

## Local smooth solutions of the relativistic Euler equation

By

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### 1. Introduction

The motion of a relativistic perfect fluid in the Minkowski space-time is governed by

$$(1.1) \quad \left\{ \begin{array}{l} \frac{\partial}{\partial t} \left( \frac{\rho c^2 + p}{c^2 - v^2} - \frac{p}{c^2} \right) + \sum_{k=1}^3 \frac{\partial}{\partial x_k} \left( \frac{\rho c^2 + p}{c^2 - v^2} v_k \right) = 0, \\ \frac{\partial}{\partial t} \left( \frac{\rho c^2 + p}{c^2 - v^2} v_i \right) + \sum_{k=1}^3 \frac{\partial}{\partial x_k} \left( \frac{\rho c^2 + p}{c^2 - v^2} v_i v_k + p \delta_{ik} \right) = 0, \quad i = 1, 2, 3. \end{array} \right.$$

Here  $c$  denotes the speed of light,  $p$  the pressure,  $(v_1, v_2, v_3)$  the velocity of the fluid particle,  $\rho$  the mass-energy density of the fluid (as measured in units of mass in a reference frame moving with the fluid particle) and  $v^2 = v_1^2 + v_2^2 + v_3^2$ .

We assume the equation of state of the form

$$(1.2) \quad p = a^2 \rho,$$

where  $a$ , the sound speed, is taken to be constant so that  $0 < a < c$ . In particular,  $a = c/\sqrt{3}$  arises in several important physical contexts. For detailed discussions of this setting, see J. Smoller and B. Temple [6].

Under the assumption (1.2), we can write the equation (1.1) as

$$(1.3) \quad \left\{ \begin{array}{l} \frac{\partial w_0}{\partial t} + \sum_{k=1}^3 \frac{\partial w_k}{\partial x_k} = 0, \\ \frac{\partial w_i}{\partial t} + \sum_{k=1}^3 \frac{\partial f_i^k}{\partial x_k} = 0, \quad i = 1, 2, 3, \end{array} \right.$$

where

$$(1.4) \quad \begin{aligned} w_0 &= \frac{c^4 + a^2 v^2}{c^2(c^2 - v^2)} \rho, \quad w_i = \frac{c^2 + a^2}{c^2 - v^2} \rho v_i, \\ f_i^k &= w_i v_k + a^2 \rho \delta_{ik}, \quad i, k = 1, 2, 3. \end{aligned}$$

We shall solve the equation (1.3) for  $t \geq 0$  and  $x = (x_1, x_2, x_3) \in \mathbf{R}^3$  together with the initial conditions

$$(1.5) \quad \begin{cases} \rho|_{t=0} = \rho_0(x), \\ v_i|_{t=0} = v_{0i}(x), \quad i = 1, 2, 3. \end{cases}$$

For the one-dimensional motions, Smoller and Temple [6] constructed global weak solutions, using Glimm's method [1]. However, no results have been known so far about the full-dimensional existence. Thus the aim of the present paper is to establish the existence of local smooth solutions of (1.3) and (1.5).

We note that in the limit  $c \rightarrow \infty$ , the system (1.3) reduces formally to the non-relativistic Euler equation

$$(1.6) \quad \begin{cases} \frac{\partial \rho}{\partial t} + \sum_{k=1}^3 \frac{\partial}{\partial x_k} (\rho v_k) = 0 \\ \frac{\partial}{\partial t} (\rho v_i) + \sum_{k=1}^3 \frac{\partial}{\partial x_k} (\rho v_i v_k + a^2 \rho \delta_{ik}) = 0, \quad i = 1, 2, 3. \end{cases}$$

It is well known that this system can be transformed to a symmetric hyperbolic system to which the Friedrichs-Lax-Kato existence theory of local smooth solutions is applicable, see, for example, Majda [4, §1.3]. Actually, several symmetrizers are known to (1.6), ([1], [2], [4], [5]), which lead to the local existence theorems in different function spaces.

In this paper, we will show that a symmetrizer exists also for the relativistic case (1.3) which results in the

**Theorem 1.1.** *Suppose that the initial data  $\rho_0$  and  $(v_{01}, v_{02}, v_{03})$  belong to the uniformly local Sobolev space  $H_{ul}^s = H_{ul}^s(\mathbf{R}^3)$ ,  $s \geq 3$ , and that there exist a positive constant  $\delta (< 1)$  such that*

$$(1.7) \quad \delta \leq \rho, \quad v_0^2 = v_{01}^2 + v_{02}^2 + v_{03}^2 \leq (1 - \delta) c^2.$$

*Then, the system (1.3) has a unique solution*

$$(1.8) \quad (\rho, v_1, v_2, v_3) \in C([0, T]; H_{loc}^s) \cap C^1([0, T]; H_{loc}^{s-1}),$$

*with  $\rho > 0$  and  $v^2 < c^2$ . Here  $T > 0$  depends only on  $\delta$  and the  $H_{ul}^s$ -norm of the initial data.*

To construct symmetrizers, insteccion is enough for the non-relativistic case (1.6), but it does not seem to work well for the present case (1.3). In-

stead, we shall follow the idea due to Godunov [1] which relies on the existence of a convex entropy function. Such an entropy function will be constructed in §3 and the symmetrization for (1.3) using this entropy function will be shown in §2. In §4, the convergence is established of solutions of the relativistic (1.3) to those of the non-relativistic (1.6) as the light speed  $c$  tends to infinity.

## 2. Symmetrization

Theorem 1.1 can be concluded if there is a change of variables

$$(2.1) \quad z = (\rho, v_1, v_2, v_3) \rightarrow (u_0, u_1, u_2, u_3) ,$$

which reduces the system (1.3) to a system of the form

$$(2.2) \quad A^0(u) \frac{\partial u}{\partial t} + \sum_{k=1}^3 A^k(u) \frac{\partial u}{\partial x_k} = 0 ,$$

whose coefficient matrices  $A^0(u)$  and  $A^k(u)$ ,  $k=1,2,3$  satisfy the condition

$$(2.3) \quad \begin{aligned} (i) & \quad \text{they are all real symmetric and smooth } u , \\ (ii) & \quad A^0(u) \text{ is positive definite} . \end{aligned}$$

The system (2.2) satisfying (2.3) is called a symmetric hyperbolic system.

We claim that one of such changes of variables is given by

$$(2.4) \quad \begin{cases} u_0 = -\frac{c^3}{(c^2 - v^2)^{1/2}} \rho^{-\theta} + c^2 + a^2 , \\ u_j = \frac{c}{(c^2 - v^2)^{1/2}} \rho^{-\theta} v_j , \quad j=1,2,3 , \end{cases}$$

where

$$(2.5) \quad \theta = \frac{a^2}{c^2 + a^2} .$$

We shall check the condition (2.3). First, note that the map (2.1) with (2.4) is a diffeomorphism from  $\Omega_z = \{\rho > 0, v^2 < c^2\}$  onto  $\Omega_u = \{u_0 < c^2 + a^2, u^2 = (u_1)^2 + (u_2)^2 + (u_3)^2 < (u_0 - c^2 - a^2)^2 / c^2\}$ . By a straight but tedious computation, we can find the coefficients  $A^0(u) = (A^0_{\alpha\beta})_{\alpha,\beta=0,1,2,3}$ ,  $A^k(u) = (A^k_{\alpha\beta})_{\alpha\beta=0,1,2,3}$ ,  $k=1,2,3$ , as follows:

$$(2.6) \quad \begin{cases} A^0_{00} = A_1 \rho^{\theta+1}, & A^0_{0i} = A^0_{i0} = A_2 \rho^{\theta+1} v_i , \\ A^0_{ij} = A_3 \rho^{\theta+1} v_i v_j + A_4 \rho^{\theta+1} \delta_{ij}, & i, j = 1, 2, 3 , \end{cases}$$

$$(2.7) \quad \begin{cases} A_{00}^k = A_2 \rho^{\theta+1} , \\ A_{0i}^k = A_0^k = A_3 \rho^{\theta+1} v_i v_k + A_4 \rho^{\theta+1} \delta_{ik} , \\ A_{ij}^k = A_3 \rho^{\theta+1} v_i v_j v_k + A_4 \rho^{\theta+1} (v_i \delta_{jk} + v_j \delta_{ik} + v_k \delta_{ij}) , \quad i, j = 1, 2, 3 , \end{cases}$$

where

$$(2.8) \quad \begin{cases} A_1 = \frac{c^4 + 3a^2 v^2}{c^3 \theta (c^2 - v^2)^{3/2}} , \quad A_2 = \frac{c^4 + 2a^2 c^2 + a^2 v^2}{c^3 \theta (c^2 - v^2)^{3/2}} , \\ A_3 = \frac{c^2 + 3a^2}{c \theta (c^2 - v^2)^{3/2}} , \quad A_4 = \frac{c^2 - a^2}{c (c^2 - v^2)^{1/2}} . \end{cases}$$

These coefficients can be calculated by the chain rule and the formula

$$(2.9) \quad \begin{cases} \frac{\partial \rho}{\partial u_0} = \frac{A_4}{a^2} \rho^{\theta+1} , \quad \frac{\partial \rho}{\partial u_j} = \frac{A_4}{a^2} \rho^{\theta+1} v_j , \\ \frac{\partial v_i}{\partial u_0} = A_5 \rho^\theta v_i , \quad \frac{\partial v_i}{\partial u_j} = c^2 A_5 \rho^\theta \delta_{ij} , \quad i, j = 1, 2, 3 , \end{cases}$$

with

$$(2.10) \quad A_5 = c^{-3} (c^2 - v^2)^{1/2} .$$

Clearly, (2.6) and (2.7) show that the matrices  $A^0(u)$  and  $A^0(u)$  are real symmetric and smooth in  $\Omega_u$ . Let us show that  $A^0(u)$  is positive definite. Let  $\mathcal{E} = (\xi_0, \xi) \in \mathbf{R}^4$  be a 4-vector with  $\xi \in \mathbf{R}^3$  and  $\|\mathcal{E}\| = \sqrt{\xi_0^2 + \xi^2}$ . We should calculate the inner product

$$(2.11) \quad (A^0(u) \mathcal{E} | \mathcal{E}) = \rho^{\theta+1} J$$

where

$$(2.12) \quad J = A_1 \xi_0^2 + 2A_2 \xi_0 (v | \xi) + A_3 (v | \xi)^2 + A_4 \xi^2 ,$$

$A_j$  being those in (2.8). It is sufficient to show that

$$(2.13) \quad J \geq \kappa \|\mathcal{E}\|^2 ,$$

with some positive constant  $\kappa$ . First, we write

$$J = A_1 \left( \xi_0 + \frac{A_2}{A_1} (v | \xi) \right)^2 - \frac{1}{A_1} (A_2^2 - A_1 A_3) (v | \xi)^2 + A_4 \xi^2 .$$

Since

$$A_6 \equiv \frac{1}{A_1} (A_2^2 - A_1 A_3) = \frac{(c^2 + a^2) (c^4 + 4a^2 c^2 - a^2 v^2)}{c (c^2 - v^2)^{1/2} (c^4 + 3a^2 v^2)} > 0$$

and by Schwarz' inequality  $(v | \xi) \leq v^2 \xi^2$ , we get

$$(2.14) \quad J \geq \kappa_1 \xi^2 ,$$

with

$$\kappa_1 = A^4 - A_6 v^2 = \frac{(c^2 - v^2)^{1/2} (c^4 - a^2 v^2)}{c^3 \theta (c^4 + 3a^2 v^2)} > 0 .$$

On the other hand, decomposition  $\xi^2 = |\xi - (\tilde{v}|\xi)\tilde{v}|^2 + (\tilde{v}|\xi)^2$  where  $\tilde{v} = v/|v| \in S^2$  gives

$$\begin{aligned} J &= A_1 \xi_0^2 + 2A_2 \xi_0 (\tilde{v}|\xi) + \left( A_3 + \frac{A_4}{v^2} \right) (\tilde{v}|\xi)^2 + A_4 |\xi - (\tilde{v}|\xi)\tilde{v}|^2 \\ &\geq (A_3 v^2 + A_4) \left( (\tilde{v}|\xi) + \frac{A_2 |v| \xi_0}{A_3 v^2 + A_4} \right)^2 + \left( A_1 - \frac{A_2^2 v^2}{A_3 v^2 + A_4} \right) \xi_0^2 \\ &\geq \kappa_2 \xi_0^2 , \end{aligned}$$

where

$$\kappa_2 = A_1 - \frac{A_2^2 v^2}{A_3 v^2 + A_4} = \frac{(c^2 + a^2) (c^2 - v^2)^{1/2} (c^4 - a^2 v^2)}{c^5 (c^2 a^2 + (c^2 + 2a^2) v^2)} > 0 .$$

This and (2.14) now given

$$J \geq \frac{1}{2} (\kappa_1 \xi^2 + \kappa_2 \xi_0^2) .$$

This shows that (2.3) (ii) is also satisfied, and hence, the Friedrichs-Kato-Lax theory works for the system (2.2). Since the map (2.1) with (2.4) defines a diffeomorphism, we then conclude Theorem 1.1. We can say more, however. Given  $\delta \in (0,1)$  and  $c > 0$ , put

$$(2.15) \quad \Omega(\delta, c) = \{ \delta \leq \rho \leq \delta^{-1}, v^2 \leq (1 - \delta) c^2 \} .$$

It is seen that, for any  $\delta \in (0,1)$  and  $c_0 > 0$ ,  $\kappa_1$  and  $\kappa_2$  are bounded and bounded away from 0 uniformly for  $c \geq c_0$  as well as for  $z = (\rho, v_1, v_2, v_3) \in \Omega(\delta, c_0)$ . Also,  $A^\alpha(u)$  and any of their derivatives are uniformly bounded both for  $c \geq c_0$  and  $z \in \Omega(\delta, c_0)$ . Hence, we have a strengthened version of Theorem 1.1.

**Theorem 2.1.** *For any numbers  $a_0, c_0 > 0$  and  $\delta_0 \in (0,1)$ , there exist positive constants  $C$  and  $T$  such that for each initial data  $z_0 = (\rho_0, v_{01}, v_{02}, v_{03}) \in H^s$  satisfying*

$$\|z_0\|_{H_{\delta_0}^s} \leq a_0, \quad z_0 \in \Omega(\delta_0, c_0) \text{ for all } x \in \mathbf{R}^3 ,$$

and for each  $c \geq c_0$ , the Cauchy problem (1.3) with (1.5) possesses a unique solution  $z = (\rho, v_1, v_2, v_3)$  belonging to the class (1.8) and satisfying

$$(2.16) \quad \|z(t)\|_{H_{\delta_0}^s} \leq C, \quad z(t) \in \Omega(\delta_0/2, c_0) \text{ for all } x \in \mathbf{R}^3 ,$$

for all  $t \in [0, T]$ .

### 3. Strictly convex entropy function

Let us consider the system of conservation laws

$$(3.1) \quad w_t + \sum_k^N (f^k(w))_{x_k} = 0, \quad w = (w_1, w_2, \dots, w_m) .$$

A scalar function  $\eta = \eta(w)$  is called an entropy function to (3.1) if there exist scalar functions,  $q^k(w)$ ,  $k=1,2,\dots, N$ , satisfying

$$(3.2) \quad D_w \eta(w) D_w f^k(w) = D_w q^k .$$

Here and in the sequel,  $D_w h$  is taken as a row vector in case  $h$  is a scalar function and is the Jacobi matrix case  $h$  is a vector valued function.

According to Godunov [1], (see also Kawashima-Shizuta [3]), if a strictly convex entropy function exists, then the transformation

$$(3.3) \quad w \rightarrow u = D_w \eta(w) ,$$

is well-defined and reduces the system (3.1) to a symmetric hyperbolic system of the form (2.2) whose coefficients

$$(3.4) \quad \begin{cases} A^0(u) = D_u w = (D_w^2 \eta)^{-1} , \\ A^k(u) = D_w f^k = D_w f^k D_u w , \end{cases}$$

satisfy the condition (2.3).

In our case, (1.3) is of the form (3.1) with

$$(3.5) \quad w = (w_0, w_1, w_2, w_3), \quad f^k(w) = (w_k f_1^k, f_2^k, f_3^k) ,$$

where  $w_0, w_k, f_i^k$ , ( $i, k=1,2,3$ ) are those in (1.4). Recall  $z = (\rho, v_1, v_2, v_3)$ . The map  $z \rightarrow w$  is a diffeomorphism from  $\Omega_z = \{\rho > 0, v^2 < c^2\}$  onto  $\Omega_w = \{w_0 > 0, (w_1, w_2, w_3) \in \mathbf{R}^3\}$ . Specifically, using the formula,

$$(3.6) \quad \begin{cases} \frac{\partial \rho}{\partial w_0} = M_1 , & \frac{\partial \rho}{\partial w_j} = M_2 v_j , \\ \frac{\partial v_i}{\partial w_0} = M_3 \rho^{-1} v_i , & \frac{\partial v_i}{\partial w_j} = M_4 \rho^{-1} v_i v_j + M_5 \rho^{-1} \delta_{ij} , \end{cases}$$

where

$$(3.7) \quad \begin{cases} M_1 = \frac{c^2(c^2 + v^2)}{c^4 - a^2 v^2} , & M_2 = -\frac{2c^2}{c^4 - a^2 v^2} , & M_3 = -\frac{c^2(c^2 - v^2)}{c^4 - a^2 v^2} , \\ M_4 = \frac{2\theta(c^2 - v^2)}{c^4 - s^2 v^2} , & M_5 = \frac{(c^2 - v^2)}{c^2 + a^2} , \end{cases}$$

we see that the Jacobi matrix  $D_w z$  is nonsingular with

$$(3.8) \quad \det(D_{wz}) = \frac{1}{\rho^3} \frac{c^2(c^2-v^2)^4}{(c^2+a^2)^3(c^4-a^2v^2)} > 0 .$$

Rewrite (3.2) as

$$(3.9) \quad D_z \eta B^k = D_z q^k, \quad k=1,2,3 ,$$

where

$$(3.10) \quad B^k = D_{wz} D_z f^k = (b_{\alpha\beta}^k)_{\alpha'\beta=0,1,2,3} ,$$

are computed using (3.5) and (3.6) as

$$(3.11) \quad \begin{cases} b_{00}^k = B_1 v_k, \quad b_{0j}^k = B_2 \rho \delta_{kj} , \\ b_{i0}^k = B_3 \rho^{-1} v_k v_i + B_4 \rho^{-1} \delta_{ki} , \\ b_{ij}^k = B_5 v_i \delta_{kj} + v_k \delta_{ij} , \end{cases}$$

with

$$(3.12) \quad \begin{cases} B_1 = \frac{c^2(c^2-a^2)}{c^4-a^2v^2} , \quad B_2 = \frac{c^2(c^2+a^2)}{c^4-a^2v^2} , \\ B_3 = -\frac{a^2(c^2-a^2)(c^2-v^2)}{(c^2+a^2)(c^4-a^2v^2)} , \\ B_j = \frac{a^2(c^2-v^2)}{c^2+a^2} , \quad B_k = -\frac{a^2(c^2-v^2)}{c^4-a^2v^2} . \end{cases}$$

We shall solve (3.9) assuming that our entropy pair  $(\eta, q^k)$  is of the form

$$(3.13) \quad \eta = H(\rho, v^2), \quad q^k = Q(\rho, v^2) v_k .$$

Then, setting  $y = v^2$ , the condition (3.9) reduces to the following set of equations for the functions  $H$  and  $Q$ .

$$(3.14) \quad H_y = Q_y ,$$

$$(3.15) \quad B_1 H_\rho + 2(B_3 y + B_4) \frac{1}{\rho} H_y = Q_\rho ,$$

$$(3.16) \quad B_2 \rho H_\rho + 2B_5 y H_y = Q .$$

From (3.14), there should exist a function  $G = G(\rho)$  of  $\rho$  only such that  $H = Q(\rho, y) + G(\rho)$ . On the other hand, eliminating  $\rho H_\rho$  from (3.15) and (3.16), and using (3.14), we have

$$(3.17) \quad (c^2+a^2) \rho Q_\rho - (c^2-a^2) Q = 2a^2(c^2-y) Q_y .$$

This and (3.15) then yield

$$(3.18) \quad \rho G_\rho = \frac{c^2-y}{c^2+a^2} \left( Q - \frac{c^2+a^2}{c^2} \rho Q_\rho \right) .$$

or putting  $q = (c^2 - y)Q$ ,

$$(3.19) \quad (1 - \theta)q - \rho q_\rho = c^2 \rho G_\rho .$$

Since the right hand side is a function of  $\rho$  only,  $q$  must be of the form

$$(3.20) \quad q = \rho^{1-\theta} [g(\rho) + h(y)] ,$$

where  $g$  and  $h$  are arbitrary functions. Substituting (3.20) into (3.17) or

$$(3.21) \quad \rho q_\rho - q = 2\theta(c^2 - y)q_y ,$$

we get, with a constant  $K_0$ ,

$$(3.22) \quad \rho g'(\rho) - \theta g(\rho) = \theta \{2(c^2 - y)h'(y) + h(y)\} = -\theta K_0 ,$$

whose solutions are

$$(3.23) \quad g(\rho) = K_2 \rho^\theta + K_0, \quad h(y) = K_1 (c^2 - y)^{1/2} - K_0 ,$$

$K_j$ 's being arbitray constants. Now, substitution of (3.23) into (3.20) and then into (3.19) yields

$$(3.24) \quad G = -\frac{K_2 \theta}{c^2} \rho + K_3 .$$

Thus we get

$$(3.25) \quad \eta = H = \frac{K_1}{(c^2 - v^2)^{1/2}} \rho^{1-\theta} + K^2 \left( \frac{1}{c^2 - v^2} - \frac{\theta}{c^2} \right) \rho + K_3 ,$$

$$(3.26) \quad Q = \frac{K_1}{(c^2 - v^2)^{1/2}} \rho^{1-\theta} + \frac{K^2}{c^2 - v^2} \rho .$$

For the later purpose, we wish to choose the constants  $K_j$ ,  $j = 1, 2, 3$ , so that (3.25) converges, as  $c \rightarrow \infty$ , to the entropy function for the non-relativistic case (1.6) given by

$$(3.27) \quad \bar{\eta} = \frac{1}{2} \rho v^2 + a^2 \rho \log \rho ,$$

which can be obtained exactly in the same way. The right choice is then found to be

$$(3.28) \quad K_1 = -c(c^2 + a^2), \quad K_2 = c^4 - a^4, \quad K_3 = 0 ,$$

with which (3.25) becomes

$$(3.29) \quad \eta = -\frac{c(c^2 + a^2)}{(c^2 - v^2)^{1/2}} \rho^{1-\theta} + \frac{(c^2 + a^2)(c^4 + a^2 v^2)}{c^2(c^2 - v^2)} \rho .$$

The change of variables (2.4) was derived from this  $\eta$  via (3.3), using (3.6). This  $\eta$  is strictly convex due to (3.4) since  $A^0(u)$  is positive definite

as was seen in the previous section.

#### 4. Non relativistic limit

Now for the non-relativistic case (1.6), the symmetrizing variables associated with the entropy function (3.27) are

$$(4.1) \quad \begin{cases} \bar{u}_0 = -\frac{1}{2}v^2 + a^2 \log \rho + a^2, \\ \bar{u}_j = v_j, \end{cases} \quad j=1,2,3,$$

and the resulting system is

$$(4.2) \quad \bar{A}^0(\bar{u})\bar{u}_t + \sum_{k=1}^3 \bar{A}^k(\bar{u})\bar{u}_{xk} = 0,$$

with

$$(4.3) \quad \begin{cases} \bar{A}_{00}^0 = a^{-2}\rho, \bar{A}_{0j}^0 = \bar{A}_{j0}^0 = a^{-2}\rho v_j, \\ \bar{A}_{ij}^0 = a^{-2}\rho v_i v_j + \rho \delta_{ij}, \end{cases}$$

and so on. The condition (2.3) can be easily checked to hold, so that the Friedrichs-Kato-Lax theory applies also to the system (4.2) and, as a consequence, to the non-relativistic Euler equation (1.6).

Let  $z = (\rho, v_1, v_2, v_3)$  and  $\bar{z} = (\bar{\rho}, \bar{v}_1, \bar{v}_2, \bar{v}_3)$  be the solutions to (1.3) and (1.6), respectively, both for the same initial data  $z_0 = (\rho_0, v_{01}, v_{02}, v_{03})$ . Let  $z_0$  be as in Theorem 2.1. Then, we may conclude that  $\bar{z}$  exists on the same time interval  $[0, T]$  as  $z$ ,  $c > c_0$ , belongs to the same class (1.8) and enjoys the same estimate (2.16). We shall show the

**Theorem 4.1.** *As  $c \rightarrow \infty$ ,  $z$  converges to  $\bar{z}$  uniformly on  $[0, T]$  in  $H_{loc}^{s-\varepsilon}$  for any  $\varepsilon > 0$ .*

*Proof.* It suffices to prove the theorem for the solutions  $u$  to (2.2) and  $\bar{u}$  to (4.2). Put  $\phi = u - \bar{u}$ . Subtracting (4.2) from (2.2), we have

$$(4.4) \quad A^0(u)\phi_t + \sum_{k=1}^3 A^k(u)\phi_{xk} = -\{A^0(u) - \bar{A}^0(\bar{u})\}\bar{u}_t - \sum_{k=1}^3 \{A^k(u) - \bar{A}^k(\bar{u})\}\bar{u}_{xk}.$$

First, we know from the remark made above that the uniform estimates

$$(4.5) \quad \begin{cases} \|u(t)\|_{H_{\bar{u}}^s}, \|\bar{u}(t)\|_{H_{\bar{u}}^s}, \|\bar{u}(t)\|_{H_{\bar{u}}^{s-1}} \leq C_0, \\ A^0(u(t))\mathcal{E}|\mathcal{E}, (\bar{A}^0(\bar{u}(t)))\mathcal{E}|\mathcal{E} \geq \kappa_0\|\mathcal{E}\|, \\ z(t), \bar{z}(t) \in \mathcal{Q}(\delta_0/2, c_0) \text{ for all } x \in \mathbf{R}^3, \end{cases}$$

hold for all  $c \geq c_0$  and for all  $t \in [0, T]$ , with some constants  $C_0, \kappa_0 > 0$ . On the

other hand, it is easily seen that the maps  $u = u(z)$  defined by (2.4) and  $\bar{u} = \bar{u}(z)$  by (4.1) satisfy

$$(4.6) \quad u(z) = \bar{u}(z) + O(c^{-2}) ,$$

whereas

$$(4.7) \quad A^\alpha(u(z)) = \bar{A}^\alpha(\bar{u}(z)) + O(c^{-2}), \alpha=0,1,2,3 ,$$

and similarly for their derivatives, as  $c \rightarrow \infty$ , where the remainders  $O(c^{-2})$  are all uniform for  $z \in \mathcal{Q}(\delta_0/2, c_0)$ . Owing to (2.16), (4.5), (4.6) and (4.7), the  $L^2$  norm of the right hand side of (4.4) is majorized by  $C(\|\psi\|_{L^2} + c^{-2})$  with some positive constant  $C$ , uniformly for  $c \geq c_0$ , and, hence, (4.4) gives, by integration by parts and using Gronwall's inequality,

$$\|\psi(t)\|_{L^2} = O(c^{-2}) ,$$

which then yields, after interpolation with (4.5),

$$\|\psi(t)\|_{H^{s-\varepsilon}} = O(c^{-2\varepsilon}) ,$$

with any  $\varepsilon > 0$ . Thus we are done.

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