots, z_h) \in \mathbf{C}_{*1}^{h+1}$ and $u \in \mathbf{R}$, and π being the projection $\pi : \mathbf{C}_{*1}^{m+1} \rightarrow CH^m(-4)$.

Proof. Inequality (6.4) is a special case of (4.16). It follows from (4.15) that a CR-warped product $\phi : M = N_T \times_f N_\perp \rightarrow CH^m(-4)$ satisfies the equality case of (6.4) if and only if the second fundamental form of ϕ satisfies

$$\sigma(\mathcal{D}, \mathcal{D}) = 0, \quad \sigma(\mathcal{D}^\perp, \mathcal{D}^\perp) = 0. \quad (6.7)$$

Suppose that ϕ is a CR-warped product in $CH^m(-4)$ satisfying (6.7). Since N_T is totally geodesic in $N_T \times_f N_\perp$, the first equation of (6.7) implies that each leaf of \mathcal{D} is totally geodesic in $CH^m(-4)$. Thus, N_T is an open portion of $CH^h(-4)$; thus the preimage $\check{N}_T = \pi^{-1}(N_T)$ is an open portion of \mathbf{C}_{*1}^{h+1} . Moreover, by applying an argument similar to the proof of Theorem 5.1 for CR-warped products in CP^m , we know that $\check{M} = \pi^{-1}(M)$ is isometric to $\check{N}_T \times_{t\check{f}} N_\perp$ with $\check{f} = f \circ \pi$ and the lift $\check{\phi} : \check{N}_T \times_{t\check{f}} N_\perp \rightarrow \mathbf{C}_{*1}^{m+1}$ is a CR-warped product in \mathbf{C}_{*1}^{m+1} .

Let $\check{\nabla}$ and $\hat{\nabla}$ denote the Levi-Civita connections on \check{M} and \hat{M} , respectively, and $\hat{\sigma}$ be the second fundamental form of the lift $\hat{\phi} : \hat{M} \rightarrow H_1^{2m+1}$. Then we have [5]

$$\hat{\nabla}_{X^*} Y^* = (\nabla_X Y)^* + \langle PX, Y \rangle V, \quad (6.8)$$

$$\hat{\nabla}_V X^* = \hat{\nabla}_{X^*} V = (PX)^*, \quad \hat{\nabla}_V V = 0, \quad (6.9)$$

$$\hat{\sigma}(X^*, Y^*) = (\sigma(X, Y))^*, \quad \hat{\sigma}(X^*, V) = (FX)^*, \quad \hat{\sigma}(V, V) = 0, \quad (6.10)$$

for vector fields X, Y tangent to M .

For a vector U tangent to $\hat{M} \subset H_1^{2m+1} \subset \mathbf{C}_{*1}^{m+1}$, we extend U to a vector field in \mathbf{C}_{*1}^{m+1} by parallel translation along the rays of the cone \check{M} over \hat{M} . From (6.3), we find

$$\check{\sigma}(U, W)(t, q) = \frac{1}{t} \hat{\sigma}(U, W)(q), \quad t \in \mathbf{R}^*, \quad q \in \hat{M}, \quad (6.11)$$

$$\check{\sigma}\left(U, \frac{\partial}{\partial t}\right) = \check{\sigma}\left(\frac{\partial}{\partial t}, \frac{\partial}{\partial t}\right) = 0, \quad (6.12)$$

for U, W tangent to \hat{M} , where $\check{\sigma}$ denotes the second fundamental form of the lift $\check{\phi} : \check{M} = \check{N}_T \times_{t\check{f}} \check{N}_\perp \rightarrow \mathbf{C}_*^{m+1}$ of ϕ via π .

By applying (6.7)–(6.12), we know that the second fundamental form $\check{\sigma}$ of $\check{\phi}$ satisfies

$$\check{\sigma}(\check{D}, \check{D}) = 0, \quad \sigma(\check{D}^\perp, \check{D}^\perp) = 0, \quad (6.13)$$

where \check{D} and \check{D}^\perp are the holomorphic and the totally real distributions of \check{M} . Since \check{N}_\perp is totally umbilical in the warped product $\check{N}_T \times_{t\check{f}} \check{N}_\perp$, the second equation in (6.13) implies that \check{B}_\perp is immersed as a totally umbilical submanifold in a complex Euclidean subspace. Hence, without loss of generality, we may assume that \check{N}_\perp is an open portion of S^p (or of \mathbf{R} when $p = 1$). Therefore, there is a complex coordinate system $\{z_0, \dots, z_h\}$ on \mathbf{C}_{*1}^{h+1} and a coordinate system on S^p or \mathbf{R} so that the metric on $\check{M} = \check{N}_T \times_{t\check{f}} \check{N}_\perp$ is given by

$$g = -dz_0 d\bar{z}_0 + \sum_{j=1}^h dz_j d\bar{z}_j + \lambda^2 \sum_{s=1}^p \left(\prod_{t=1}^{s-1} \cos^2 u_t du_t^2 \right), \quad (6.14)$$

where $\lambda = \lambda(z_0, \dots, z_h)$ is the corresponding warping function.

From (6.13) and (6.14) we know that $\check{\phi}$ satisfies the following system of partial differential equations:

$$\check{\phi}_{z_j z_k} = \check{\phi}_{z_j \bar{z}_k} = \check{\phi}_{\bar{z}_j \bar{z}_k} = 0, \quad j, k = 0, \dots, h, \quad (6.15)$$

$$\check{\phi}_{u_s u_t} = -\tan u_s \check{\phi}_{u_t}, \quad 1 \leq s < t \leq p, \quad (6.16)$$

$$\begin{aligned} \check{\phi}_{u_t u_t} = & \lambda \prod_{s=1}^{t-1} \cos^2 u_s \left\{ \lambda_{x_0} \check{\phi}_{x_0} + \lambda_{y_0} \check{\phi}_{y_0} - \sum_{k=1}^h \left(\lambda_{x_k} \check{\phi}_{x_k} + \lambda_{y_k} \check{\phi}_{y_k} \right) \right\} \\ & + \sum_{q=1}^{t-1} \left(\frac{\sin 2u_q}{2} \prod_{s=q+1}^{t-1} \cos^2 u_s \right) \check{\phi}_{u_q}, \quad t = 1, \dots, p. \end{aligned} \quad (6.17)$$

Solving (6.15) gives

$$\check{\phi}(z_1, \dots, z_h, u_1, \dots, u_p) = \sum_{j=0}^h A_j(u_1, \dots, u_p) z_j + B(u_1, \dots, u_p) \quad (6.18)$$

for some \mathbf{C}_1^{m+1} -valued functions A_0, \dots, A_h, B . From (6.17) with $t = 1$, we find

$$\check{\phi}_{u_1 u_1} = \frac{1}{2} \left(\frac{\partial \lambda^2}{\partial x_0} \check{\phi}_{x_0} + \frac{\partial \lambda^2}{\partial y_0} \check{\phi}_{y_0} \right) - \frac{1}{2} \sum_{k=1}^h \left(\frac{\partial \lambda^2}{\partial x_k} \check{\phi}_{x_k} + \frac{\partial \lambda^2}{\partial y_k} \check{\phi}_{y_k} \right) \quad (6.19)$$

Substituting (6.18) into (6.19) yields

$$\sum_{j=0}^h \frac{\partial^2 A_j}{\partial u_1^2} z_j + \frac{\partial^2 B}{\partial u_1^2} = \frac{1}{2} \frac{\partial \lambda^2}{\partial \bar{z}_0} A_0 - \frac{1}{2} \sum_{j=1}^h \frac{\partial \lambda^2}{\partial \bar{z}_j} A_j. \quad (6.20)$$

Applying the same argument as for *Case (1)* in the proof of Theorem 4.1, we know that $\sum_{j=0}^h (\partial A_j / \partial u_1) A_j$ cannot be independent on all z_0, \dots, z_h . Then, by applying an argument similar to that given in the first part of *Case (2)* of the proof of Theorem 4.1, we know that the warping function λ can be chosen to be

$$\lambda = \left(\sum_{j=0}^n a_j^2 z_j \bar{z}_j \right)^{1/2}, \quad a_0, \dots, a_h \geq 0. \quad (6.21)$$

Substituting (6.21) into (6.20) gives

$$\frac{\partial^2 A_0}{\partial u_1^2} = a_0^2 A_0, \quad \frac{\partial^2 A_j}{\partial u_1^2} = -a_j^2 A_j, \quad j = 1, \dots, h, \quad (6.22)$$

$$\frac{\partial^2 B}{\partial u_1^2} = 0. \quad (6.23)$$

Case (a): $a_0 = \dots = a_\beta = 0, a_{\beta+1}, \dots, a_h > 0$ for some β satisfying $0 < \beta \leq h$.

In this case, by applying an argument similar to *Case (2)* in the proof of Theorem 4.1, we may obtain

$$\check{\phi} = \sum_{j=0}^{\beta} \left\{ c_1^j \prod_{t=1}^p \cos u_t + c_2^j \sin u_1 + c_3^j \sin u_2 \cos u_1 + \cdots \right. \\ \left. + c_{p+1}^j \sin u_p \prod_{t=1}^{p-1} \cos u_t \right\} z_j + \sum_{k=\beta+1}^h E_k z_k + G, \quad (6.24)$$

for some constant vectors c_t^j , E_k , G in \mathbf{C}_{*1}^{m+1} . Thus, after choosing some suitable initial conditions, we obtain (6.5).

Case (b): $a_0, \dots, a_\alpha > 0$, $a_{\alpha+1} = \cdots = a_h = 0$ for some natural number $\alpha \leq h$.

In this case, after solving (6.22) and (6.23), we find

$$\begin{aligned} A_0 &= D_0(u_2, \dots, u_p) \cosh(a_0 u_1) + E_0(u_2, \dots, u_p) \sinh(a_0 u_1), \\ A_j &= D_j(u_2, \dots, u_p) \cos(a_j u_1) + E_j(u_2, \dots, u_p) \sin(a_j u_1), \\ A_k &= D_k(u_2, \dots, u_p) u_1 + E_k(u_2, \dots, u_p), \\ B &= F(u_2, \dots, u_p) u_1 + G(u_2, \dots, u_p) \end{aligned} \quad (6.25)$$

for some vector functions $D_0, \dots, D_h, E_0, \dots, E_h, G, G$, where $j = 1, \dots, \alpha$, and $k = \alpha + 1, \dots, h$. Substituting (4.53), (4.54) and (4.55) into (4.31) gives

$$\check{\phi} = (D_0(u_2, \dots, u_p) \cosh(a_0 u_1) + E_0(u_2, \dots, u_p) \sinh(a_0 u_1)) z_0 \\ + \sum_{j=1}^{\alpha} (D_j(u_2, \dots, u_p) \cos(a_j u_1) + E_j(u_2, \dots, u_p) \sin(a_j u_1)) z_j \quad (6.26)$$

$$+ \sum_{k=\alpha+1}^h (D_k(u_2, \dots, u_p) u_1 + E_k(u_2, \dots, u_p)) z_k \quad (6.27) \\ + F(u_2, \dots, u_p) u_1 + G(u_2, \dots, u_p).$$

Because $\check{\phi}$ is invariant under the \mathbf{C}^* -action, we have $F = G = 0$.

If $p = 1$, then $D_0, \dots, D_h, E_0, \dots, E_h$ are constant vectors.

If $p > 1$, then (6.26) and (6.16) with $s = 1$ and $t = 2, \dots, p$ imply that D_0 and E_0 are constant vectors. Also, by applying arguments similar to that given in *Case (2)* of the proof of Theorem 4.1, we also know that E_0, \dots, E_h are constant vectors and $a_0 = \cdots = a_\alpha = 1$. The latter condition implies

$$\lambda^2 = \sum_{j=0}^{\alpha} z_j \bar{z}_j. \quad (6.28)$$

Thus, from (6.26), we get

$$\begin{aligned}\check{\phi} &= (D_0 \cosh u_1 + E_0 \sinh u_1)z_0 \\ &\quad + \sum_{j=1}^{\alpha} (D_j(u_2, \dots, u_p) \cos u_1 + E_j \sin u_1)z_j + \sum_{k=\alpha+1}^h E_k z_k.\end{aligned}\quad (6.29)$$

If $p > 1$, then by substituting (4.27) and (4.28) into (6.17) with $t = 2$, we find

$$\begin{aligned}&\sum_{j=1}^{\alpha} \cos u_1 \frac{\partial^2 D_j}{\partial u_2^2} z_j \\ &= \cos^2 u_1 \left\{ (D_0 \cosh u_1 + E_0 \sinh u_1)z_0 + \sum_{j=1}^{\alpha} (D_j \cos u_1 + E_j \sin u_1)z_j \right\} \\ &\quad - \frac{\sin 2u_1}{2} \left\{ (D_0 \sinh u_1 + E_0 \cosh u_1)z_0 + \sum_{j=1}^{\alpha} (D_j \sin u_1 - E_j \cos u_1)z_j \right\}.\end{aligned}\quad (6.30)$$

By comparing the coefficients of z_0 in (6.30) we find

$$\cos u_1 (D_0 \cosh u_1 + E_0 \sinh u_1) = \sin u_1 (D_0 \sinh u_1 + E_0 \cosh u_1)$$

which is impossible. Hence, we must have $p = 1$ in *Case* (b). Thus, (6.29) becomes

$$\begin{aligned}\check{\phi} &= (D_0 \cosh u_1 + E_0 \sinh u_1)z_0 \\ &\quad + \sum_{j=1}^{\alpha} (D_j \cos u_1 + E_j \sin u_1)z_j + \sum_{k=\alpha+1}^h E_k z_k.\end{aligned}\quad (6.31)$$

for some constant vectors $D_0, \dots, D_{\alpha}, E_0, \dots, E_h$. From (6.14) and (6.31), we know that D_0 is a unit time-like vector and $D_1, \dots, D_{\alpha}, E_0, \dots, E_h$ are space-like orthonormal vectors in \mathbf{C}_1^{m+1} . Therefore, after choosing suitable initial conditions, we may obtain (6.6).

Conversely, it is straightforward to verify that (6.5) defines a *CR*-warped product $\mathbf{C}_{*1}^{h+1} \times_{\lambda} S^p$ and (6.6) defines a *CR*-warped product $\mathbf{C}_{*1}^{h+1} \times_{\lambda} \mathbf{R}$ in \mathbf{C}_{*1}^{m+1} ; both cases satisfy (6.13). Since the immersions $\check{\phi}$ defined by (6.5) and (6.6) are invariant under the \mathbf{C}^* -action, their projections under $\pi : \mathbf{C}_{*1}^{m+1} \rightarrow CH^m(-4)$ give rise to *CR*-warped products $CH^h(-4) \times_f S^p$

and $CH^h(-4) \times_f \mathbf{R}$ in $CH^m(-4)$. Because the second fundamental form of $CH^h(-4) \times_f S^p$ and $CH^h(-4) \times_f \mathbf{R}$ both satisfy condition (6.7) in $CH^m(-4)$, their second fundamental forms satisfy the equality case of (6.4). \square

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