

## REMARKS ON REGULARITY CRITERIA FOR THE 2D GENERALIZED MHD SYSTEM IN BESOV SPACES

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ABSTRACT. This paper concerns regularity criteria for the 2D generalized MHD system and shows that, if we can control the Besov norm of the vorticity and/or the current density, then the solution is, in fact, smooth. This improves the recent result [5].

**1. Introduction.** In this paper, we consider the following two-dimensional (2D) generalized MHD system:

$$(1.1) \quad \begin{cases} \partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} - (\mathbf{b} \cdot \nabla) \mathbf{b} + \Lambda^{2\alpha} \mathbf{u} + \nabla \Pi = \mathbf{0}, \\ \partial_t \mathbf{b} + (\mathbf{u} \cdot \nabla) \mathbf{b} - (\mathbf{b} \cdot \nabla) \mathbf{u} + \Lambda^{2\beta} \mathbf{b} = \mathbf{0}, \\ \nabla \cdot \mathbf{u} = \nabla \cdot \nabla \mathbf{b} = 0, \\ (\mathbf{u}, \mathbf{b})|_{t=0} = (\mathbf{u}_0, \mathbf{b}_0), \end{cases}$$

where  $\mathbf{u} = (u_1, u_2)$ ,  $\mathbf{b} = (b_1, b_2)$  and  $\Pi$  are the fluid velocity field, the magnetic field and the scalar pressure, respectively; and  $\mathbf{u}_0$  and  $\mathbf{b}_0$  are the prescribed initial data satisfying the compatibility condition

$$\nabla \cdot \mathbf{u}_0 = \nabla \cdot \mathbf{b}_0 = 0,$$

$\Lambda^\alpha$  and  $\Lambda^\beta$  with  $\alpha, \beta \geq 0$  the fractional diffusion operators, defined through the Fourier transform as

$$\mathcal{F}(\Lambda^\gamma f)(\xi) = |\xi|^\gamma \mathcal{F}(f)(\xi), \quad \gamma = \alpha \text{ or } \beta.$$

The global regularity for system (1.1) has attracted the attention of many authors, and much interesting and important progress has been

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made in the past decade. In 2003, Wu [13] showed that system (1.1) admits a global classical solution if

$$(1.2) \quad \alpha \geq 1, \quad \beta \geq 1,$$

which was extended in [14] as

$$(1.3) \quad \alpha \geq 1, \quad \beta > 0, \quad \alpha + \beta \geq 2,$$

with a logarithmic improvement (also, see [12, 16] for the margin case  $\beta = 0$ ). Tran, Yu and Zhai [11] then considered the following three cases:

$$(1.4) \quad \alpha \geq 1, \quad \beta \geq 1; \quad 0 \leq \alpha < \frac{1}{2}, \quad 2\alpha + \beta > 2; \quad \alpha \geq 2, \quad \beta = 0.$$

The above second case was improved by Jiu and Zhao [7] as

$$(1.5) \quad 0 \leq \alpha < \frac{1}{2}, \quad \beta \geq 1, \quad 3\alpha + 2\beta > 3,$$

with the limiting case  $\alpha = 0, \beta > 3/2$  independently proven by Yamazaki [15] and Yuan and Bai [20]. Improvement to  $\alpha = 0, \beta > 1$ , was done by Cao, Wu and Yuan [2] and Jiu and Zhao [8]. Finally, we would like to mention that Ji [4] covered the case  $1/2 < \alpha \leq 1, \beta = 1$  (with improvement  $\alpha > 1/3, \beta = 1$ , by Yamazaki [17], and further improvement  $\alpha \geq 1/4, \beta = 1$ , by Ye and Xu [19]), Fan, et al. [3] considered the case  $0 < \alpha < 1/2, \beta = 1$ .

For the cases not mentioned above, the global regularity of system (1.1) has not been solved. Thus, it is natural to derive regularity criteria, by which we mean a condition on the solution guaranteeing its global smoothness. For system (1.1) with  $\alpha = 1, \beta = 0$ , we have the following regularity conditions:

$$(1.6) \quad \begin{aligned} & (1) \text{ by Jiu and Niu [6],} \\ & \mathbf{b} \in L^p(0, T; W^{2,q}(\mathbb{R}^2)), \quad \frac{2}{p} + \frac{1}{q} \leq 2, \quad 1 \leq p \leq \frac{4}{3}, \quad 2 < q \leq \infty; \end{aligned}$$

$$(1.7) \quad \begin{aligned} & (2) \text{ by Fan and Ozawa [10],} \\ & \nabla \mathbf{u} \in L^1(0, T; L^\infty(\mathbb{R}^3)); \end{aligned}$$

(3) by Lei, Masmoudi and Zhou [9],

$$(1.8) \quad \mathbf{b} \otimes \mathbf{b} \in L^1(0, T; BMO(\mathbb{R}^2));$$

(4) by Zhou and Fan [23],

$$(1.9) \quad \nabla \mathbf{b} \in L^1(0, T; BMO(\mathbb{R}^2)).$$

Then, Jiang, Wang and Zhou [5] showed regularity criteria involving the vorticity

$$\omega = \nabla \times \mathbf{u} \stackrel{\text{def}}{=} \partial_1 u_2 - \partial_2 u_1$$

and/or the current density

$$j = \nabla \times \mathbf{b} \stackrel{\text{def}}{=} \partial_1 b_2 - \partial_2 b_1.$$

Among them are:

$$(1.10) \quad \omega \in L^{p\beta/(p\beta-1)}(0, T; L^p(\mathbb{R}^2)) \quad \text{if } p > \frac{1}{\beta}, \quad \alpha, \beta \geq \frac{1}{2};$$

$$(1.11) \quad \omega, j \in L^{\max\{(p\alpha/p\alpha-1), (p\beta/p\beta-1)\}}(0, T; L^p(\mathbb{R}^2))$$

$$\text{if } p > \max \left\{ \frac{1}{\alpha}, \frac{1}{\beta} \right\}, \quad \alpha, \beta > 0.$$

Meanwhile, Ye [18] showed the regularity condition

$$(1.12) \quad j \in L^1(0, T; \dot{B}_{\infty, \infty}^0(\mathbb{R}^2)) \quad \text{if } \alpha > \frac{1}{2}, \quad \beta > \frac{1}{2},$$

and

$$(1.13) \quad \omega \in L^1(0, T; \dot{B}_{\infty, \infty}^0(\mathbb{R}^2)) \quad \text{if } \alpha + \beta > 1, \quad \beta > \frac{1}{2}.$$

Here, and in what follows,  $\dot{B}_{p, q}^s(\mathbb{R}^2)$  with  $s \in \mathbb{R}, \{p, q\} \subset [1, \infty]$  represent the homogeneous Besov spaces, see [1] for the definition, fine properties and applications to fluid dynamical systems.

Our main results are the following two theorems. The first concerns large  $\alpha$  and  $\beta$ .

**Theorem 1.1.** *Let  $\alpha, \beta \geq 1/2$ . Assume that  $(\mathbf{u}_0, \mathbf{b}_0) \in H^2(\mathbb{R}^2)$  and  $(\mathbf{u}, \mathbf{b})$  is the local smooth solution of (1.1). If*

$$(1.14) \quad \omega \in L^{2\beta/(2\beta-r)}(0, T; \dot{B}_{\infty, \infty}^{-r}(\mathbb{R}^2)) \quad \text{for some } 0 < r < \beta$$

or

$$(1.15) \quad j \in L^{2\beta/(2\beta-r)}(0, T; \dot{B}_{\infty, \infty}^{-r}(\mathbb{R}^2)) \quad \text{for some } 0 < r < \beta,$$

then the solution can be smoothly extended beyond  $T$ .

**Remark 1.2.** Due to the Sobolev imbedding  $L^p(\mathbb{R}^2) \subset \dot{B}_{p, \infty}^0(\mathbb{R}^2) \subset \dot{B}_{\infty, \infty}^{-2/p}(\mathbb{R}^2)$ , see [1, Propositions 2.20 and 2.39], we see our result (1.14) implies the following regularity criterion

$$(1.16) \quad \omega \in L^{p\beta/(p\beta-1)}(0, T; L^p(\mathbb{R}^2)), \quad p > 2/\beta,$$

which greatly improves (1.10).

Our second aim is to improve (1.11) from Lebesgue spaces to Besov spaces of negative regular indices. Precisely, we have the following.

**Theorem 1.3.** *Let  $\alpha, \beta > 0$ . Assume that  $(\mathbf{u}_0, \mathbf{b}_0) \in H^2(\mathbb{R}^2)$  and  $(\mathbf{u}, \mathbf{b})$  is the local smooth solution of (1.1). If*

$$(1.17) \quad \omega, j \in L^{\max\{(2\alpha/(2\alpha-r)), (2\beta/(2\beta-r))\}}(0, T; \dot{B}_{\infty, \infty}^{-r}(\mathbb{R}^2))$$

for some  $0 < r < \min\{\alpha, \beta\}$ ,

then the solution can be smoothly extended beyond  $T$ .

**Remark 1.4.** As in Remark 1.2, our result (1.17) greatly extends (1.11).

**2. Proof of Theorem 1.1.** In this section, we shall prove Theorem 1.1. Since the  $H^2$  estimate of the solution can be performed as in [5], once the  $H^1$  estimate is accomplished, what we must do is merely obtain the global  $H^1$  estimate under assumption (1.14) or (1.15).

First, multiplying (1.1)<sub>1,2</sub> by  $\mathbf{u}$  and  $\mathbf{b}$ , respectively, we easily deduce the following energy estimate:

$$(2.1) \quad \|(\mathbf{u}, \mathbf{b})(t)\|_{L^2}^2 + 2 \int_0^t \|(\Lambda^\alpha \mathbf{u}, \Lambda^\beta \mathbf{b})(\tau)\|_{L^2} d\tau = \|(\mathbf{u}_0, \mathbf{b}_0)\|_{L^2}^2.$$

Taking the curl operator of (1.1)<sub>1,2</sub>, we obtain the governing equations of  $\omega$  and  $j$  as

$$(2.2) \quad \begin{cases} \partial_t \omega + (\mathbf{u} \cdot \nabla) \omega + \Lambda^{2\alpha} \omega - (\mathbf{b} \cdot \nabla) j = 0, \\ \partial_t j + (\mathbf{u} \cdot \nabla) j + \Lambda^{2\beta} j - (\mathbf{b} \cdot \nabla) \omega = T(\nabla \mathbf{u}, \nabla \mathbf{b}), \end{cases}$$

where

$$(2.3) \quad T(\nabla \mathbf{u}, \nabla \mathbf{b}) \stackrel{\text{def}}{=} 2\partial_1 b_1 (\partial_1 u_2 + \partial_2 u_1) + 2\partial_2 u_2 (\partial_1 b_2 + \partial_2 b_1).$$

Taking the inner product of (2.2)<sub>1,2</sub> with  $\omega$  and  $j$  in  $L^2(\mathbb{R}^3)$ , respectively, we get

$$(2.4) \quad \frac{1}{2} \frac{d}{dt} \|(\omega, j)\|_{L^2}^2 + \|(\Lambda^\alpha \omega, \Lambda^\beta j)\|_{L^2}^2 = \int_{\mathbb{R}^2} T(\nabla \mathbf{u}, \nabla \mathbf{b}) \cdot j \, dx \equiv I.$$

**Case I.** (1.14) holds. In this circumstance, we shall use the following lemma to dominate  $I$ , which is a variant of that in [21].

**Lemma 2.1.** *For any  $\varepsilon > 0$ ,*

$$f \in \dot{B}_{\infty, \infty}^{-r}(\mathbb{R}^n), \quad g, h \in H^\beta(\mathbb{R}^n),$$

*we have*

$$(2.5) \quad \int_{\mathbb{R}^n} fgh \, dx \leq C \|f\|_{\dot{B}_{\infty, \infty}^{-r}}^{2\beta/(2\beta-r)} \|(g, h)\|_{L^2}^2 + \varepsilon \|\Lambda^\beta(g, h)\|_{L^2}^2.$$

We provide the proof for the convenience of the reader.

*Proof.*

$$\int_{\mathbb{R}^n} f \cdot (gh) \, dx \leq C \|f\|_{\dot{B}_{\infty, \infty}^{-r}} \|gh\|_{\dot{B}_{1,1}^r}$$

(by [1, Proposition 2.29])

$$\leq C \|f\|_{\dot{B}_{\infty, \infty}^{-r}} \|(g, h)\|_{L^2} \|(g, h)\|_{\dot{B}_{2,1}^r}$$

(by Lemma A.1 in the appendix)

$$\leq C\|f\|_{\dot{B}_{\infty,\infty}^{-r}} \|(g, h)\|_{L^2} \cdot \|(g, h)\|_{\dot{B}_{2,\infty}^0}^{1-r/\beta} \|(g, h)\|_{\dot{B}_{2,\infty}^\beta}^{r/\beta}$$

(by [1, Proposition 2.22])

$$\leq C\|f\|_{\dot{B}_{\infty,\infty}^{-r}} \|(g, h)\|_{L^2}^{(2\beta-r)/\beta} \|A^\beta(g, h)\|_{L^2}^{r/\beta}$$

(by [1, Proposition 2.39])

$$\leq C\|f\|_{\dot{B}_{\infty,\infty}^{-r}}^{2\beta/(2\beta-r)} \|(g, h)\|_{L^2}^2 + \varepsilon \|A^\beta(g, h)\|_{L^2}^2. \quad \square$$

Invoking Lemma 2.1 with  $f = \nabla \mathbf{u}$ ,  $g = \nabla \mathbf{b}$  and  $h = j$ , we find

$$\begin{aligned} (2.6) \quad I &\leq C\|\nabla \mathbf{u}\|_{\dot{B}_{\infty,\infty}^{-r}}^{2\beta/(2\beta-r)} \|(\nabla \mathbf{b}, j)\|_{L^2}^2 + \varepsilon \|A^\beta(\nabla \mathbf{b}, j)\|_{L^2}^2 \\ &\leq C\|\omega\|_{\dot{B}_{\infty,\infty}^{-r}}^{2\beta/(2\beta-r)} \|j\|_{L^2}^2 + C\varepsilon \|A^\beta j\|_{L^2}^2. \end{aligned}$$

Choosing  $\varepsilon = 1/(2C)$ , and plugging (2.6) into (2.4), we may apply the Gronwall inequality to deduce the global  $H^1$  estimate of the solution as desired.

**Case II.** (1.15) holds. In this case, we shall use the following, specific case of [1, Theorem 2.42]

$$(2.7) \quad \|f\|_{L^4} \leq C\|f\|_{\dot{B}_{\infty,\infty}^{-r}}^{1/2} \|f\|_{\dot{H}^r}^{1/2} \quad \text{if } r > 0.$$

With (2.7) in hand,  $I$  can be bounded as

$$\begin{aligned} (2.8) \quad I &\leq C\|\omega\|_{L^2} \|j\|_{L^4}^2 \\ &\leq C\|\omega\|_{L^2} \|j\|_{\dot{B}_{\infty,\infty}^{-r}} \|j\|_{\dot{H}^r} \\ &\leq C\|\omega\|_{L^2} \|j\|_{\dot{B}_{\infty,\infty}^{-r}} \|j\|_{L^2}^{1-r/\beta} \|A^\beta j\|_{L^2}^{r/\beta} \\ &\leq C\|j\|_{\dot{B}_{\infty,\infty}^{-r}}^{2\beta/(2\beta-r)} \|(\omega, j)\|_{L^2}^2 + \frac{1}{2} \|A^\beta j\|_{L^2}^2. \end{aligned}$$

Substituting (2.8) into (2.4), we obtain the desired  $H^1$  estimate of the solution by invoking the Gronwall inequality. The proof of Theorem 1.1 is complete.  $\square$

**3. Proof of Theorem 1.3.** In this section, we shall provide the proof of Theorem 1.3.

Just as was done in Section 2, we have the global  $H^1$  estimate. In order to derive the global  $H^2$  estimate, we multiply (2.2)<sub>1,2</sub> by  $-\Delta\omega$  and  $-\Delta j$ , respectively, and integrate by parts to derive:

$$\begin{aligned}
 (3.1) \quad & \frac{1}{2} \frac{d}{dt} \|\nabla(\omega, j)\|_{L^2}^2 + \|\nabla(\Lambda^\alpha \omega, \Lambda^\beta j)\|_{L^2}^2 \\
 &= - \sum_{i=1}^2 \int_{\mathbb{R}^2} [(\partial_i \mathbf{u} \cdot \nabla)\omega] \cdot \partial_i \omega \, dx + \sum_{i=1}^2 \int_{\mathbb{R}^2} [(\partial_i \mathbf{b} \cdot \nabla)j] \cdot \partial_i \omega \, dx \\
 &\quad - \sum_{i=1}^2 \int_{\mathbb{R}^2} [(\partial_i \mathbf{u} \cdot \nabla)j] \cdot \partial_i j \, dx + \sum_{i=1}^2 \int_{\mathbb{R}^2} [(\partial_i \mathbf{b} \cdot \nabla)\omega] \cdot \partial_i j \, dx \\
 &\quad + \sum_{i=1}^2 \int_{\mathbb{R}^2} \partial_i T(\nabla \mathbf{u}, \nabla \mathbf{b}) \cdot \partial_i j \, dx \\
 &\equiv J.
 \end{aligned}$$

We can first simplify  $J$  as

$$\begin{aligned}
 (3.2) \quad J &\leq \int_{\mathbb{R}^2} |\nabla \mathbf{u}| \cdot |\nabla \omega|^2 \, dx + \int_{\mathbb{R}^2} |\nabla \mathbf{b}| \cdot |\nabla j| \cdot |\nabla \omega| \, dx \\
 &\quad + \int_{\mathbb{R}^2} |\nabla \mathbf{u}| \cdot |\nabla j|^2 \, dx + \int_{\mathbb{R}^2} |\nabla \mathbf{b}| \cdot |\nabla \omega| \cdot |\nabla j| \, dx \\
 &\quad + \int_{\mathbb{R}^2} |\nabla^2 \mathbf{u}| \cdot |\nabla \mathbf{b}| \cdot |\nabla j| \, dx + \int_{\mathbb{R}^2} |\nabla \mathbf{u}| \cdot |\nabla^2 \mathbf{b}| \cdot |\nabla j| \, dx \\
 &\leq C \int_{\mathbb{R}^2} |\nabla(\mathbf{u}, \mathbf{b})| \cdot (|\nabla^2 \mathbf{u}|^2 + |\nabla^2 \mathbf{u}| \cdot |\nabla^2 \mathbf{b}| + |\nabla^2 \mathbf{b}|^2) \, dx \\
 &\leq C \int_{\mathbb{R}^2} |\nabla(\mathbf{u}, \mathbf{b})| \cdot (|\nabla^2 \mathbf{u}|^2 + |\nabla^2 \mathbf{b}|^2) \, dx.
 \end{aligned}$$

Then, invoking Lemma 2.1 yields

$$\begin{aligned}
 (3.3) \quad J &\leq C \|\nabla(\mathbf{u}, \mathbf{b})\|_{\dot{B}_{\infty, \infty}^{-r}}^{2\alpha/(2\alpha-r)} \|\nabla^2 \mathbf{u}\|_{L^2}^2 + \varepsilon \| \Lambda^\alpha \nabla^2 \mathbf{u} \|_{L^2}^2 \\
 &\quad + C \|\nabla(\mathbf{u}, \mathbf{b})\|_{\dot{B}_{\infty, \infty}^{-r}}^{2\beta/(2\beta-r)} \|\nabla^2 \mathbf{b}\|_{L^2}^2 + \varepsilon \| \Lambda^\alpha \nabla^2 \mathbf{b} \|_{L^2}^2 \\
 &\leq C \left[ 1 + \|(\omega, j)\|_{\dot{B}_{\infty, \infty}^{-r}}^{\max\{(2\alpha/(2\alpha-r)), (2\beta/(2\beta-r))\}} \right] \|\nabla(\omega, j)\|_{L^2}^2 \\
 &\quad + C\varepsilon \|\nabla(\Lambda^\alpha \omega, \Lambda^\beta j)\|_{L^2}^2.
 \end{aligned}$$

Placing (3.3) into (3.1) and choosing  $\varepsilon = 1/(2C)$ , we may apply the

Gronwall inequality to deduce the desired  $H^2$  bound of the solution. From the Sobolev embedding theorems,

$$\omega, j \in L^2(0, T; H^1(\mathbb{R}^2)) \subset L^2(0, T; BMO(\mathbb{R}^2)) \subset L^2(0, T; \dot{B}^0_{\infty, \infty}(\mathbb{R}^2)).$$

By [22], the proof of Theorem 1.3 is accomplished. □

### APPENDIX

**A.** In this appendix, we provide a bilinear estimate in Besov spaces, which is utilized in the proof of Lemma 2.1.

**Lemma A.1.** *Let  $(s, p, q, p_1, p_2, p_3, p_4) \in (0, \infty) \times [1, \infty]^6$ . Then, there exists a constant  $C$ , depending upon  $s$  and the dimension  $n$ , such that*

$$(A.1) \quad \|uv\|_{\dot{B}^s_{p, q}} \leq C(\|u\|_{L^{p_1}} \|v\|_{\dot{B}^s_{p_2, q}} + \|u\|_{\dot{B}^s_{p_3, q}} \|v\|_{L^{p_4}})$$

with

$$\frac{1}{p} = \frac{1}{p_1} + \frac{1}{p_2} = \frac{1}{p_3} + \frac{1}{p_4}.$$

*Proof.* The proof of this lemma is similar to [1, Corollary 2.54] and is trivial for experts; however, the proof is provided in full detail for the convenience of the reader. The notation and tools are borrowed from [1]. We shall abbreviate  $\|u\|_{L^p(\mathbb{R}^n)}$  as  $\|u\|_{L^p}$  for simplicity.

By [1, Equation (2.29)], we have the following Bony decomposition

$$uv = \dot{T}_u v + \dot{T}_v u + \dot{R}(u, v),$$

and what we need to do is to estimate these three terms.

**A.1. The estimation of  $\dot{T}_u v$  and  $\dot{T}_v u$ .** By [1, equation (2.9)],

$$\dot{\Delta}_j(\dot{T}_u v) = \sum_{|j'-j| \leq 4} \Delta_j(\dot{S}_{j'-1} u \dot{\Delta}_{j'} v),$$

and thus,

$$(A.2) \quad \begin{aligned} \|\dot{T}_u v\|_{\dot{B}^s_{p, q}} &= \|\{2^{js} \|\Delta_j(\dot{T}_u v)\|_{L^p}\}_{\ell^q}\| \\ &= \left\| \left\{ 2^{js} \left\| \sum_{|j'-j| \leq 4} \Delta_j(\dot{S}_{j'-1} u \dot{\Delta}_{j'} v) \right\|_{L^p} \right\} \right\|_{\ell^q} \end{aligned}$$

$$\begin{aligned}
 &\leq C\|\{2^{js}\|\Delta_j(\dot{S}_{j-1}u\dot{\Delta}_jv)\|_{L^p}\}\|_{\ell^q} \\
 &\leq C\|\{2^{js}\|\dot{S}_{j-1}u\dot{\Delta}_jv\|_{L^p}\}\|_{\ell^q} \\
 &\leq C\|\{2^{js}\|\dot{S}_{j-1}u\|_{L^{p_1}}\|\dot{\Delta}_jv\|_{L^{p_2}}\}\|_{\ell^q} \\
 &\leq C\|u\|_{L^{p_1}}\|\{2^{js}\|\dot{\Delta}_jv\|_{L^{p_2}}\}\|_{\ell^q} \\
 &= C\|u\|_{L^{p_1}}\|v\|_{\dot{B}_{p_2,q}^s}.
 \end{aligned}$$

Similarly,

$$(A.3) \quad \|\dot{T}_v u\|_{\dot{B}_{p,q}^s} \leq C\|v\|_{L^{p_3}}\|u\|_{\dot{B}_{p_4,q}^s}.$$

**A.2. The estimation of  $\dot{R}(u, v)$ .** By the analysis of the support, we deduce, as in [1, Proof of Theorem 2.52], that there exists an integer  $N$  such that

$$\begin{aligned}
 \dot{\Delta}_{j'}\dot{R}(u, v) &= \dot{\Delta}_{j'}\sum_j\sum_{|\nu|\leq 1}\dot{\Delta}_{j-\nu}u\dot{\Delta}_jv \\
 &= \sum_{j\geq j'-N}\dot{\Delta}_{j'}\sum_{|\nu|\leq 1}\dot{\Delta}_{j-\nu}u\dot{\Delta}_jv \\
 &= \sum_{\substack{j\geq j'-N \\ |\nu|\leq 1}}\dot{\Delta}_{j'}(\dot{\Delta}_{j-\nu}u\dot{\Delta}_jv).
 \end{aligned}$$

Consequently,

$$\begin{aligned}
 2^{j's}\|\dot{\Delta}_{j'}\dot{R}(u, v)\|_{L^p} &\leq 2^{j's}\sum_{\substack{j\geq j'-N \\ |\nu|\leq 1}}\|\dot{\Delta}_{j'}(\dot{\Delta}_{j-\nu}u\dot{\Delta}_jv)\|_{L^p} \\
 &\leq C2^{j's}\sum_{\substack{j\geq j'-N \\ |\nu|\leq 1}}\|\dot{\Delta}_{j-\nu}u\dot{\Delta}_jv\|_{L^p} \\
 &\leq C2^{j's}\sum_{\substack{j\geq j'-N \\ |\nu|\leq 1}}\|\dot{\Delta}_{j-\nu}u\|_{L^{p_1}}\|\dot{\Delta}_jv\|_{L^{p_2}} \\
 &\leq C\|u\|_{L^{p_1}}\sum_{j\geq j'-N}2^{(j'-j)s}\cdot 2^{js}\|\dot{\Delta}_jv\|_{L^{p_2}} \\
 &= C\|u\|_{L^{p_1}}\sum_{i\leq N}2^{is}\cdot 2^{(j'-i)s}\|\dot{\Delta}_{j'-i}v\|_{L^{p_2}} \quad (j'-j=i) \\
 &= C\|u\|_{L^{p_1}}\left(\{a_i\} * \{2^{is}\|\dot{\Delta}_i v\|_{L^{p_2}}\}\right)_{j'},
 \end{aligned}$$

where

$$a_i = \begin{cases} 2^{is} & i \leq N, \\ 0 & i > N, \end{cases}$$

and  $(\{a_i\} * \{b_j\})_{j'}$  denotes the  $j'$ 'th term of the convolution of these two sequences, namely,  $\sum_i a_i b_{j'-i}$ .

Invoking the Young inequality for a series, we find

$$\begin{aligned} \text{(A.4)} \quad \|\dot{R}(u, v)\|_{\dot{B}_{p,q}^s} &= \|\{2^{j's} \|\Delta_{j'} \dot{R}(u, v)\|_{L^p}\}\|_{\ell^q} \\ &\leq C \|u\|_{L^{p_1}} \|\{a_i\} * \{2^{is} \|\dot{\Delta}_i v\|_{L^{p_2}}\}\|_{\ell^q} \\ &\leq C \|u\|_{L^{p_1}} \|\{a_i\}_{\ell^1}\| \|\{2^{is} \|\dot{\Delta}_i v\|_{L^{p_2}}\}\|_{\ell^q} \\ &\leq C \|u\|_{L^{p_1}} \|v\|_{\dot{B}_{p_2,q}^s} \end{aligned}$$

(since  $s > 0$ ). Combining (A.2)–(A.4), the proof of Lemma A.1 is concluded.  $\square$

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