# Range characterization of Radon transforms on complex projective spaces 

By<br>Tomoyuki Kakehi

## § 0. Introduction

The purpose of this paper is to characterize the ranges of Radon transforms on $\boldsymbol{P}^{n} \boldsymbol{C}$ by invariant differential operators.

Range characterization of a Radon transform by a differential operator was first treated by F. John 18]. Consider the set $M$ of all lines in $\boldsymbol{R}^{3}$ of the form

$$
l: x=\alpha_{1} t+\beta_{1}, \quad y=\alpha_{2} t+\beta_{2}, \quad z=t, \quad(t: \text { parameter }) .
$$

We define a coordinate system on $M$ by $l \mapsto\left(\alpha_{1}, \alpha_{2}, \beta_{1}, \beta_{2}\right) \in \boldsymbol{R}^{4}$. Let $R: C_{0}^{\infty}\left(\boldsymbol{R}^{3}\right) \rightarrow C_{0}^{\infty}(M)$ be the Radon transform defined by

$$
R f(l)=\int_{-\infty}^{\infty} f\left(\alpha_{1} t+\beta_{1}, \alpha_{2} t+\beta_{2}, t\right) d t \quad \text { for } f \in C_{1}^{\infty}\left(\boldsymbol{R}^{3}\right)
$$

Then it is easily chacked that the range of $R$ is included in the kernel of an ultrahyperbolic differential operator $P$ defined by

$$
\begin{equation*}
P=\frac{\partial^{2}}{\partial \alpha_{1} \partial \beta_{2}}-\frac{\partial^{2}}{\partial \alpha_{2} \partial \beta_{1}}, \tag{0.1}
\end{equation*}
$$

and, in fact, F . John showed that $\operatorname{Ker} P=\operatorname{Im} R$, that is, the range of $R$ is characterized by $P$. Gelfand, Graev, and Gindikin [1] later extended F. John's result to Radon transforms on $\boldsymbol{R}^{n}$ and $\boldsymbol{C}^{n}$. They characterized the range of the $d$-plane Radon transform on $\boldsymbol{R}^{n}$ (resp. on $\boldsymbol{C}^{n}$ ) ( $d<n-1$ ) by a system of second order differential operators on a corresponding real (resp. complex) affine Grassmann manifold.

For Radon transforms on compact symmetric spaces, there exists Grinberg's result [4]. He showed that the range of the projective $d$-plane Radon transform on a real or complex projective space is characterized by an invariant system of second order differential operators in a corresponding compact Grassman manifold. We notice that his construction of the system was led by representation theoretical consideration.

On the other hand, our approach is based on the idea of F. John, which yields characterization by a single invariant differential operator on a Grassmann manifold. In fact, the range-characterizing operator can be represented as an ultrahyperbolic differential operator like ( 0.1 ) on a vector bundle, but we here treat the one reduced to a single differential operator for the sake of simplicity.

Let $M$ be the set of all projective $l$-planes in $\boldsymbol{P}^{n} \boldsymbol{C}$, which is a complex Grassmann manifold and is a compact symmetric space of rank $\min \{l+1, n-l\}$.

We define a Radon transform $R: C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right) \rightarrow C^{\infty}(M)$ by

$$
R f(\xi)=\frac{1}{\operatorname{Vol}\left(\boldsymbol{P}^{l} \boldsymbol{C}\right)} \int_{x \in \xi} f(x) d v_{\xi}(x), \quad \xi \in M, \quad f \in C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right),
$$

where $d v_{\xi}(x)$ denotes the measure on $\xi\left(\subset \boldsymbol{P}^{n} \boldsymbol{C}\right)$ induced by the canonical measure on $P^{n} C$.

We assume that rank $M \geqq 2$, that is, $1 \leqq l \leqq n-2$. The main theorem of this paper is as follows.

Theorem. There exists a fourth order invariant differential operator $P$ on $M$ such that the range of the Radon transform $R$ is characterized by $P$, i.e., $\operatorname{Ker} P=\operatorname{Im} R$.

The explicit form of $P$ will be given in the next section.
The author would like to thank Professor Chiaki Tsukamoto for suggesting the problem and for many valuable discussions.

## § 1. Invariant differential operator $P$

Let $M$ be the set of all $(l+1)$-dimensional complex vector subspaces of $\boldsymbol{C}^{n+1}$, that is, the set of projective $l$-planes in $\boldsymbol{P}^{n} \boldsymbol{C}$. Then $M$ is a compact symmetric space $S U(n+1) / S(U(l+1) \times U(n-l))$ of rank $\min \{l+1, n-l\}$. We assume that $r:=\operatorname{rank} M \geqq 2$, that is, $1 \leqq l \leqq n-2$.

For a Lie group $G$ and its closed subgroup $H$, we denote by $C^{\infty}(G, H)$ the set $\left\{f \in C^{\infty}(G) ; f(g h)=f(g) \forall g \in G\right.$ and $\left.\forall h \in H\right\}$, and we identify $C^{\infty}(G, H)$ with $C^{\infty}(G / H)$. We define an action $L_{g}$ of $G$ on $C^{\infty}(G)$ by $\left(L_{g} f\right)(x)=f\left(g^{-1} x\right)$ for $x \in G$, and $f \in C^{\infty}(G)$. Similarly we define an action $R_{g}$ of $G$ on $C^{\infty}(G)$ by $\left(R_{g} f\right)(x)=f(x g)$. A differential operator $D$ on $G$ is called left- $G$-invariant if $L_{g} D=D L_{g}$ for all $g \in G$. Similarly, $D$ is called right- $H$-invariant if $R_{h} D=D R_{h}$ for all $h \in H$. We identify a right- $H$-invariant differential operator on $G$ with a differential operator on $G / H$.

Let $G, K$, and $K^{\prime}$ be the groups $S U(n+1), S(U(l+1) \times U(n-l))$, and $S(U(1) \times U(n))$, respectively. Then we have $M=G / K, \boldsymbol{P}^{n} \boldsymbol{C}=G / K^{\prime}$, and by the above identification, $C^{\infty}(G, K)=C^{\infty}(M), \quad C^{\infty}\left(G, K^{n}\right)=C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right)$. We choose a Killing form metrics on $G$, which induces metrics on $K, K^{\prime}, M$, and $\boldsymbol{P}^{n} \boldsymbol{C}$. Let $g$ and $\mathfrak{f}$ denote the Lie algebras of $G$ and $K$, respectively,

$$
\begin{gathered}
\mathrm{g}=\left\{X \in M_{n+1}(\boldsymbol{C}) ; X+X^{*}=0, \operatorname{tr} X=0\right\}, \\
\mathfrak{f}=\left\{\left(\begin{array}{cc}
X_{1} & 0 \\
0 & X_{2}
\end{array}\right) \in \mathrm{g} ; X_{1} \in M_{l+1}(\boldsymbol{C}), \quad X_{2} \in M_{n-l}(\boldsymbol{C})\right\} .
\end{gathered}
$$

Let $\mathfrak{g}=\mathfrak{f} \oplus \mathfrak{m}$ be the Cartan decomposition, where $\mathfrak{m}$ is all the matrices of the form

$$
Z=\left(\begin{array}{cccccc}
0 & \cdots & 0 & -\bar{z}_{l+2,1} & \cdots & -\bar{z}_{n+1,1} \\
\vdots & & \vdots & \vdots & & \\
0 & \cdots & 0 & -\bar{z}_{l+2, l+1} & \cdots & -\bar{z}_{n+1, l+1} \\
z_{l+2,1} & \cdots & z_{l+2, l+1} & 0 & \cdots & 0 \\
\vdots & & \vdots & \vdots & & \vdots \\
z_{n+1,1} & \cdots & z_{n+1, l+1} & 0 & \cdots & 0
\end{array}\right) .
$$

We define second order differential operators $L_{i j, \alpha \beta}(l+2 \leqq i<j \leqq n+1,1 \leqq \alpha<\beta \leqq l+1)$ and a fourth order differential operator $P$ on $G$ as follows.

$$
\begin{gathered}
L_{i j, \alpha \beta} f(g)=\left.\left(\frac{\partial^{2}}{\partial z_{i \alpha} \partial z_{j \beta}}-\frac{\partial^{2}}{\partial z_{i \beta} \partial z_{j \alpha}}\right) f(g \exp Z)\right|_{z=0}, \quad f \in C^{\infty}(G), \\
P=\sum_{\substack{l+2 \leq i<j \leq n+1 \\
1 \leq \alpha<\beta \leq l+1}} L_{i j, \alpha \beta}^{*} L_{i j, \alpha \beta},
\end{gathered}
$$

where $L_{i j, \alpha \beta}^{*}$ denotes the adjoint operator of $L_{i j, \alpha \beta}$ and is given by

$$
L_{i j, \alpha \beta}^{*} f(g)=\left.\left(\frac{\partial^{2}}{\partial \bar{z}_{i \alpha} \partial \bar{z}_{j \beta}}-\frac{\partial^{2}}{\partial \bar{z}_{i \beta} \partial \bar{z}_{j \alpha}}\right) f(g \exp Z)\right|_{z=0} .
$$

Lemma 1.1. $P$ is a right-K-invariant differential operator.
Proof. We define Ad- $K$-invariant polynomials $F_{j}(Z)(j=1,2, \cdots)$ on $\mathfrak{m}$ by

$$
\operatorname{det}(\lambda I+Z)=\lambda^{n+1}+F_{1}(Z) \lambda^{n-1}+F_{2}(Z) \lambda^{n-3}+\cdots .
$$

Then we have

$$
\begin{equation*}
F_{2}(Z)=\sum_{\substack{l+2 \leq i<j=n+1 \\ 1 \leqq \alpha<\beta l+1}}\left(\bar{z}_{i \alpha} \bar{z}_{j \beta}-\bar{z}_{i \beta} \bar{z}_{j \alpha}\right)\left(z_{i \alpha} z_{j \beta}-z_{i \beta} z_{j \alpha}\right) . \tag{1.1}
\end{equation*}
$$

On the other hand, we have

$$
R_{k} P R_{k^{-1}}=\sum_{\substack{l+2 \leq i=j \leq j \leq n+1 \\ 1 \leqslant \alpha-\beta \leqslant l+1}} R_{k} L_{i j, \alpha \beta}^{*} R_{k^{-1}} \circ R_{k} L_{i j, \alpha \beta} R_{k^{-1}},
$$

where

$$
\begin{aligned}
& R_{k} L_{i j, \alpha \beta} R_{k-1} f(g)=\left.\left(\frac{\partial^{2}}{\partial z_{i \alpha} \partial z_{j \beta}}-\frac{\partial^{2}}{\partial z_{i \beta} \partial z_{j \alpha}}\right) f\left(g \exp k Z k^{-1}\right)\right|_{z=0}, \\
& R_{k} L_{i j, \alpha \beta}^{*} R_{k-1} f(g)=\left.\left(\frac{\partial^{2}}{\partial \bar{z}_{i \alpha} \partial \bar{z}_{j \beta}}-\frac{\partial^{2}}{\partial \bar{z}_{i \alpha} \partial \bar{z}_{j \alpha}}\right) f\left(g \exp k Z k^{-1}\right)\right|_{z=0},
\end{aligned}
$$

for $f \in C^{\infty}(G)$ and $k \in K$.
Thus, we have only to prove that $P$ is invariant under the linear transform $Z \mapsto$ $k Z k^{-1}=A d_{k} Z$, which follows easily from the fact that the polynomial $F_{2}(Z)$ is Ad- $K$ invariant.

It is obvious that $P$ is left- $G$-invariant. Therefore, $P$ is well-defined as an invariant differential operator on $M$.

The purpose of this paper is to prove the following theorem.

Theorem 1.2. The range of the Radon transform $R$ is characterized by the invariant differential operator $P$, that is, $\operatorname{Ker} P=\operatorname{Im} R$.

Remark 1.3. The above differential operators $L_{i j, \alpha \beta}$ and $L_{i j, \alpha \beta}^{*}$ are of the form similar to (0.1). In this sense, we can say that the range of the Radon transform on $\boldsymbol{P}^{n} \boldsymbol{C}$ is also characterized by an ultrahyperbolic differential operator.

## §2. Proof that Im $R \subset K e r P$

We first prove that $\operatorname{Im} R \subset \operatorname{Ker} P$. By the identification $C^{\infty}\left(G, K\left(=C^{\infty}(M)\right.\right.$ and $C^{\infty}\left(G, K^{\prime}\right)=C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right)$, we consider the Redon transform $R$ as a map from $C^{\infty}\left(G, K^{\prime}\right)$ to $C^{\infty}(G, K)$. Then $R$ is given by

$$
\begin{equation*}
(R f)(g)=\frac{1}{\operatorname{Vol}(K)} \int_{k \in K} f(g k) d k, \quad f \in C^{\infty}\left(G, K^{\prime}\right) . \tag{2.1}
\end{equation*}
$$

From this section, we use the representation of the form (2.1).
We define a bilinear form $\langle\cdot, \cdot\rangle$ on $C^{n+1} \times C^{n+1}$ by $\langle u, v\rangle=\sum_{j=1}^{n+1} u_{j} v_{j}$ for $u=$ $\left(u_{1}, \cdots, u_{n+1}\right), v=\left(v_{1}, \cdots, v_{n+1}\right)$, and a function $h_{a, b}^{m} \in C^{\infty}(G)$ by $h_{a, b}^{m}(g)=\left\langle a, g \boldsymbol{e}_{1}\right\rangle^{m}\left\langle b \overline{\boldsymbol{e}} \overline{\boldsymbol{e}}_{1}\right\rangle^{m}$, where $a, b \in \boldsymbol{C}^{n+1}, \boldsymbol{e}_{1}=(1,0, \cdots, 0) \in \boldsymbol{C}^{n+1}$ and $m$ is a nonnegative integer. It is easily checked that $h_{a}^{m}{ }_{b} \in C_{\infty}\left(G, K^{\prime}\right)$, that is, $h_{a, b}^{m} \in C^{\infty}\left(\boldsymbol{P}^{n}(\boldsymbol{C})\right.$. Moreover the following lemma holds.

Lemma 2.1. Let $V_{m}$ denote the subspace of $C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right)$ generated by the set $\left\{h_{a, b}^{m} ;\langle a, b\rangle=0\right\}$. Then $V_{m}$ is the eigenspace of $\Delta_{P n c}$, the Laplacian on $\boldsymbol{P}^{n} \boldsymbol{C}$, corresponding to the $m$-th eigenvalue and $V_{m}$ is irreducible under the action of $G$.

For the proof, see [10] § 14.
Proposition 2.2. Im $R \subset \operatorname{Ker} P$.
Proof. Since $P$ and $R$ are $G$-invariant operators and $L_{g^{-1}} h_{a, b}^{m}=h_{g^{* a, ~}{ }^{*} b}^{m}$, we have

$$
P\left(R\left(h_{a, b}^{m}\right)\right)(g)=P\left(R\left(h_{g^{* a}, \boldsymbol{g}^{*} b}^{m}\right)\right)(I),
$$

where $I$ denotes the $(n+1) \times(n+1)$ identity matrix.
Since the direct sum $\oplus_{m=0}^{\infty} R\left(V^{m}\right)$ is dense in Im $R$ in $C^{\infty}$-topology, we have only to prove $P\left(R\left(h_{a, b}^{m}\right)(I)=0\right.$, or,

$$
\begin{aligned}
& L_{i j, \alpha \beta}\left(R\left(h_{a}^{m}\right)\right)(I) \\
& \quad=\left.\frac{1}{\operatorname{Vol}(K)}\left(\frac{\partial^{2}}{\partial z_{i \alpha} \partial z_{j \beta}}-\frac{\partial^{2}}{\partial z_{i \beta} \partial z_{j \alpha}}\right) \int_{k \in K} h_{a, b}^{m}((\exp Z) k) d k\right|_{Z=0} \\
& \quad=0 .
\end{aligned}
$$

Here we have

$$
\begin{aligned}
& \left.\left(\frac{\partial^{2}}{\partial z_{i \alpha} \partial z_{j \beta}}-\frac{\partial^{2}}{\partial z_{i \beta} \partial z_{j \alpha}}\right)\left\{\left\langle a,(\exp Z) k \boldsymbol{e}_{1}\right\rangle^{m}\left\langle b,(\exp Z) k \boldsymbol{e}_{1}\right\rangle^{m}\right\}\right|_{z=0} \\
& \quad=m(m-1)\left\langle a, k \boldsymbol{e}_{1}\right\rangle^{m-2}\left\langle b, \overline{k \boldsymbol{e}_{1}}\right\rangle^{m} \\
& \quad \times\left\{\frac{\partial}{\partial z_{i \alpha}}\left\langle a, Z k \boldsymbol{e}_{1}\right\rangle \frac{\partial}{\partial z_{j \beta}}\left\langle a, Z k \boldsymbol{e}_{1}\right\rangle-\frac{\partial}{\partial z_{j \alpha}}\left\langle a, Z k \boldsymbol{e}_{1}\right\rangle \frac{\partial}{\partial z_{i \beta}}\left\langle a, Z k \boldsymbol{e}_{1}\right\rangle\right\} \\
& =m(m-1)\left(a_{i} k_{\alpha 1} a_{j} k_{\beta_{1}}-a_{i} k_{\beta 1} a_{j} k_{\alpha 1}\right)\left\langle a, k \boldsymbol{e}_{1}\right\rangle^{m-2}\left\langle b, \overline{k \boldsymbol{e}_{1}}\right\rangle^{m}=0,
\end{aligned}
$$

where $k \in K$, and $k_{i j}$ denotes the $(i, j)$ entry of $k$. In the above computation, we used the fact that the polynomial $\left\langle b, \overline{Z k e_{1}}\right\rangle$ on $\mathfrak{m}$ is a linear combination of $\bar{z}_{p q}$ 's and the fact that the polynomial $\left\langle a, Z^{2} k \boldsymbol{e}_{1}\right\rangle$ and $\left\langle b, \overline{Z^{2} k \boldsymbol{e}_{1}}\right\rangle$ on m consist only of the terms of the form (constant) $\times z_{p q} \bar{z}_{p^{\prime} q^{\prime}}$.)

Therefore the assertion is verified.

## § 3. The inversion Formula

We construct a continuous linear map $S: C^{\infty}(M) \rightarrow C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right)$ such that $S R=I d$, where $I d$ denotes the identity map.

Let $\Xi$ denote the set of ( $n-1$ ) dimensional complex projective subspaces of $\boldsymbol{P}^{n} \boldsymbol{C}$. Then $\Xi=S U(n+1) / S(U(n) \times U(1))$, and we put $K^{\prime \prime}=S(U(n) \times U(1))$. We define a Radon transform $\mathscr{I}: C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right) \rightarrow C^{\infty}(\boldsymbol{E})$ and its dual Radon transform $\dot{\mathscr{I}}: C^{\infty}(\boldsymbol{\Xi}) \rightarrow C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right)$ by

$$
\begin{array}{ll}
\mathscr{F} f(g)=\frac{1}{\operatorname{Vol}\left(K^{\prime \prime}\right)} \int_{k^{\prime \prime} \in K^{\prime \prime}} f\left(g k^{\prime \prime}\right) d k^{\prime \prime}, & f \in C^{\infty}\left(G, K^{\prime}\right), \\
\check{\mathscr{F}} \phi(g)=\frac{1}{\operatorname{Vol}\left(K^{\prime}\right)} \int_{k^{\prime} \in K^{\prime}} \phi\left(g k^{\prime}\right) d k^{\prime}, & \phi \in C^{\infty}\left(G, K^{\prime \prime}\right) .
\end{array}
$$

We define a polynomial $\Phi(t)$ by

$$
\Phi(t)=\left(t+\frac{(n-1) 1}{n+1}\right)\left(t+\frac{(n-2) 2}{n+1}\right) \cdots\left(t+\frac{1(n-1)}{n+1}\right) .
$$

Theorem 3.1 (Helgason [6], Ch. 1, Theorem 4.11). We have the inversion formula

$$
c_{n} \Psi\left(\Delta_{P n c}\right) \check{\mathscr{F}} \mathscr{F}=I d,
$$

where $c_{n}$ is a constant depending on $n$.

Proposition 3.2. There exists an inversion map $S: C^{\infty}(M) \rightarrow C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right)$ such that $S R=l d$.

Proof. We define a continuous linear map $\tilde{R}: C^{\infty}(M) \rightarrow C^{\infty}(\boldsymbol{\Xi})$ by

$$
\tilde{R} f(g)=\frac{1}{\operatorname{Vol}\left(K^{\prime \prime}\right)} \int_{k^{\prime \prime} \in K^{\prime \prime}} f\left(g k^{\prime \prime}\right) d k^{\prime \prime}, \quad f \in C^{\infty}(G, K) .
$$

Then, it is easily checked that $\tilde{R} R=\mathscr{F}$. Therefore, if we put

$$
\begin{equation*}
S=c_{n} \Phi\left(\Lambda_{P n c}\right) \check{\mathscr{L}} \tilde{R} \tag{3.1}
\end{equation*}
$$

we get $S R=I d$ by Theorem 3.1.

## § 4. Representation of ( $G, K$ )

In this section, we describe the root, the weight, and the Weyl group of ( $G, K$ ).
Let $\mathfrak{a} \subset \mathfrak{m}$ be the set of all matrices of the form

$$
H(t)=H\left(t_{1}, \cdots, t_{r}\right)=\sqrt{ }-1\left(\begin{array}{cccccc}
0 & \cdots & 0 & t_{1} & & \\
\vdots & & \vdots & & \ddots & \\
0 & \cdots & 0 & & & t_{r} \\
t_{1} & & & 0 & \cdots & 0 \\
& \ddots & & \vdots & & \vdots \\
& & t_{r} & & & \\
& & & 0 & \cdots & 0
\end{array}\right) .
$$

where we put $r=\operatorname{rank} M(=\operatorname{rank} G / K)$ in Section 1 and $t=\left(t_{1}, \cdots, t_{r}\right) \in \boldsymbol{R}^{r}$. Then, $\mathfrak{a}$ is a maximal abelian subalgebra of m . We identify $\mathfrak{a}$ with $\boldsymbol{R}^{r}$ by the mapping $H(t) \mapsto t$.

Let $(\cdot, \cdot)$ denote an invariant inner product on $g$ defined by

$$
(X, Y)=-2(n+1) \operatorname{tr}(X Y), \quad X, Y \in g,
$$

which is a minus signed Killing form on $\mathfrak{g}$.
For $\alpha \in \mathfrak{a}$, we set $\mathfrak{g}_{\alpha}:=\left\{X \in \mathfrak{g}^{c} ;[H, X]=\sqrt{-1}(\alpha, H) X\right.$ for all $\left.H \in \mathfrak{a}\right]$, and $\alpha$ is called a root of ( $\mathfrak{g}, \mathfrak{a}$ ) when $\mathfrak{g}_{\alpha} \neq\{0\}$. We put $m_{\alpha}=\operatorname{dim}_{c} \mathfrak{g}_{\alpha}$, and call it a multiplicity of $\alpha$.

We put $H_{i}=H(0, \cdots, \stackrel{(i)}{1}, \cdots, 0)(1 \leqq i \leqq r)$. Then the roots of $(\mathfrak{g}, \mathfrak{a})$ and their multiplicities are given by the table:

$$
\begin{array}{ccc}
\alpha & m_{\Omega} \\
\pm \frac{1}{2(n+1)} H_{j} & 1 & (1 \leqq j \leqq r), \\
\pm \frac{1}{4(n+1)} H_{j} & 2(n+1-2 r) & (1 \leqq j \leqq r), \\
\pm \frac{1}{4(n+1)}\left(H_{j} \pm H_{k}\right) & 2 & (1 \leqq j<k \leqq r),
\end{array}
$$

We fix a lexicographical order $<$ on a such that $H_{1}>\cdots>H_{r}>0$. Then the positive roots are $(1 / 2(n+1)) H_{j},(1 / 4(n+1)) H_{j},(1 \leqq j \leqq r),(1 / 4(n+1))\left(H_{j} \pm H_{k}\right),(1 \leqq j<k \leqq r)$. The simple roots are $(1 / 4(n+1))\left(H_{1}-H_{2}\right),(1 / 4(n+1))\left(H_{2}-H_{3}\right), \cdots,(1 / 4(n+1))\left(H_{r-1}-H_{r}\right)$, $(1 / 4(n+1)) H_{r}$. We define the positive Weyl chamber $\mathcal{A}^{+}$by $\left\{t \in \boldsymbol{R}^{r} ; 0<t_{j}<\pi / 2\right.$ $\left.(1 \leqq j \leqq r), t_{1}>\cdots>t_{r}\right\}$.

We set

$$
\Omega((\exp H(t)) K):=\mid \prod_{\alpha: \text { positive root }}\left(e^{\gamma-\overline{1}(\alpha, H(t))}-e^{-\sqrt{-1(\alpha, H(t))})^{m} \alpha \mid .}\right.
$$

We consider $\Omega$ as a density function on $\boldsymbol{R}^{+}$, and we have
(4.1)

$$
\begin{gathered}
\Omega=\sigma \omega^{2}, \\
\text { where } \sigma=2^{r(2 n-2 r+3)}\left|\prod_{j=1}^{r} \sin 2 t_{j} \sin 2(n-r+1) t_{j}\right|, \\
\omega=2^{(1 / 2) r(r-1)} \prod_{j<k}\left(\cos 2 t_{j}-\cos 2 t_{k}\right) .
\end{gathered}
$$

The Satake diagram of $G / K$ is given by (4.2) or (4.3),

$$
\text { case } A \quad n+1>2 r \text { : }
$$



$$
\text { case } B \quad n+1=2 r \text { : }
$$



In the diagram (4.2) or (4.3), $\Lambda_{1}, \cdots, \Lambda_{n}$ denote the fundamental weights of $\mathfrak{g}$, corresponding to the simple roots of g .

Since rank $G / K=r$, there are $r$ fundamental weights $M_{1}, \cdots, M_{r}$ of $(G, K)$. By the diagram (4.2) or (4.3), $M_{1}, \cdots, M_{r}$ are given by

$$
\begin{aligned}
& M_{1}=\Lambda_{1}+\Lambda_{n}, \cdots, M_{r-1}=\Lambda_{r-1}+\Lambda_{n-r+2}, M_{r}=\Lambda_{r}+\Lambda_{n-r+1}, \quad(\text { case A) }, \\
& M_{1}=\Lambda_{1}+\Lambda_{n}, \cdots, M_{r-1}=\Lambda_{r-1}+\Lambda_{n-r+2}, M_{r}=2 \Lambda_{r}, \quad \text { (case B). }
\end{aligned}
$$

Then we have

$$
M_{k}=\frac{1}{2(n+1)} \sum_{j=1}^{k} H_{j}, \quad(1 \leqq k \leqq r)
$$

Let $Z(G, K)$ be the weight lattice, that is, $Z(G, K)=\left\{\left(1(4(n+1))\left(\mu_{1} H_{1}+\cdots+\mu_{r} H_{r}\right)\right.\right.$; $\left.\mu_{1}, \cdots, \mu_{r} \in \boldsymbol{Z}\right\}$. The highest weight of a spherical representation of $(G, K)$ is of the form $m_{1} M_{1}+\cdots+m_{r} M_{r}$, where $m_{1}, \cdots, m_{r}$ are non-negative integers. Let $V\left(m_{1}, \cdots, m_{r}\right)$ denote the eigenspace of the Laplacian $A_{M}$ on $G / K$ that is an irreducible representation space with the highest weight $m_{1} M_{1}+\cdots+m_{r} M_{r}$.

The Weyl group $W(G, K)$ of $(G, K)$ is the set of all maps $s: \mathfrak{a} \rightarrow \mathfrak{a}$ such that

$$
s:\left(t_{1}, \cdots, t_{r}\right) \longmapsto\left(\varepsilon_{1} t_{\sigma(1)}, \cdots, \varepsilon_{r} t_{\sigma(r)}\right), \quad \varepsilon_{j}= \pm 1, \sigma \in \mathbb{S}_{r},
$$

## § 5. Radial part of $P$

We calculate the radial part of the invariant differential operator $P$. The result in this section is used to calculate the eigenvalues of $P$ in the next section.

To each invariant differential operator $D$ on $G / K$, there corresponds a unique
differential operator on Weyl chambers which is invariant under the action of the Weyl group $W(G, K)$. This operator is called a radial part of $D$, and we denote it by $\operatorname{rad}(D)$.

The following lemma is well-known. (See [10] Theorem 10.4.)
Lemma 5.1. The radial part of the Laplacian $\Delta_{M}$ on $M$ is given by

$$
\operatorname{rad}\left(\Delta_{M}\right)=-\frac{1}{4(n+1)} \sum_{j=1}^{r}\left(\frac{\partial^{2}}{\partial t_{j}^{2}}+\frac{\Omega_{t_{j}}}{\Omega} \frac{\partial}{\partial t_{j}}\right) .
$$

We define a differential operator $Q_{1}$ on $\boldsymbol{R}^{r}$ by

$$
Q_{1}:=\frac{1}{\omega} \sum_{j=1}^{r}\left(\frac{\partial^{2}}{\partial t_{j}{ }^{2}}+\frac{\sigma_{t_{j}}}{\sigma} \frac{\partial}{\partial t_{j}}\right) \circ \omega .
$$

The next lemma is easily checked.

## Lemma 5.2.

$$
-4(n+1) \operatorname{rad}\left(\Delta_{M}\right)=Q_{1}-\sum_{j=1}^{r} 4 j(j+n+2-2 r) .
$$

We consider the following conditions $(A),(B),(C)$ and $(D)$ on a differential operater $Q$ on $\boldsymbol{R}^{r}$ that is regular in all Weyl chambers.
(A) $Q=\frac{1}{16} \Sigma_{j<k} \frac{\partial^{2}}{\partial t_{j}{ }^{2}} \frac{\partial^{2}}{\partial t_{k}{ }^{2}}+$ lower order terms.
(B) $Q$ is formally self-adjoint with respect to the density $\Omega d$.
(C) $Q$ is $W(G, K)$-invariant.
(D) $\left[Q, \operatorname{rad}\left(\Lambda_{M}\right)\right]:=Q \operatorname{rad}\left(\Lambda_{M}\right)-\operatorname{rad}\left(\Delta_{M}\right) Q=0$.

Then the differential operator $\operatorname{rad}(P)$ satisfies the above four conditions $(A),(B)$, $(C)$, and $(D)$. Indeed, the principal symbol of $P$ is given by $\frac{1}{16} F_{2}(Z)$, which was
 fore its restriction to a $\frac{1}{16} F_{2}(H(t))$ is $\frac{1}{16} \sum_{j<k} t_{j}^{2} t_{k}^{2}$, and the condition (A) holds. The condition ( $B$ ) follows from the self-adjointness of $P$. Since $P$ is an invariant differential opərator, the conditions ( $C$ ) and ( $D$ ) are easily verified.

We defined a differential operator $Q_{2}$ by

$$
Q_{2}:=\frac{1}{16 \omega} \sum_{j<k}\left(\frac{\partial^{2}}{\partial t_{j}{ }^{2}}+\frac{\sigma_{\iota_{j}}}{\sigma} \frac{\partial}{\partial t_{j}}\right)\left(\frac{\partial^{2}}{\partial t_{k}{ }^{2}}+\frac{\sigma_{\iota_{k}}}{\sigma} \frac{\partial}{\partial t_{k}}\right) \circ \omega .
$$

Lemma 5.3. The differential operator $Q_{2}$ satisfies the conditions $(A),(B),(C)$, and (D).

Proof. The condition ( $A$ ) is obvious. The condition ( $D$ ) follows from Lemma 5.2.

The conditions ( $B$ ) and ( $C$ ) are easily checked using the formula (4.3).

Lemma 5.4. If a differential operator $Q$ satisfies the conditions $(A),(B),(C)$ and $(D)$, then $Q$ can be written in the form

$$
Q=Q_{2}+c_{1} \operatorname{rad}\left(\Delta_{M}\right)+c_{2},
$$

for suitable constants $c_{1}, c_{2}$.
Proof. Because of the conditions $(A)$ and $(B), Q-Q_{2}$ is a second order differential operator and satisfies the conditions $(B),(C)$, and $(D)$. Therefore the proof is reduced to the following lemma.

Lemma 5.5. If a second order differential operator

$$
Q:=\sum_{j=1}^{r} A_{j} \frac{\partial^{2}}{\partial t_{j}{ }^{2}}+\sum_{j<k} B_{j_{k}} \frac{\partial^{2}}{\partial t_{j} \partial t_{k}}+\sum_{j=1}^{r} C_{j} \frac{\partial}{\partial t_{j}}
$$

satisfies the conditions $(B),(C)$, and ( $D$ ), then $Q$ can be written in the form

$$
Q=c \operatorname{rad}\left(\Delta_{M}\right),
$$

where $c$ is a suitable constant.
Proof. By the condition ( $D$ ), the third order terms of $\left[Q, \operatorname{rad}\left(\Delta_{M}\right)\right]$ vanish. Thus we have the following equations.

$$
\begin{array}{ll}
A_{j, t_{j}}=0 & (1 \leqq j \| \wedge r) ; \\
A_{k, \iota_{j}}+B_{j k, \iota_{k}}=0, \quad A_{j, \iota_{k}}+B_{j k, \iota_{j}}=0, & (j<k) ; \\
B_{i j, \iota_{k}}+B_{j k, t_{i}}+B_{i k, \iota_{j}}=0, & (1 \leqq i<j<k \leqq r) . \tag{5.3}
\end{array}
$$

By the equations (5.1), (5.2), and (5.3), we obtain

$$
\begin{align*}
& A_{j, \iota_{k} t_{k} \iota_{k}}=0, \quad(j \neq k) ;  \tag{5.4}\\
& B_{j k, t_{j} \iota_{j}}=B_{j k, \iota_{k} \iota_{k}}=0,  \tag{5.5}\\
& B_{j k, t_{i} t_{i} t_{i}}=0, \quad(i \neq j, k) . \tag{5.6}
\end{align*}
$$

From the condition ( $C$ ) and the equations (5.1-6), the coefficients $A_{j}$ and $B_{j k}$ are polynomials of the form

$$
\begin{align*}
& A_{j}=\delta_{1} \sum_{k \neq j} t_{k}^{2}+\delta_{2},  \tag{5.7}\\
& B_{j_{k}}=-2 \delta_{1} t_{j} t_{k}, \tag{5.8}
\end{align*}
$$

where $\delta_{1}$ and $\delta_{2}$ are some constants.
Using the conditions ( $B$ ), we have

$$
\begin{equation*}
C_{j}=\frac{1}{\Omega}\left(A_{j} \Omega\right)_{t_{j}}+\frac{1}{2 \Omega} \sum_{j<k}\left(B_{j k} \Omega\right)_{t_{k}}+\frac{1}{2 \Omega} \sum_{k<j}\left(B_{k j} \Omega\right)_{t_{k}} \tag{5.9}
\end{equation*}
$$

If $\delta_{1}=0$, then the coefficient $B_{j k}=0$, and the coefficient $C_{j}=\delta_{2} \Omega_{t_{j}} / \Omega$ by (5.9).

Therefore we obtain $Q=-4(n+1) \boldsymbol{\delta}_{2} \operatorname{rad}\left(\Lambda_{M}\right)$, and the lemma holds.
Now, we suppose that $\delta_{1} \neq 0$. Furthermore, we may suppose that $\delta_{1}=1$ and $\delta_{2}=0$. By the condition $(D)$, the first order terms of $\left[Q, \operatorname{rad}\left(\Delta_{M}\right)\right]$ vanish. Thus we have

$$
\begin{equation*}
Q a_{j}=-4(n+1) \operatorname{rad}\left(\Delta_{M}\right) C_{j} \quad(1 \leqq j \leqq r), \tag{5.10}
\end{equation*}
$$

where we put $a_{j}=\Omega_{t_{j}} / \Omega$.
We extend the both sides of (5.10) to $C$ as meromorphic functions of $t_{1}=\mu_{1}+\sqrt{-1} \nu_{1}$. By the formula (4.1), we have

$$
a_{1}=2 \frac{\cos 2 t_{1}}{\sin 2 t_{1}}+2(n-r+1) \frac{\cos t_{1}}{\sin t_{1}}+2 \sum_{j=2}^{r} \frac{-2 \sin 2 t_{1}}{\cos 2 t_{1}-\cos 2 t_{j}} .
$$

 fact holds for $a_{j}(j=2, \cdots, r)$. Thus $Q a_{1} \rightarrow 0$ (rapidly decreasing). Therefore we get $\operatorname{rad}\left(\Delta_{M}\right) C_{1} \rightarrow 0$ (rapidly decreasing) by (5.10). However, when $\nu_{1}$ tends to $+\infty$, we have

$$
\begin{aligned}
-4(n+1) \operatorname{rad}\left(\Delta_{M}\right) C_{1}= & \frac{1}{2} \sum_{j, k=2}^{r}\left(\frac{\partial^{2}}{\partial t_{k}^{2}}+a_{k} \begin{array}{c}
\partial \\
\partial t_{k}
\end{array}\right)\left(B_{1 j} a_{j}+B_{1 j, t_{j}}\right)+O(1) \\
& =-t_{1} \sum_{k=2}^{r} a_{k}^{2}+O(1) .
\end{aligned}
$$

(In the above computation, we used (5.7), (5.8) and the fact that $a_{j}=O(1)$ and the derivatives of $a_{j} \rightarrow 0$ as $\left.\nu_{1} \rightarrow \infty\right)$ Therefore, we have $\operatorname{rad}\left(\Delta_{M}\right) C_{1} \rightarrow \infty$, for suitable $t_{2}, \cdots, t_{r}$, and $\mu_{1}$. It is a contradiction.

Lemmas $5.1,5.2$, and 5.3 imply the following proposition.
Proposition 5.5. The differential operator $\operatorname{rad}(P)$ can be expressed in the form

$$
\operatorname{rad}(P)=Q_{2}+c_{1} Q_{1}+c_{2}
$$

for some constants $c_{2}, c_{2}$.

## §6. Proof of Theorem 1.2

We calculate the eigenvalue of $P$ on $V\left(m_{1}, \cdots, m_{r}\right)$ to prove Theorem 1.2.
Let $a\left(m_{1}, \cdots, m_{r}\right)$ be the eigenvalue of $P$ on $V\left(m_{1}, \cdots, m_{r}\right)$ and $\phi_{\left(m_{1}, \cdots, m_{r}\right)}$ the zonal spherical function which belongs to $V\left(m_{1}, \cdots, m_{r}\right)$. We denote by $u_{\left(m_{1}, \cdots, m_{r}\right)}$ the restriction of $\phi_{\left(m_{1}, \cdots, m_{r}\right)}$ to the Weyl chamber $\mathcal{A}^{+}$.

Lemma 6.1 ([10], Theorem 8.1). The function $u_{\left(m_{1}, \ldots, m_{r}\right)}$ has a Fourier series expansion on $\mathcal{A}^{+}$of the form

$$
u_{\left(m_{1}, \cdots, m_{r}\right)}\left(t_{1}, \cdots, t_{r}\right)=\sum_{\substack{\lambda_{s} m_{1} M_{1},+\cdots m_{r} M_{r}, \lambda \in Z(G, K), \text { finite sum }}} \eta_{\lambda} \exp \sqrt{-1}\left(\lambda, t_{1} H_{1}+\cdots+t_{r} H_{r}\right),
$$

where $\eta_{m_{1} M_{1}+\cdots+m_{r} M_{r}}>0$.
Let $f_{1}$ and $f_{2}$ be Fourier series on $\mathcal{A}^{+}$of the form

$$
\begin{aligned}
& f_{1}=\sum_{\lambda \leq 1_{1} \in \in Z(G, K)} \zeta_{\lambda} \exp \sqrt{-1}\left(\lambda, t_{1} H_{1}+\cdots+t_{r} H_{r}\right), \\
& f_{2}=\sum_{\lambda \leq A_{2} \lambda \in Z(G, K)} \tilde{\xi}_{\lambda} \exp \sqrt{-1}\left(\lambda, t_{1} H_{1}+\cdots+t_{r} H_{r}\right) .
\end{aligned}
$$

We denote $f_{1} \sim f_{2}$ when $\Lambda_{1}=\Lambda_{2}$ and $\zeta_{\Lambda_{1}}=\zeta_{\Lambda_{2}}(\neq 0)$. Obviously the relation $\sim$ is an equivalence relation.

Lemma 6.2. We have the following relations.

$$
\begin{gather*}
\sigma_{t_{j}} \sim 2 \sqrt{ }-1(n+2-2 r) \sigma  \tag{6.1}\\
\omega_{t_{j}} \sim 2 \sqrt{-1}(r-j) \omega  \tag{6.2}\\
\frac{\partial}{\partial t_{j}} u_{\left(m_{1}, \cdots, m_{r}\right)} \sim 2 \sqrt{-1}\left(m_{j}+m_{j+1}+\cdots+m_{r}\right) u_{\left(m_{1}, \cdots, m_{r}\right)} \tag{6.3}
\end{gather*}
$$

Proof. The relations (6.1) and (6.2) are easily checked. The relation (6.3) follows from Lemma 6.1.

## Lemma 6.3.

$$
\begin{align*}
a\left(m_{1}, \cdots, m_{r}\right)= & \sum_{j<k}\left(l_{j}+r-j\right)\left(l_{j}+n+2-r-j\right)\left(l_{k}+r-k\right)\left(l_{k}+n+2-r-k\right)  \tag{6.4}\\
& -4 c_{1} \sum_{j=1}^{r}\left(l_{j}+r-j\right)\left(l_{j}+n+2-r-j\right)+c_{2},
\end{align*}
$$

where $c_{1}$ and $c_{2}$ are constants in Proposition 5.5, and $l_{j}=m_{j}+m_{j+1}+\cdots+m_{r}$.
Proof. Since $\phi_{\left(m_{1} \cdots, m_{r}\right)} \in V\left(m_{1}, \cdots, m_{r}\right)$,

$$
\begin{equation*}
P \phi_{\left(m_{1}, \cdots, m_{r}\right)}=a\left(m_{1}, \cdots, m_{r}\right) \dot{\phi}_{\left(m_{1}, \cdots, m_{r}\right)} . \tag{6.5}
\end{equation*}
$$

We restrict the both sides of (6.5) to $\mathcal{A}^{+}$, and then we have

$$
\operatorname{rad}(P) u_{\left(m_{1}, \cdots, m_{r}\right)}=a\left(m_{1}, \cdots, m_{r}\right) u_{\left(m_{1}, \cdots, m_{r}\right)} .
$$

By Proposition 5.4, we get

$$
\begin{aligned}
& \sigma^{2} \omega \sum_{j<k} \frac{1}{\omega}\left(\frac{\partial^{2}}{\partial t_{j}{ }^{2}}+\frac{\sigma_{t_{j}}}{\sigma} \frac{\partial}{\partial t_{j}}\right)\left(\frac{\partial^{2}}{\partial t_{k}{ }^{2}}+\frac{\sigma_{t_{k}}}{\sigma} \frac{\partial}{\partial t_{k}}\right)\left(\omega u_{\left(m_{1}, \cdots, m_{r}\right)}\right) \\
& \quad+c_{1} \sigma^{2} \omega \sum_{j=1} \frac{1}{\omega}\left(\frac{\partial^{2}}{\partial t_{j}{ }^{2}}+\frac{\sigma_{t_{j}}}{\sigma} \frac{\partial}{\partial t_{j}}\right)\left(\omega u_{\left(m_{1}, \cdots, m_{r}\right)}\right)+c_{2} \sigma^{2} \omega u_{\left(m_{1}, \cdots, m_{r}\right)} \\
& =a\left(m_{1}, \cdots, m_{r}\right) \sigma^{2} \omega u_{\left(m_{1}, \cdots, m_{r}\right)} .
\end{aligned}
$$

Using Lemma 6.2, we have

$$
\begin{align*}
& \sum_{j<k}\left\{\left(l_{j}+r-j\right)\left(l_{j}+n+2-r-j\right)\left(l_{k}+r-k\right)\left(l_{k}+n+2-r-k\right) \sigma^{2} \omega u_{\left(m_{1}, \cdots, m_{r}\right)}\right\} \\
& -4 c_{1} \sum_{j=1}^{r}\left(l_{j}+r-j\right)\left(l_{j}+n+2-r-j\right) \sigma^{2} \omega u_{\left(m_{1}, \cdots, m_{r}\right)}+c_{2} \sigma^{2} \omega u_{\left(m_{1}, \cdots, m_{r}\right)}  \tag{6.6}\\
& \quad \sim a\left(m_{1}, \cdots, m_{r}\right) \sigma^{2} \omega u_{\left(m_{1}, \cdots, m_{r}\right)} .
\end{align*}
$$

Comparing the leading coefficients of the both sides of (6.6), we get (6.4).
Lemma 6.4. $R: V_{m} \rightarrow V(m, 0, \cdots, 0)$ is an isomorphism.
Froof. By Proposition 3.2, $R$ is $G$-equivariant and one to one. Thus we have only to prove that the highest weight of $V_{m}$ is equal to that of $V(m, 0, \cdots, 0)$. The Satake diagram of $\boldsymbol{P}^{\boldsymbol{n}} \boldsymbol{C}$ is given by


Comparing (6.7) with the diagram (4.2) or (4.3), we find that $V_{m}$ corresponds to $m M_{1}$. On the other hand, the highest weight of $V(m, 0, \cdots, 0)$ is $m M_{1}$ by definition. This completes our proof.

Now, we can calculate the eigenvalue of $P$ by combining the above lemmas.
Theorem 6.5. The eigenvalue $a\left(m_{1}, \cdots, m_{r}\right)$ of $P$ on $V\left(m_{1}, \cdots, m_{r}\right)$ is given by

$$
\begin{align*}
a\left(m_{1}, \cdots, m_{r}\right)= & \sum_{j<k} l_{j} l_{k}\left(l_{j}+n+2-2 j\right)\left(l_{k}+n+2-2 k\right)  \tag{6.8}\\
& +\sum_{j=2}^{r}(j-1)(n+1-j) l_{j}\left(l_{j}+n+2-2 j\right),
\end{align*}
$$

where $l_{j}=m_{j}+m_{j+1}+\cdots+m_{r}$.
Proof. By Proposition 2.2 and Lemma 6.4 , we have $a(m, 0, \cdots, 0)=0$ for any nonnegative integer $m$. Then, by Lemma 6.3, we have

$$
\begin{aligned}
& (m+r-1)(m+n+1-r) \sum_{k=2}^{r}(r-k)(n+2-r-k) \\
& +\sum_{2 \leq j<k<r}(r-j)(n+2-r-j)(r-k)(n+2-r-k) \\
& \quad-4 c_{1}\left(m^{2}+n m\right)-4 c_{1} \sum_{j=1}^{r}(r-j)(n+2-r-j)+c_{2} \\
& \quad=0 .
\end{aligned}
$$

Therefore, we get

$$
\begin{gather*}
c_{1}=\frac{1}{4} \sum_{k=2}^{r-1}(r-k)(n+2-r-k),  \tag{6.9}\\
c_{2}=\sum_{j<k}(r-j)(n+2-r-j)(r-k)(n+2-r-k)  \tag{6.10}\\
+\left\{\sum_{j=1}^{r-1}(r-j)(n+2-r-j)\right\}^{2} .
\end{gather*}
$$

Substituting (6.9) and (6.10) to (6.4), we obtain the formula (6.8).
The following corollary is now obvious.

Corollary 6.6. $V\left(m_{1}, \cdots, m_{r}\right)$ is contained in Ker $P$, if and only if $m_{2}=\cdots=m_{r}=0$.
Proof of Theorem 1.2. Let $V:=\oplus_{m=0}^{\infty} V(m, 0, \cdots, 0)$ and $\hat{V}:=\bigoplus_{m=0}^{\infty} V_{m}$ (direct sums). Then, we have $R: \tilde{V} \rightarrow V$ and $S: V \rightarrow \tilde{V}$. Here $S$ is the inversion map defined in (3.1). Moreover, we have $S R=I d$ on $\tilde{V}$ and $R S=I d$ on $V$ by Proposition 3.2 and Lemma 6.4.

By Collorary 6.6, $V$ is dense in $\operatorname{Ker} P$ in $C^{\infty}$-topology. Since the inversion map $S: C^{\infty}(M) \rightarrow C^{\infty}\left(\boldsymbol{P}^{n} \boldsymbol{C}\right)$ is continuous, we have $R S=I d$ on $\operatorname{Ker} P$. This completes the proof.

Remark 6.7. If $\phi \in \operatorname{Ker} P$, the inverse image of $\phi$ is given by $S \phi$, this is, $R(S \phi)$ $=\phi$.

Remark 6.8. The invariant differential operator $P$, which we constructed in Section 1 , is of least degree in all the invariant differential operators on $M$ that characterize the range of $R$. It follows from the fact that the principal symbol $(1 / 16) F_{2}(Z)$ of $P$ is of least degree in all the Ad- $K$-invariant polynomials on m except for the principal symbol of the Laplacian.

Institute of Mathematics<br>University of Tsukuba

## References

[1] I. M. Gelfand, S.G. Gindikin and M.I. Graev, Integral geometry in affine and projective spaces, J. Soviet Math., 18 (1982), 39-167.
[2] I. M. Gelfand and M.I. Graev, Complexes of straight lines in the space $C^{n}$, Funct. Anal. Appl., 2 (1968), 39-52.
[3] I. M. Gelfand, M. I. Graev and R. Rosu, The problem of integral gometry and intertwining operator for a pair of real Grassmannian manifolds, J. Operator Theory 12 (1984), 339-383.
[4] E.L. Grinberg, On images of Radon transforms, Duke Math. J., 52 (1985), 935-972.
[5] V. Guillemin and S. Sternberg, Some problems in integral prometry and some related problems in micro-local analysis, Amer. J, Math., 101 (1979), 915-955.
[6] S. Helgason, Groups and Geometric Analysis, Academic Press, New York, 1984.
[7] S. Helgason, Differential Geometry, Lie Goups, and Symmetric Spaces, Academic Press, New York, 1978.
[8] F. John, The ultrahyperbolic differential equation with four independent variables, Duke Math. J., 4 (1938), 300-322.
[9] T. Kakehi and C. Tsukamoto, Characterization of images of Radon transforms. (to appear)
[10] M. Takeuchi, Gendai No Kyukansu, (in Japanese), Iwanami shoten, Tokyo, 1974.

