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INDICATOR FRACTIONAL STABLE MOTIONS

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Abstract

Using the framework of random walks in random scenery, Cohen and Samorodnitsky (2006) introduced a family of symmetric α -stable motions called local time fractional stable motions. When $\alpha = 2$, these processes are precisely fractional Brownian motions with 1/2 < H < 1. Motivated by random walks in alternating scenery, we find a complementary family of symmetric α -stable motions which we call indicator fractional stable motions. These processes are complementary to local time fractional stable motions in that when $\alpha = 2$, one gets fractional Brownian motions with 0 < H < 1/2.

1 Introduction

There are a plethora of integral representations for Fractional Brownian motion (FBM) with Hurst parameter $H \in (0, 1)$, and not surprisingly there are several generalizations of these integral representations to stable processes. These generalizations are often called fractional symmetric α -stable (S α S) motions, with $0 < \alpha < 2$, and they can be considered analogs of FBM. Two common fractional S α S motions include linear fractional stable motion (L-FSM) and real harmonizable fractional stable motion (RH-FSM).

In [CS06], a new generalization of FBM, H > 1/2, called *local time fractional stable motion* (LT-FSM) was introduced. LT-FSM is particularly interesting because it is a subordinated process (this terminology is taken from Section 7.9 of [ST94] and should not be confused with subordination in the sense of time-changes). Subordinated processes are processes constructed from integral representations with random kernels, or said another way, where the stable random measure (of the integral representation) has a control measure related in some way to a probability measure of some other stochastic process (see Section 2 below). We note that subordinated processes are examples of what are known in the literature as doubly stochastic models.

1

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In this work we introduce another subordinated process which can be considered a natural extension of LT-FSM to H < 1/2. The processes we consider have random kernels of a very simple type, namely the indicator function

$$1_{[A_0,A_t]}(x) \quad ([A_s,A_t] := [A_t,A_s] \text{ if } A_t < A_s) \tag{1}$$

with respect to some self-similar stationary increment (SSSI) process A_t . As such we call these processes *indicator fractional stable motions* (I-FSM).

I-FSM's relation to LT-FSM comes from the idea that the indicator function of a real-valued process A_t can be thought of as an alternating version of the local time of A_t in the following way. Suppose S_n , with $S_0 = 0$, is a discrete-time simple random walk on \mathbb{Z} . If e is the edge between k and k + 1, then the discrete local time of S_n at e is the total number of times S_n has gone from either k to k+1 or from k+1 to k, up to time n. Now, instead of *totaling* the number of times S_n crosses over edge e, one can consider the *parity* of the number of times S_n crosses e up to time n. The parity of the discrete local time at edge e up to time n is odd if and only if e is between 0 and S_n . Thus, heuristically, the edges which contribute to an "alternating local time" are those edges which lie between 0 and A_t . This heuristic is discussed more rigorously in [JM11].

We can generalize the motivational discrete model to all random walks on \mathbb{Z} . In this case, when S_n goes from x to y on a given step, it "crosses" all edges in between. In terms of the discrete local time, we heuristically think of the random walk as having spent a unit time at *all* edges between x and y during that time-step.

The first question one must ask is: are these new stable processes a legitimate new class of processes or are they just a different representation of L-FSMs and/or RH-FSMs? Using characterizations of the generating flows for the respective processes (see Section 3 below), [CS06] showed that the class of LT-FSMs is disjoint from the classes of RH-FSMs and L-FSMs. Following their lead, we use the same characterizations to show that when the (discretized) subordinating process $\{A_n\}_{n\in\mathbb{N}}$ is recurrent, the class of I-FSMs is also disjoint from the two classes, RH-FSMs and L-FSMs. Since I-FSMs and LT-FSMs have disjoint self-similarity exponents when $1 < \alpha < 2$, these two classes of processes are also disjoint when $1 < \alpha < 2$. For $\alpha < 1$, the class of I-FSMs has a strictly larger self-similarity range than the class of LT-FSMs.

The outline of the rest of the paper is as follows. In the next section we define I-FSMs and show that they are $S\alpha$ S-SSSI processes. In Section 3 we give the necessary background concerning generating flows and characterizations with respect to them. In Section 4, we give the classification of I-FSMs according to their generating flows along with a result on the mixing properties of the stable noise associated with an I-FSM.

2 Indicator fractional stable motions

Let *m* be a σ -finite measure on a measurable space (*B*, \mathscr{B}), and let

$$\mathscr{B}_0 = \{A \in \mathscr{B} : m(A) < \infty\}.$$

Definition 2.1. A S α S random measure *M* with control measure *m* is a σ -additive set function on \mathscr{B}_0 such that for all $A_i \in \mathscr{B}_0$

- 1. $M(A_1) \sim S_{\alpha}(m(A_1)^{1/\alpha})$
- 2. $M(A_1)$ and $M(A_2)$ are independent whenever $A_1 \cap A_2 = \emptyset$

where $S_{\alpha}(\sigma)$ is a S α S random variable with scale parameter σ (see Section 3.3 of [ST94] for more details).

Another way to say the second property above is to say that *M* is *independently scattered*. For context, let us first define LT-FSM. Throughout this paper

 $\lambda :=$ Lebesgue measure on \mathbb{R} .

Let $(\Omega', \mathscr{F}', \mathbf{P}')$ support a subordinating process A_t . A_t is either a FBM-H' or a S β S-Levy motion, $\beta \in (1, 2]$, with jointly continuous local time $L_A(t, x)(\omega')$. By self-similarity, $A_0 = 0$ almost surely. Suppose a S α S random measure M with control measure $\mathbf{P}' \times \lambda$ lives on some other probability space $(\Omega, \mathscr{F}, \mathbf{P})$. An LT-FSM is a process

$$X_A^H(t) := \int_{\Omega'} \int_{\mathbb{R}} L_A(t, x)(\omega') M(d\omega', dx), \ t \ge 0,$$
⁽²⁾

where $X_A^H(t)$ is a S α S-SSSI process with self-similarity exponent $H = 1 - H' + H'/\alpha$ and H' is the self-similarity exponent of A_t (see Theorem 3.1 in [CS06] and Theorem 1.3 in [DGP08]).

We now define I-FSM which is the main subject of this work. Let $(\Omega', \mathscr{F}', \mathbf{P}')$ support A_t , a nondegenerate S β S-SSSI process with $\beta \in (1, 2]$ and self-similarity exponent $H' \in (0, 1)$ (again by self-similarity $A_0 = 0$ almost surely). Suppose a S α S random measure M with control measure $\mathbf{P}' \times \lambda$ lives on some other probability space $(\Omega, \mathscr{F}, \mathbf{P})$.

An indicator fractional stable motion is a process

$$Y_A^H(t) := \int_{\Omega'} \int_{\mathbb{R}} \mathbb{1}_{[0,A_t(\omega')]}(x) M(d\omega',dx), \ t \ge 0.$$
(3)

A nice observation is that the finite dimensional distributions of the process do not change if we replace the kernel $1_{[0,A_t(\omega')]}(x)$ with $sign(A_t(\omega'))1_{[0,A_t(\omega')]}(x)$:

$$\sum_{j=1}^{n} \theta_{j} \int_{\Omega'} \int_{\mathbb{R}} \operatorname{sign}(A_{t_{j}}(\omega')) \mathbf{1}_{[0,A_{t_{j}}(\omega')]}(x) M(d\omega', dx)$$

$$= \sum_{j=1}^{n} \theta_{j} \int_{\Omega'} \int_{\mathbb{R}^{+}} \mathbf{1}_{\{\omega':A_{t_{j}}(\omega')>0\}} \mathbf{1}_{[0,A_{t_{j}}(\omega')]}(x) M(d\omega', dx)$$

$$+ \sum_{j=1}^{n} \theta_{j} \int_{\Omega'} \int_{\mathbb{R}^{-}} -\mathbf{1}_{\{\omega':A_{t_{j}}(\omega')<0\}} \mathbf{1}_{[0,A_{t_{j}}(\omega')]}(x) M(d\omega', dx)$$

$$\stackrel{d}{=} \sum_{j=1}^{n} \theta_{j} \int_{\Omega'} \int_{\mathbb{R}} \mathbf{1}_{[0,A_{t_{j}}(\omega')]}(x) M(d\omega', dx). \tag{4}$$

where the last line holds since M is both symmetric and independently scattered. The reason that this is helpful is because the equality

$$\operatorname{sign}(A_t) \mathbf{1}_{[0,A_t]}(x) = (A_t - x)^0_+ - (-x)^0_+$$
(5)

makes it intuitively clear that the increments of $Y_A^H(t)$ are stationary.

We note that both LT-FSM and I-FSM can technically be extended to the case where A_t has selfsimilarity exponent H' = 1. In these degenerate cases, the kernels for LT-FSM and I-FSM coincide becoming the non-random family of functions $\{1_{[0,t]}\}_{t\geq 0}$ thereby giving us

$$\int_{\mathbb{R}} \mathbf{1}_{[0,t]} M(dx), \ t \ge 0.$$

These are the S α S Levy motions with $\alpha \in (0, 2)$.

Theorem 2.2. The process $Y_A^H(t)$ is a well-defined S α S-SSSI process with self-similarity exponent $H = H'/\alpha$.

Proof. We start by noting that

$$\int_{\Omega'} \int_{\mathbb{R}} |\mathbf{1}_{[0,A_t(\omega')]}(x)|^{\alpha} dx \, \mathbf{P}'(d\omega') = \mathbf{E}' \int_{\mathbb{R}} \mathbf{1}_{[0,A_t(\omega')]}(x) dx$$
$$= \mathbf{E}'|A_t| < \infty$$
(6)

where the finite expectation follows since A_t is a S β S process with $\beta > 1$. This shows that $Y_A^H(t)$ is a well-defined S α S process (see Section 3.2 of [ST94] for details).

Recall that the control measure for *M* is $\mathbf{P}' \times \lambda$. Using the alternative kernel given in (4), by Proposition 3.4.1 in [ST94] we have for $\theta_j \in \mathbb{R}$ and times $t_j, s_j \in \mathbb{R}^+$:

$$\operatorname{Eexp}\left(i\sum_{j=1}^{k}\theta_{j}(Y_{A}^{H}(t_{j})-Y_{A}^{H}(s_{j}))\right)$$

$$= \operatorname{exp}\left(-\int_{\mathbb{R}}\mathbf{E}'\left|\sum_{j=1}^{k}\theta_{j}\cdot\operatorname{sign}(A_{t_{j}}-A_{s_{j}})\mathbf{1}_{[A_{s_{j}},A_{t_{j}}]}(x)\right|^{\alpha}dx\right).$$
(7)

Note that if we had not used the alternative kernel given in (4), then the right-side above would have been more complicated. Using (7), we have

$$\mathbf{E} \exp\left(i\sum_{j=1}^{k} \theta_{j}(Y_{A}^{H}(t_{j}+h)-Y_{A}^{H}(h))\right)$$

$$= \exp\left(-\int_{\mathbb{R}} \mathbf{E}' \left|\sum_{j=1}^{k} \theta_{j} \cdot \operatorname{sign}(A_{t_{j}+h}-A_{h})\mathbf{1}_{[A_{h},A_{t_{j}+h}]}(x)\right|^{\alpha} dx\right)$$

$$= \exp\left(-\int_{\mathbb{R}} \mathbf{E}' \left|\sum_{j=1}^{k} \theta_{j} \cdot \operatorname{sign}(A_{t_{j}})\mathbf{1}_{[0,A_{t_{j}}]}(x)\right|^{\alpha} dx\right)$$

$$= \operatorname{E} \exp\left(i\sum_{j=1}^{k} \theta_{j}Y_{A}^{H}(t_{j})\right)$$
(8)

where the second equality follows since A_t has stationary increments. The above shows that $Y_A^H(t)$ has stationary increments.

Using (7) once more, the self-similarity of $\{A_t\}_{t\geq 0}$, and the change of variables $y = c^{-H'}x$, we obtain

$$\mathbf{E} \exp\left(i\sum_{j=1}^{k} \theta_{j} Y_{A}^{H}(ct_{j})\right) = \exp\left(-\int_{\mathbb{R}} \mathbf{E}' \left|\sum_{j=1}^{k} \theta_{j} \cdot \operatorname{sign}(A_{ct_{j}}) \mathbf{1}_{[0,A_{ct_{j}}]}\right|^{\alpha} dx\right)$$

$$= \exp\left(-c^{H'} \int_{\mathbb{R}} \mathbf{E}' \left|\sum_{j=1}^{k} \theta_{j} \cdot \operatorname{sign}(A_{t_{j}}) \mathbf{1}_{[0,A_{t_{j}}]}\right|^{\alpha} dy\right)$$

$$= \operatorname{E} \exp\left(i\sum_{j=1}^{k} \theta_{j} c^{H'/\alpha} Y_{A}^{H}(t_{j})\right)$$

$$(9)$$

Remarks.

- 1. For each fixed $0 < \alpha < 2$, I-FSM is a class of S α S-SSSI processes with self-similarity exponents *H* in the feasibility range $0 < H < 1/\alpha$. In particular, when $1 < \alpha < 2$, this range of feasible *H* complements that of LT-FSM which has the feasibility range $1/\alpha < H < 1$. When $0 < \alpha < 1$, the feasibility range $0 < H < 1/\alpha$ of I-FSM is strictly bigger than that of LT-FSM: $1 < H < 1/\alpha$.
- 2. It is not hard to see that I-FSMs are continuous in probability since the subordinating process A_t is SSSI and continuous in probability. However, it follows from Theorem 10.3.1 in [ST94] that I-FSMs are not sample continuous. This is intuitive since I-FSMs should have continuity properties similar to those of S α S Levy motions since the latter have the form

$$\int_{\mathbb{R}^{+}} \mathbf{1}_{[0,t]}(x) M(dx), \ t \ge 0$$
(10)

where *M* is a S α S random measure with Lebesgue control measure.

3. By Theorem 11.1.1 in [ST94] an I-FSM has a measurable version if and only if the subordinating process A_t has a measurable version.

3 Background: Ergodic properties of flows

Throughout this section we suppose that $0 < \alpha < 2$. The general integral representations of α -stable processes, of the type

$$X(t) = \int_{E} f_{t}(x) M(dx), \ t \in T$$
(11)

 $(T = \mathbb{Z} \text{ or } \mathbb{R})$ are well-known (see the introduction of [Sam05]). Here *M* is a S α S random measure on *E* with a σ -finite control measure *m*, and $f_t \in L^{\alpha}(E, m)$ for each *t*. We call $\{f_t(x)\}_{t \in T}$ a spectral representation of $\{X(t)\}$.

Definition 3.1. A measurable family of functions $\{\phi_t\}_{t\in T}$ mapping *E* onto itself and such that

- 1. $\phi_{t+s}(x) = \phi_t(\phi_s(x))$ for all $t, s \in T$ and $x \in E$,
- 2. $\phi_0(x) = x$ for all $x \in E$
- 3. $m \circ \phi_t^{-1} \sim m$ for all $t \in T$

is called a nonsingular flow. A measurable family $\{a_t\}_{t\in T}$ is called a cocycle for the flow $\{\phi_t\}_{t\in T}$ if for every $s, t \in T$ we have

$$a_{t+s}(x) = a_s(x)a_t(\phi_s(x)) \text{ m-a.e.}.$$
 (12)

In [Ros95] it was shown that in the case of measurable stationary S α S processes one can choose the (spectral) representation in (11) to be of the form

$$f_t(x) = a_t(x) \left(\frac{dm \circ \phi_t}{dm}(x)\right)^{1/\alpha} f_0 \circ \phi_t(x)$$
(13)

where $f_0 \in L^{\alpha}(E, m)$, $\{\phi_t\}_{t \in T}$ is a nonsingular flow, and $\{a_t\}_{t \in T}$ is a cocycle, for $\{\phi_t\}_{t \in T}$, which takes values in $\{-1, 1\}$. Also, note that one may always assume the following full support condition:

$$\sup\{f_t : t \in T\} = E. \tag{14}$$

Henceforth we shall assume that $T = \mathbb{Z}$ and will write f_n , ϕ_n , and X(n). Note that in the discrete case we may always assume measurability of the process (see Section 1.6 of [Aar97]). Given a representation of the form (13), we say that X(n) is generated by ϕ_n .

In [Ros95] and [Sam05], the ergodic-theoretic properties of a generating flow ϕ_n are related to the probabilistic properties of the S α S process X(n). In particular, certain ergodic-theoretic properties of the flow are found to be invariant from representation to representation.

In Theorem 4.1 of [Ros95] it was shown that the *Hopf decomposition* of a flow is a representationinvariant property of stationary S α S processes. Specifically, one has the disjoint union $E = C \cup D$ where the *dissipative* portion *D* is the union of all wandering sets and the *conservative* portion *C* contains no wandering subset. A *wandering* set is one such that $\{\phi_n(B)\}_{n \in \mathbb{Z}}$ are disjoint modulo sets of measure zero. Since *C* and *D* are $\{\phi_n\}$ -invariant, one can decompose a flow by looking at its restrictions to *C* and *D*, and the decomposition is unique modulo sets of measure zero. A nonsingular flow $\{\phi_n\}$ is said to conservative if m(D) = 0 and dissipative if m(C) = 0.

The following result appeared as Corollary 4.2 in [Ros95] and has been adapted to the current context:

Theorem 3.2 (Rosinski). Suppose $0 < \alpha < 2$. A stationary S α S process is generated by a conservative (dissipative, respectively) flow if and only if for some (all) measurable spectral representation $\{f_n\}_{n \in \mathbb{R}^+} \subset L^{\alpha}(E, m)$ satisfying (14), the sum

$$\sum_{n\in\mathbb{Z}} |f_n(x)|^{\alpha} \tag{15}$$

is infinite (finite) m-a.e. on E.

In [Sam05], another representation-invariant property of flows, the *positive-null* decomposition of stationary S α S processes, was introduced.

A subset $B \subset E$ is called *weakly wandering* if there is a subsequence with $n_0 = 0$ such that the sets $\{\phi_{n_k}B\}_{k\in\mathbb{N}}$ are disjoint modulo sets of measure zero. The null part *N* of *E* is the union of all weakly

wandering sets, and the positive part *P* contains no weakly wandering set. Note that the positive part of *E* is a subset of the conservative part, i.e. $P \subset C$. Again, one can decompose $\{\phi_n\}$ by restricting to *P* and *N*. This decomposition is unique modulo sets of measure zero, and Theorem 2.1 of [Sam05] states that the decomposition is representation-invariant modulo sets of measure zero. A null flow is one with m(P) = 0 and a positive flow has m(N) = 0. Note that dissipative flows are automatically null flows, however in the case of conservative flows, both positive and null flows are possible.

4 Ergodic properties of indicator fractional stable noise

Properties of a S α S-SSSI process Y(t) are often deduced from its increment process $Z(n) = Y(n) - Y(n-1), n \in \mathbb{N}$ called a *stable noise*. In this section, we study the ergodic-theoretic properties (which were introduced in the previous section) of *indicator fractional stable noise* (I-FSN) which we define as

$$Z_{A}(n) := \int_{\Omega'} \int_{\mathbb{R}} \mathbb{1}_{[0,A_{n}(\omega')]}(x) - \mathbb{1}_{[0,A_{n-1}(\omega')]}(x) M(d\omega',dx), \ n \in \mathbb{N}.$$
(16)

We note that in light of the proof of Theorem 2.2, one may deem it natural to instead use the kernel

$$sign(A_n(\omega'))1_{[0,A_n(\omega')]}(x) - sign(A_{n-1}(\omega'))1_{[0,A_{n-1}(\omega')]}(x).$$

However, as seen in (4), the $sign(A_t)$ has no affect on the distribution of the process and therefore has no affect on the distribution of its increments.

It is known that stationary $S\alpha S$ processes generated by dissipative flows are mixing [SRMC93]. Concerning conservative flows, Theorem 3.1 of [Sam05] states that a stationary $S\alpha S$ process is ergodic if and only if it is generated by a null flow, and examples are known of both mixing and non-mixing stationary $S\alpha S$ processes generated by conservative null flows (see Section 4 of [GR93]). Our next goal is to show that I-FSN is mixing which implies that its flow is either dissipative or conservative null. We first need a result which appeared as Theorem 2.7 of [Gr094]:

Lemma 4.1 (A. Gross). Suppose X_n is some stationary S α S process, and assume $\{f_n\} \subset L^{\alpha}(E,m)$ is a spectral representation of X_n with respect to the control measure m. Then X_n is mixing if and only if for every compact $K \subset \mathbb{R} - \{0\}$ and every $\epsilon > 0$,

$$\lim_{n \to \infty} m\{x : f_0 \in K, |f_n| > \epsilon\} = 0.$$
(17)

Theorem 4.2. Indicator fractional stable noise is a mixing process.

Proof. Using the above lemma, it suffices to show that

$$\lim_{n \to \infty} (\mathbf{P}' \times \lambda) \{ (\omega', x) : x \in [0, A_1], x \in [A_n, A_{n+1}] \} = 0,$$
(18)

recalling that $[A_n, A_{n+1}] := [A_{n+1}, A_n]$ whenever $A_{n+1} < A_n$. Let c_i be constants such that for all M > 0, $\mathbf{P}'(A_1 > M) < c_1 M^{-\beta}$ and

$$\int_{M}^{\infty} \mathbf{P}'(A_1 > x) \, dx < c_2 M^{-\beta + 1} \tag{19}$$

where $\beta > 1$. Also, recall that 0 < H' < 1 is the self-similarity exponent of A_t . We have that

$$(\mathbf{P}' \times \lambda)\{(\omega', x) : x \in [0, A_1], x \in [A_n, A_{n+1}]\}$$

$$= (\mathbf{P}' \times \lambda)\{(\omega', x) : |x| > M, x \in [0, A_1], x \in [A_n, A_{n+1}]\}$$

$$+ (\mathbf{P}' \times \lambda)\{(\omega', x) : |x| \le M, x \in [0, A_1], x \in [A_n, A_{n+1}]\}$$

$$\le 2 \int_{M}^{\infty} \mathbf{P}'(A_1 > x) dx + (\mathbf{P}' \times \lambda)\{(\omega', x) : |x| \le M, x \in [A_n, A_{n+1}]\}$$

$$\le 2c_2 M^{-\beta+1} + 2M \sup_{x \in [-M,M]} \mathbf{P}'\{\omega' : x \in [A_n(\omega'), A_{n+1}(\omega')]\}$$

$$\le 2c_2 M^{-\beta+1} + 2M \mathbf{P}'(\{|A_n| \le M\} \cup \{|A_{n+1}| \le M\})$$

$$+ 2M \mathbf{P}'(\{A_n < -M, A_{n+1} > M\} \cup \{A_n > M, A_{n+1} < -M\})$$

$$\le 2c_2 M^{-\beta+1} + 4M \mathbf{P}'(|A_1| \le M/n^{H'}) + 2M \cdot 2c_1 M^{-\beta}.$$

$$(20)$$

where the first inequality uses the symmetry of A_1 . The second inequality uses (19), and the third inequality uses the fact that for $x \in [-M, M]$, the event $\{\omega' : x \in [A_n(\omega'), A_{n+1}(\omega')]\}$ is contained by the event that either A_n or A_{n+1} is in [-M, M] or that $[A_n, A_{n+1}]$ (which we defined as equivalent to $[A_{n+1}, A_n]$) contains [-M, M]. The final inequality uses both self-similarity and stationarity of increments.

Since the right side of (20) can be made arbitrarily small by choosing M and then n appropriately, the result is proved.

Since I-FSN is mixing, it is generated by a flow which is either dissipative or conservative null. Our next result classifies the flow of I-FSN as conservative if almost surely

$$\limsup_{n \to \infty} A_n = +\infty \quad \text{and} \quad \liminf_{n \to \infty} A_n = -\infty \quad \text{where } n \in \mathbb{N}.$$
(21)

This holds, for example, when A_t is a FBM or a S β S Levy motion with $\beta > 1$.

Theorem 4.3. If the subordinating process A_t satisfies (21), then the indicator fractional stable noise, $\{Z_A(n)\}_{n \in \mathbb{Z}}$, is generated by a conservative null flow.

Proof. By (21), we have that \mathbf{P}' -almost surely

$$\sum_{n=0}^{\infty} |1_{[0,A_{n}(\omega')]}(x) - 1_{[0,A_{n-1}(\omega')]}(x)|^{\alpha}$$

=
$$\sum_{n=0}^{\infty} 1_{[A_{n}(\omega'),A_{n+1}(\omega')]}(x) = \infty \quad \text{for every } x.$$
(22)

Hence by Theorem 3.2 we have that $Z_A(n)$ is generated by a conservative flow. By Theorem 4.2 the flow is also null.

Remarks.

- 1. When A_n satisfies (21), the fact that I-FSMs are generated by conservative null flows implies they form a class of processes which are disjoint from the class of RH-FSMs (positive flows) and disjoint from the class of L-FSMs (dissipative flows). We have already seen that the classes of I-FSMs and LT-FSMs are disjoint when $1 < \alpha < 2$ due to their self-similarity exponents.
- 2. Another useful property of conservative flows comes from Theorem 4.1 of [Sam04]: If $Z_A(n)$ is generated by a conservative flow, then it satisfies the following extreme value property:

$$n^{-1/\alpha} \max_{j=1,\dots,n} Z_A(n) \xrightarrow{p} 0.$$
⁽²³⁾

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