SOLVING (I - S)g = fWHEN S IS A GENERALIZED SHIFT OPERATOR

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ABSTRACT. Solutions to the equation (I-S)g = f include Weierstrass functions and fractal interpolation functions of Barnsley. Closure of the range of I-S in C and L^r is characterized when ||S|| = 1 and solutions g are represented as weak Abel-like limits.

1. Introduction. Solutions to the equation

$$(1.1) (I-S)g = f$$

are studied, where S is a generalized shift operator defined in Section 2. The closures of the ranges of the operators I-S in the spaces C and L^p depend upon parameters in S. They are characterized simply, and it is shown that solutions g can be obtained as Abel limits.

In the case of the ordinary shift operator $S = \Sigma$ defined by $\Sigma f(t) =$ f(2t) Fortet [3] stated that if f is a Lip (α) , $\alpha > 1/2$, periodic function with period 1 and with $\int_0^1 f(t) dt = 0$, then the equation (1.1) has a solution g in L^2 if and only if

$$\frac{1}{n} \int_0^1 \left| \sum_{i=0}^n f(2^i t) \right|^2 dt \to 0$$

as $n \to \infty$. Kac [5] proved the theorem and Cieselski [2] proved it for all $\alpha > 0$. Rochberg [6] studied a more general equation in the context of shift operators on a Hilbert space and showed that Kac's result is an immediate consequence of his results.

When ||S|| < 1 there is for each right hand side f of (1.1) a unique solution given by the Neumann series

$$(1.2) g = \sum_{j \ge 0} S^j f.$$

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When ||S||=1 solutions may not exist for certain right hand sides since I-S need not be invertible and, when they exist, are not generally obtainable as in (1.2) since the series may no longer converge. It is the latter case, ||S||=1, investigated in this note. The FKC theorem addresses the problem when f is Hölder continuous, solutions are sought in L^2 , and $S=\Sigma$. We prove that the norm closure of the set of functions f for which a solution g exists is the set of f's for which $\int_0^1 f(x) \, dx = 0$. Although it is not generally true that the range of the operator $I-\Sigma$ is closed, this entails (see Lemma 3.4) the existence of many more solutions to the equation than those covered by the FKC theorem. It is shown in the general case that when ||S||=1, $0 < a_n < 1$, and f is in the range of I-S the functions

$$(1.3) g_n = \sum_{j>0} a_n^j S^j f$$

are approximate solutions in the sense that $||f - (I - S)g_n|| \to 0$ and the g_n converge weakly to a solution of (1.1) as $a_n \uparrow 1$.

The fractal interpolation functions studied by Barnsley [1] can be expressed as solutions of an equation (1.1) on the space C[0,1] for ||S|| < 1. Here we extend the notion to what one could call L^r fractal interpolation functions and extend the notion in both L^r and C to the case of ||S|| = 1.

The functional equation

(1.4)
$$\frac{1}{p} \sum_{i=0}^{p-1} f\left(\frac{x+i}{p}\right) = \lambda f(x)$$

has been studied by Artin (see [4]) for $\lambda = p^{-1}$ and more generally by Hata [4] for $\lambda \neq 1$. A generalization of this equation (see (3.2) and Lemma 3.3 below) arises in consideration of the adjoint of the generalized shift operator S when $\lambda = 1$.

2. The generalized shift operator. Let F be a collection of real valued functions on $(-\infty, \infty)$, periodic with period 1, and having restrictions to [0,1] which are elements of a normed linear space B of functions. The norm of $f \in F$ is the B-norm of its restriction to [0,1].

Let p be a positive integer and d_0, \ldots, d_{p-1} be real numbers. Define the generalized shift operator S on F by its restriction to [0,1],

$$Sf(t) = D(t)f(pt),$$

where

(2.1)
$$D(t) = \sum_{i=0}^{p-1} d_i I_i(t)$$

and $I_i(t)$ is the indicator of the interval [i/p, (i+1)/p). The usual shift operator Σ is obtained by taking p=2 and $d_0=d_1=1$. It is assumed that S maps F into itself and that S has norm no more than 1.

If B is the space $L^r[0,1], 1 \leq r < \infty$, then straightforward computation shows

$$||Sf||_r^r = \left(\frac{1}{p}\sum_{i=0}^{p-1}|d_i|^r\right)||f||_r^r.$$

If B is C[0,1], then one must generally have f(0) = f(1) = 0 to make S map F into F. Denoting by C the subspace of C[0,1] with f(0) = f(1) = 0, one has in this case

$$||S|| = \max_{0 \le i \le p-1} |d_i|.$$

For B the space of normalized functions of bounded variation NBV[0,1]

$$||S|| = \left(\sum_{i=0}^{p-1} |d_i|\right).$$

For example, in the case of $S=a\Sigma$ applying this to the function $f(t)=\sin(2\pi t)$ yields the Weierstrass function $g(t)=\sum_{j\geq 0}a^j\sin(2^{j+1}\pi t)$ and it is seen that if $|a|\in [0,1)$ the series representing g converges uniformly to g, a continuous function, and if |a|<1/2, g is of bounded variation. If $|a|\in [1/2,1)$, then the series does not converge in NBV. It is well known that g is not of bounded variation on any subinterval in this case, but this does not follow from these arguments.

The usual definitions and notations regarding a normed linear space X and its dual X^* are observed below including weak and weak*

convergence. For a subset A of X the set A^{\perp} is the collection of elements x^* in X^* for which $\langle x^*, x \rangle$ vanishes on A while if A is a subset of X^* , A^{\perp} is the set of $x \in X$ for which $\langle x^*, x \rangle$ vanishes on A. The range of a linear mapping T is R(T), its null space is N(T), and \overline{A} denotes the norm closure of subset A. Introduce

(2.2)
$$\overline{d} = \frac{1}{p} \sum_{i=0}^{p-1} d_i.$$

Lemma 2.1. If $f \in R(I - S)$, ||S|| = 1, $|a_n| < 1$, and g_n is given in (1.3), then whenever $a_n \uparrow 1$,

$$||f - (I - S)g_n|| \rightarrow 0.$$

Proof. Let f = (I - S)g and $a_n \uparrow 1$. Then

$$||k_n - f|| \le |a_n - 1| ||S|| ||g||,$$

where $k_n = (I - a_n S)g$, and observing that

$$g = \sum_{i>0} a_n^j S^j k_n$$

yields

$$\begin{split} ||f - (I - S)g_n|| &= ||(I - S)(g - g_n)|| \\ &= ||k_n - f + (a_n - 1)S\sum_{j \ge 0} a_n^j S^j(k_n - f)|| \\ &\le ||f - k_n|| + ||a_n - 1||\sum_{j \ge 0} |a_n|^j ||f - k_n|| \\ &\le 2||f - k_n||. \quad \Box$$

3. The range of I-S in L^r . When $||S||_r < 1$, $R(I-S) = L^r$ and $N(I-S) = \{0\}$, $1 \le r \le \infty$. It is assumed throughout this section that 1 = ||S||, or equivalently when $1 \le r < \infty$, that

(3.1)
$$1 = \left[\frac{1}{p} \sum_{i=0}^{p-1} |d|_i^r\right]^{1/r}.$$

Here $\langle g, f \rangle = \int_0^1 f(t)g(t) dt$ for $f \in L^r$, $g \in L^s$ and 1/r + 1/s = 1.

Theorem 3.1. If $1 < r < \infty$, (3.1) holds and all $d_i = 1$, then

$$\overline{R}(I-S) = \{ f \in L^r : \langle 1, f \rangle = 0 \},$$

$$N(I - S) = \{c1 : -\infty < c < +\infty\},\$$

and if f = (I - S)g and $a_n \uparrow 1$ then g_n converges weakly to $g - \langle 1, g \rangle$. If $1 < r < \infty$, (3.1) holds and not all d_i are 1, then

$$\overline{R}(I - S) = L^r,$$

$$N(I - S) = \{0\},$$

and if f = (I - S)g the functions g_n of (1.3) converge weakly to g as $a_n \uparrow 1$.

The proof is accomplished by invoking Lemmas 3.2, 3.5 and 3.7 below.

Lemma 3.2. With S given by (2.1) as a mapping on $L^r[0,1]$, $1 < r < \infty$, and under the condition (3.1)

$$\overline{R}(I-S) = \{ f \in L^r : \langle 1, f \rangle = 0 \}$$

if all d_i are 1; otherwise, $\overline{R}(I-S) = L^r$.

Proof. Let

(3.2)
$$Af(t) = S^*f(t) = \frac{1}{p} \sum_{i=0}^{p-1} d_i f\left(\frac{t+i}{p}\right)$$

and introduce the step-function approximations h_n to $h \in L^s$ defined by

(3.3)
$$h_n(s) = \sum_{i=0}^{p^n - 1} \xi(n, i) I_{n,i}(s),$$

where $I_{n,i}(s)$ is the indicator function which is one on $(i/p^n, (i+1)/p^n]$ and zero elsewhere and

$$\xi(n,i) = p^n \int h(s) I_{n,i}(s) \, ds.$$

Under Lebesgue measure the h_n s form a martingale, and the martingale convergence theorem shows that h_n converges to h a.e. and in L^s .

Under (3.1), Hölder's inequality shows that (see (2.2)) $|\overline{d}| \leq 1$ with equality if and only if all d's are 1 (or all are -1). There are three possibilities: (a) $d_i \equiv 1$, (b) $d_i \equiv -1$, or (c) $|\overline{d}| < 1$.

(a) Noting that for m > n,

$$A^m h_n = \langle h, 1 \rangle 1$$

and using ||A||=1 it follows that A^mh converges a.e. and in L^s to the constant $\langle h,1\rangle 1$. The null space of the operator T^* , where T=I-S, is the set of functions h such that Ah=h and since $N(T^*)^{\perp}=\overline{R}(T)$, $f\in \overline{R}(T)$ if and only if $\langle f,h\rangle=0$ for all constant h. Therefore $f\in \overline{R}(T)$ if and only if $\int_0^1 f(x)\,dx=0$.

- (b) The proof is similar to that in (a) except one examines the two subsequences m=2j and m=2j+1 to conclude that if h is in L^s then $A^{2j}h$ converges to $\langle h,1\rangle 1$ while $A^{2j+1}h$ converges to $-\langle h,1\rangle 1$; so if h is in the null space of I-A, $A^mh\to 0$ and $\overline{R}(T)=L^r$.
- (c) The proof is similar to (b)'s. In this case observe that if m is a sufficiently large integer then A^m h_n is a constant, say c_m . Then $A^{m+1}h_n=\overline{d}c_m$. Since ||A||=1 and $|\overline{d}|<1$, one has A^mh converging to 0 and $\overline{R}(T)=L^r$.

Equation (3.2) shows that Hata's equation (1.4) with $\lambda = 1$ is a special case of the equation $(I - S^*)f = 0$ and we have the following.

Lemma 3.3. If $||S^*|| = 1$ and $1 < s < \infty$, then the set of solutions f in L^s to $(I - S^*)f = 0$ consists precisely of all constants if all d_i are 1 and otherwise the unique solution is f = 0.

That R(I-S) is not generally closed can be seen by applying the FKC theorem to the function $f(t) = \cos(2\pi t)$. For this function,

 $\int_0^1 f(t) dt = 0$ but there is no solution in L^2 to Tg = f. Even so, there are many solutions to the equation (1.1) when ||S|| = 1 which are not covered by the FKC theorem as can be seen by the fact that the f's of the FKC theorem are a meager set in the closure of the range of T. We state this as follows.

Lemma 3.4. The set of solutions E covered by the FKC theorem is a set of first category in $\overline{R}(I-S)$.

Lemma 3.5. If $1 \le r < \infty$, then the solutions to (1.1) are unique except in the case all d_i are one and then the solutions are unique up to an additive constant.

Proof. There are the three cases (a) $d_i \equiv 1$, (b) $d_i \equiv -1$ or (c) $|\overline{d}| < 1$. Let h be in $N(T) \subset L^r$. Then for all $g \in L^s$ one has $\langle (I-S)h, g \rangle = 0$. Therefore, for all g,

$$\langle h, g \rangle = \langle h, S^*g \rangle = \langle h, Ag \rangle = \langle h, A^2g \rangle = \cdots$$

In case (a), by continuity of the inner product and what has been shown above it follows that if h is in the null space of T, then

$$\langle h, A^n g \rangle \to \langle h, 1 \rangle \langle g, 1 \rangle$$

so that for all g,

$$\langle h, g \rangle = \langle h, 1 \rangle \langle g, 1 \rangle.$$

Therefore, if $g \in V = \{f \in L^s : \langle f, 1 \rangle = 0\}$ one has $\langle g, 1 \rangle = 0$ and hence $\langle h, g \rangle = 0$. This shows that $N(T) \subset V^{\perp}$. Since V^{\perp} consists of the constants and these are clearly in N(T) it follows that the null space consists of the constants.

In case (b), taking limits twice, once for n=2j and once for n=2j+1, it follows that if $h \in N(T)$, then for all $g \in L^r$, $\langle h, g \rangle = 0$. So $N(T) = \{0\}$.

The argument in case (c) also shows that if $h \in N(T)$ then $\langle h, g \rangle = 0$ for all g since it has previously been shown that $||A^m h|| \to 0$. So $N(T) = \{0\}$.

Lemma 3.6. Assume f = (I - S)g and $1 < r < \infty$. If not all d_i are 1, then (i) and (iii) are equivalent. If all d_i are 1, then (ii) and (iii) are equivalent.

- (i) The approximate solutions g_n of (1.3) converge weakly to the unique solution g of equation (1.1).
- (ii) Every subsequence $g_{n'}$ has a further subsequence $g_{n''}$ and there is a constant c such that $g_{n''}$ converges weakly to g + c.
 - (iii) $||g_n||$ is a bounded sequence.

Proof. Assume that not all d_i s are 1. It is proven that if (iii) holds, then for every $q \in L^s$, $\langle q, g - g_n \rangle \to 0$. Let $\varepsilon > 0$ be given. Since in the present case under consideration $\overline{R}(T^*) = N(T)^{\perp} = L^s$, let $v \in R(T^*)$ be such that $||v - q|| < \varepsilon/M$, where

$$(3.4) ||g|| + \sup ||g_n|| \le M$$

and

$$(3.5) |\langle q, g - g_n \rangle - \langle v, g - g_n \rangle| \le \varepsilon$$

for all n. It suffices to prove that $\langle v, g - g_n \rangle \to 0$; but this follows immediately from Lemma 2.1 and

$$|\langle v, g - g_n \rangle| = |\langle T^* w, g - g_n \rangle| = |\langle w, T(g - g_n) \rangle|$$

$$\leq ||w|| \, ||f - (I - S)g_n||.$$

Still assuming that not all d_i are 1, suppose that (i) holds. Then $||g - g_n||$ is a bounded sequence and $||g_n|| \le ||g - g_n|| + ||g||$.

Now suppose that all d_i are 1. First, assume that (iii) holds. We require the following fact when $||g_n||$ is a bounded sequence. A point x in a normed linear space X is in the closed subspace F if and only if $\langle x^*, x \rangle = 0$ for all points $x^* \in F^{\perp}$. Let $q \in L^s$ be such that $\langle q, 1 \rangle = 0$. Then q is in the closure of the range of T^* . Letting $\varepsilon > 0$ be arbitrary and $v = T^*w$ be such that $||q - v|| < \varepsilon/M$, where M is chosen as in (3.4), observe that (3.5) holds and that to prove $\langle q, g - g_n \rangle \to 0$ it suffices to prove that $\langle v, g - g_n \rangle \to 0$. This is true by the same argument as above. Now since $||g - g_n||$ is a bounded sequence, for every sequence n' there is a weakly convergent subsequence $g - g_{n''}$ and an element k

to which it weakly converges. We conclude that $\langle v, k \rangle = 0$ for all v in $\{q \in L^s : \langle q, 1 \rangle = 0\}$. Therefore, k is a constant. Still assuming that all d_i are 1, suppose now that (ii) holds. Then, for every subsequence n', there is a subsequence $||g - g_{n''}||$ which is bounded so (iii) holds.

Lemma 3.7. Assume f = (I - S)g and $1 < r < \infty$. If not all d_i are 1, then the g_n in (1.3) converge weakly to the unique solution g of (1.1). If all d_i are 1, then g_n converges weakly to $g - \langle 1, g \rangle$.

Proof. Observing that

$$||g_n|| \le ||g_n - g|| + ||g||$$

where

(3.6)
$$||g_n - g|| = \left\| \sum_{j \ge 0} a_n^j S^j(k_n - f) \right\| \le \frac{1}{1 - a_n} ||f - k_n||$$

$$\le \frac{1}{1 - a_n} |a_n - 1| ||S|| ||g||$$

shows the norms of the g_n remain bounded. If not all d_i are 1 the claim is immediate from Lemma 3.6.

If all d_i are 1 we argue as follows. If g_n does not converge weakly to $g - \langle 1, g \rangle 1$, then there is a $v \in L^s$ and a subsequence n' such that

$$\langle v, g_{n'} \rangle \to \lambda > \langle v, g - \langle 1, g \rangle 1 \rangle = \langle v, g \rangle - \langle 1, g \rangle \langle 1, v \rangle.$$

Noting that $\langle 1, g_n \rangle = 1/(1 - \overline{d}a_n)\langle 1, f \rangle = 0$, one also has $\langle v - \langle 1, v \rangle 1, g_{n'} \rangle \to \lambda$. By Lemma 3.6 there is a subsequence $g_{n''}$ and a constant c for which

$$\langle v - \langle 1, v \rangle 1, g_{n''} \rangle \rightarrow \langle v - \langle 1, v \rangle 1, g + c \rangle = \langle v, g \rangle - \langle 1, v \rangle \langle 1, g \rangle.$$

This contradiction establishes the result.

4. The range of I-S in C. Assume that the mapping S is defined on periodic functions f of period 1 whose restriction to [0,1] is in C[0,1] and satisfies f(0)=f(1)=0. Our interest centers on the case ||S||=1.

Barnsley [1] defines a fractal interpolation function to the initial data $(i/p, y_i)$, $i = 0, \ldots, p$, as follows. Define the p mappings $w_i : [0,1] \times R^1 \to [i/p, (i+1)/p] \times R^1$ for $i = 0, \ldots, p-1$ by

$$w_i \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a_i & 0 \\ c_i & d_i \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} e_i \\ f_i \end{pmatrix},$$

where $e_i = i/p$ and $a_i = 1/p$ and the remaining constants, except the d_i which are free parameters, are chosen to satisfy

$$w_i \begin{pmatrix} 0 \\ y_0 \end{pmatrix} = \begin{pmatrix} i/p \\ y_i \end{pmatrix}, \qquad w_i \begin{pmatrix} 1 \\ y_p \end{pmatrix} = \begin{pmatrix} (i+1)/p \\ y_{i+1} \end{pmatrix}$$

for i = 0, ..., p - 1. If $W : [0, 1] \times R^1 \to [0, 1] \times R^1$ is defined by

$$W(A) = \bigcup_{i=0}^{p-1} w_i(A)$$

and all $|d_i| < 1$, then there is a fixed set G of the transformation W which is shown to be the graph of a continuous function g on [0,1]. The function g is called the fractal interpolation function to the initial data and it can be shown that for all bounded A, $W^n(A) \to G$ as $n \to \infty$. Consider $W([0,1] \times \{0\})$. This is the graph of a piecewise linear function f which satisfies $f(i/p) = y_i$ for $i = 0, \ldots, p$. One can check that if $y_0 = 0 = y_p$ and the same d_i 's are used in the operator S, then for all $n \ge 1$,

$$\sum_{i=0}^{n-1} S^i f = W^n([0,1] \times \{0\}).$$

In Barnsley's treatment of fractal interpolation functions the condition $|d_i| < 1$ is made and for this case, of course, it is immediate that the left hand side converges to a continuous function g and g satisfies (I-S)g = f. We seek solutions g in G to the equation (1.1) where $f \in G$ need not be piecewise linear and g need not be of the form $g = \sum_{i \ge 0} S^i f$.

Lemma 4.1. The adjoint S^* of the mapping $S: C \to C$ is defined on the space BV of signed measures ν of bounded variation by

$$S^*\nu([0,w]) = \sum_{i=0}^{p-1} d_i \nu\left(\left(\frac{i}{p}, \frac{w+i}{p}\right]\right).$$

Proof. Consider the action of the linear functional corresponding to the signed measure ν on the function Sf, where $f \in C$,

$$\langle \nu, Sf \rangle = \int I_{[0,1]}(t)Sf(t) d\nu(t)$$

$$= \int \left(\sum_{i=0}^{p-1} d_i I_{I_i}(t)\right) f(pt) d\nu(t)$$

$$= d_0 \int f(w)I_{[0,1]}(w) d\nu\left(\frac{w}{p}\right)$$

$$+ \sum_{i=1}^{p-1} d_i \int f(w)I_{(i,i+1]}(w) d\nu\left(\frac{w}{p}\right).$$

Therefore, by the periodicity of f and f(0) = 0,

$$\langle \nu, Sf \rangle = \int f(w) I_{(0,1]}(w) d\left(\sum_{i=0}^{p-1} d_i \nu\left(\frac{w+i}{p}\right)\right) = \langle S^* \nu, f \rangle.$$

We need to characterize the collection of signed measures ν in BV which solve the equation $S^*\nu = \nu$. Toward that end we introduce the notion of a real valued stationary stochastic process on $\mathbf{Z} = \{1, 2, \ldots\}$. The stochastic process $\{X(t): t \in \mathbf{Z}\}$ is said to be stationary if for every $k < \infty$, $(t_1, t_2, \ldots, t_k) \in \mathbf{Z}^k$, and Borel measurable subset A in R^k one has for all positive integers v

$$P[(X(t_1), \ldots, X(t_k)) \in A] = P[(X(t_1 + v), \ldots, X(t_k + v)) \in A].$$

A stochastic process $\{X(t): t \in \mathbf{Z}\}$ taking values in $\{0, 1, \ldots, p-1\}$ defines a random variable X taking values in [0,1] by $X(\omega) = \sum_{i \geq 1} X(\omega, i) p^{-i}$ and conversely, once it is decided which representation is to be used, terminating or nonterminating, any Borel random variable X defines a $\{0, 1, \ldots, p-1\}$ -valued process $\{X(t): t \in \mathbf{Z}\}$.

Lemma 4.2. If $d_i \geq 0$ for all i, then a finite nonnull Borel measure μ on [0,1] solves $S^*\mu = \mu$ if and only if

(i) $\mu(\{0\}) = 0$ and when

$$X(\omega) = \sum_{i>1} X(\omega, i) p^{-i}$$

has the probability distribution $\mu(A)/\mu([0,1]) = P[X \in A]$ then for all indices i such that $d_i < 1$ one has for all j

- (ii) P[X(j) = i] = 0 and
- (iii) $\{X(k): k \in \mathbf{Z}\}$ is a stationary stochastic process.

Proof. First assume that μ is a nonnull solution. If a finite nonnull Borel measure μ on [0,1] solves $S^*\mu=\mu$, then the probability measure $\eta(A)=\mu(A)/\mu([0,1])$ also solves the equation. Therefore it can be assumed without loss of generality that the solution μ is a probability measure P. That $\mu(\{0\})=0$ follows from the representation formula for S^* . One has

$$S^*\mu([0,1]) = S^*\mu((0,1]) = \sum_{i \in J} \mu\left(\left(\frac{i}{p}, \frac{i+1}{p}\right]\right) + \sum_{i \notin J} d_i \mu\left(\left(\frac{i}{p}, \frac{i+1}{p}\right]\right),$$

where $J = \{k : k \in \{0, ..., p-1\} \text{ and } d_k = 1\}$. By additivity of μ it follows that if J^c is not empty then

$$S^*\mu((0,1]) < \sum_{i \in J} \mu\left(\left(\frac{i}{p}, \frac{i+1}{p}\right]\right) + \sum_{i \notin J} \mu\left(\left(\frac{i}{p}, \frac{i+1}{p}\right]\right) = \mu((0,1])$$

so that $S^*\mu((0,1]) = \gamma\mu((0,1])$, where $|\gamma| < 1$. Iterating S^* , this implies $\mu((0,1]) = 0$ which is impossible under our assumptions. Therefore, if $i \notin J$, then $\mu((i/p, (i+1)/p)) = 0$. For $i \notin J$, consider

$$\mu\left(\left(\frac{i}{p}, \frac{i+1}{p}\right]\right) = S^*\mu\left(\left(\frac{i}{p}, \frac{i+1}{p}\right]\right) = \sum_{j \in J} \mu\left(\left(\frac{j}{p} + \frac{i}{p^2}, \frac{j}{p} + \frac{i+1}{p^2}\right]\right)$$
$$+ \sum_{j \notin J} d_j \mu\left(\left(\frac{j}{p} + \frac{i}{p^2}, \frac{j}{p} + \frac{i+1}{p^2}\right]\right)$$
$$= \sum_{j \in J} \mu\left(\left(\frac{j}{p} + \frac{i}{p^2}, \frac{j}{p} + \frac{i+1}{p^2}\right]\right).$$

Since $0 = \mu((i/p, (i+1)/p]) = \sum_{j \in J} \mu((j/p+i/p^2, j/p+(i+1)/p^2])$ it follows that for all $j \in \{0, \ldots, p-1\}$ $\mu((j/p+i/p^2, j/p+(i+1)/p^2]) = 0$. The argument can be repeated showing that if $i \notin J$, then for all $j \geq 1$ and all $x = \sum_{i=1}^{j-1} x_i p^{-i}$, $\mu((x+ip^{-j}, x+(i+1)p^{-j}]) = 0$. In terms of the probability measure this means that for all indices i such that $d_i < 1$ one has for all $j \in J$.

To see that the measure μ must correspond to a stationary process, consider

$$P(\{X : X(i_1) = k_1, \dots, X(i_m) = k_m\})$$

$$= \sum_{i \in J} P(\{X : X(1) = i, X(i_1 + 1) = k_1, \dots, X(i_m + 1) = k_m\})$$

$$= P(\{X : X(i_1 + 1) = k_1, \dots, X(i_m + 1) = k_m\}).$$

The converse follows by the same arguments.

For any S, denote the collection of probability measures which solve $S^*\mu = \mu$ by M_S .

Lemma 4.3. Under the conditions of Lemma 4.2 the solutions $\nu \in BV(0,1]$ to $S^*\nu = \nu$ consist of all signed measures of the form

$$(4.1) \nu = c_1 \mu_1 - c_2 \mu_2,$$

where the μ 's are in M_S and the c's are nonnegative real numbers.

Proof. Clearly all signed measures in (4.1) solve $S^*\nu = \nu$ since S^* is linear. Now let ν be a solution. By the Hahn decomposition there is a Borel set D such that $\nu^+(A) = \nu(A \cap D)$ and $\nu^-(A) = -\nu(A \cap D^c)$ for all measurable sets A. It follows that on D, ν is a measure satisfying $S^*\nu = \nu$ and on D^c the measure $-\nu$ solves $S^*(-\nu) = -\nu$. With the obvious adjustments in case $\nu(D)$ or $\nu(D^c)$ zero, let $\mu_1(A) = \nu(A \cap D)/\nu(D)$, $\mu_2(A) = \nu(A \cap D^c)/\nu(D^c)$, $c_1 = \nu(D)$, and $c_2 = -\nu(D^c)$.

Theorem 4.4. Let ||S|| = 1 and $d_i \ge 0$ for all i. Then $\overline{R}(I - S) = \{f \in C : E[f(X)] = 0 \text{ for all } X \in \mathbf{X}, \text{ where } \}$

$$X(\omega) = \sum_{i>1} X(\omega, i) p^{-i} \in \mathbf{X}$$

if for all indices i such that $d_i < 1$ and for all j

- (i) P[X(j) = i] = 0 and
- (ii) $\{X(k): k \in \mathbf{Z}\}\ is\ a\ stationary\ stochastic\ process.$

The null space is $N(T) = \{0\}.$

Proof. The closure of the range of T is the orthogonal complement of the null space of $I-S^*$ so $f\in \overline{R}(T)$ if and only if $\int f\,d\nu=0$ for all ν in BV[0,1] solving $S^*\nu=\nu$. Therefore, $f\in \overline{R}(T)$ if and only if $\int f\,d\mu=0$ for any measure $\mu([0,t])=P[X\leq t]$, where X satisfies (i) and (ii).

To prove the claim regarding N(T), let $v, x \in (0,1)$ and $f \in N(T)$ be arbitrary. Then upon iterating the relation

$$f\left(\frac{x+i}{p}\right) = d_i f(x+i) = d_i f(x)$$

for points $v_k = \sum_{i=1}^k v(i)p^{-i}$ it follows that

$$f(v_k + xp^{-k}) = \prod_{i=1}^k d_{v(i)} f(x).$$

Using $v = \sum_{i \geq 1} v(i) p^{-i}$, $xp^{-k} \to 0$, $v_k \to v$, and the continuity of f shows

$$f(v) = f(x) \limsup_{k \to \infty} \prod_{i=1}^k d_{v(i)} \le f(x) \liminf_{k \to \infty} \prod_{i=1}^k d_{v(i)} = f(v).$$

Taking $x \to 0$ shows f(v) = 0.

Theorem 4.5. If ||S|| = 1 and $f \in R(T)$, then the approximate solutions of (1.3) converge in the weak* topology of L^{∞} to the unique solution g of (1.1) unless all d_i 's are one, in which case the g_n converge to $g - \langle 1, g \rangle$.

Proof. Let $b \in L^1$ be such that $\langle b, 1 \rangle = 0$. Then b must be in $\overline{R}(T^*)$. This can be seen as follows. If b is not in $\overline{R}(T^*)$, then there is a function

 $u \in L^{\infty}$ such that $\langle u, b \rangle > 0$ and for all $v \in L^{1}$, $\langle u, T^{*}v \rangle = 0$. Hence, for all $v \in L^{1}$, $\langle Tu, v \rangle = 0$ and this entails Tu = 0. Now this must mean that u is constant a.e. as is seen by using Lusin's theorem and a simple adaptation of the proof in Theorem 4.4 that $N(T) = \{0\}$. But then $0 < \langle u, b \rangle = c\langle 1, b \rangle = 0$, which is a contradiction; so $b \in \overline{R}(T^{*})$.

By the boundedness of the sequence $||g_n - g||$ (see (3.6)) and the fact that for $b = T^*w$, $w \in L^1$, one has

$$|\langle b, g_n - g \rangle| = |\langle T^* w, g_n - g \rangle| = |\langle w, Tg_n - f \rangle| \le ||w|| ||f - Tg_n|| \to 0,$$

it must be that for all $b \in L^1$ such that $\langle b, 1 \rangle = 0$ the sequence $\langle b, g_n - g \rangle$ converges to zero.

Now suppose $b \in L^1$ is arbitrary. We show that $\langle b, g_n - g \rangle \to 0$ when not all d_i are 1. If not all d_i are 1, then for n sufficiently large

$$\langle 1, g_n \rangle = \sum_{j>0} (\overline{d}a_n)^j \int f = \frac{1}{1 - \overline{d}a_n} \int f,$$

while $\int f = \int (I - S)g = \int g - \overline{d} \int g$ shows that $\langle 1, g_n \rangle \to \langle 1, g \rangle$. Consequently, if $b \in L^1$ is arbitrary and $b' = b - \langle 1, b \rangle$, then $0 = \lim \langle b', g_n - g \rangle = \lim \langle b, g_n - g \rangle - 0$.

Suppose $b \in L^1$ is arbitrary and all $d_i = 1$. If all $d_i = 1$, then $\int f = \int (I - S)g = \int g - \int g = 0$. Therefore, $\langle g_{n'} 1 \rangle \equiv 0$ and for all $b \in L^1$

$$\lim \langle b, g_n - (g - \langle 1, g \rangle 1) \rangle = 0. \qquad \Box$$

When all d_i 's are 1 the assertion of Theorem 4.5 leaves open the question of whether the approximate solutions g_n may converge to a function which is not in C. A simple example shows that they can; let f(t) = g(t) - g(2t) with $g(t) = 2tI_{[0,.5]}(t) + (2-2t)I_{(.5,1]}(t)$ so that g_n converges to g - 1/2.

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