# A Coincidence Best Proximity Point Problem in G-Metric Spaces 

M. Abbas, ${ }^{1}$ A. Hussain, ${ }^{2}$ and P. Kumam ${ }^{3}$<br>${ }^{1}$ Department of Mathematics, Lahore University of Management Sciences, Pakistan<br>${ }^{2}$ Department of Mathematics, University of Sargodha, Pakistan<br>${ }^{3}$ Department of Mathematics, Faculty of Science, King Mongkut's University of Technology Thonburi (KMUTT), 126 Pracha Uthit Road, Bang Mod, Thung Khru, Bangkok 10140, Thailand

Correspondence should be addressed to P. Kumam; poom.kum@kmutt.ac.th
Received 2 June 2014; Accepted 3 August 2014
Academic Editor: Sehie Park
Copyright © 2015 M. Abbas et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.


#### Abstract

The aim of this paper is to initiate the study of coincidence best proximity point problem in the setup of generalized metric spaces. Some results dealing with existence and uniqueness of a coincidence best proximity point of mappings satisfying certain contractive conditions in such spaces are obtained. An example is provided to support the result proved herein. Our results generalize, extend, and unify various results in the existing literature.


## 1. Introduction and Preliminaries

Let $Y$ be any nonempty subset of a metric space $X$ and $T$ : $Y \rightarrow X$. A fixed point problem $\operatorname{Fix}(X, Y, T)$ defined by $X, Y$ and $T$ is to find a point $x^{*}$ in $Y$ such that $d\left(x^{*}, T x^{*}\right)=0$. A point $x^{*}$ in $Y$, where $\inf \left\{d\left(y, T x^{*}\right): y \in Y\right\}$, is attained; that is, $d\left(x^{*}, T x^{*}\right)=\inf \left\{d\left(y, T x^{*}\right): y \in Y\right\}$ holds and is called an approximate fixed point of $T$. In case it is not possible to solve $\operatorname{Fix}(X, Y, T)$, it could be interesting to study the conditions that assure existence and uniqueness of approximate fixed point of a mapping $T$.

Let $A$ and $B$ be two nonempty subsets of $X$ and $T: A \rightarrow$ $B$. Suppose that $\Delta_{A B}=d(A, B)=\inf (\{d(a, b): a \in A, b \in B\})$ is the measure of a distance between two sets $A$ and $B$. A point $x^{*}$ is called the best proximity point of $T$ if $d\left(x^{*}, T x^{*}\right)=\Delta_{A B}$. Thus the best proximity point problem defined by a mapping $T$ and a pair of sets $(A, B)$ is to find a point $x^{*}$ in $A$ such that $d\left(x^{*}, T x^{*}\right)=\Delta_{A B}$. If $A \cap B=\phi$, the fixed point problem defined by $A, B$ and $T$ has no solution. If $A=B$, the best proximity point problem reduces to a fixed point problem. In this way, the best proximity point problem can be viewed as a natural generalization of a fixed point problem. Furthermore, results dealing with existence and uniqueness of the best proximity point of certain mappings are more general than the ones dealing with fixed point problem of those mappings. A coincidence best proximity point problem is defined as
follows: find a point $x^{*}$ in $A$ such that $d\left(g x^{*}, T x^{*}\right)=\Delta_{A B}$, where $g$ is a self-mapping on $A$. This is an extension of the best proximity point problem. There are several results dealing with proximity point problem in the setup of metric spaces (see, e.g., [1-11] and references mentioned therein).

Mustafa and Sims [12] introduced the concept of a Gmetric space as a substantial generalization of metric space. They [13] obtained some fixed point theorems for mappings satisfying different contractive conditions in such spaces. Based on the notion of generalized metric spaces, Mustafa et al. [14-16] obtained several fixed point theorems for mappings satisfying different contractive conditions. Mustafa et al. [17-19] obtained some fixed point theorems for mappings satisfying different contractive conditions. Chugh et al. [20] obtained some fixed point results for maps satisfying property $P$ in $G$-metric spaces. Saadati et al. [21] studied fixed point of contractive mappings in partially ordered $G$-metric spaces. Shatanawi [22] obtained fixed points of $\Phi$-maps in $G$ metric spaces. For more details, we refer to, for example, [2239] and references therein.

A study of the best proximity point problem in the setup of $G$-metric space is a recent development by Hussain et al. [40]. This motivates us to extend the scope of this investigation and extend this study to coincidence proximity point problem of certain mappings in the framework of generalized metric spaces.

Consistent with Mustafa and Sims [12], the following definitions and results will be needed in the sequel.

Definition 1. Let $X$ be a nonempty set. Suppose that a mapping $G: X \times X \times X \rightarrow R^{+}$satisfies
(G1) $0 \leq G(x, y, z)$ for all $x, y, z \in X$ and $G(x, y, z)=0$ if and only if $x=y=z$,
(G2) $0<G(x, x, y)$ for all $x, y \in X$, with $x \neq y$,
(G3) $G(x, x, y) \leq G(x, y, z)$ for all $x, y, z \in X$, with $y \neq z$,
(G4) $G(x, y, z)=G(x, z, y)=G(y, z, x)=\cdots$ (symmetric in all three variables),
(G5) $G(x, y, z) \leq G(x, a, a)+G(a, y, z)$ for all $x, y, z, a \in X$ (rectangle inequality).
Then $G$ is called a generalized metric on $X$ or $G$-metric on $X$ and $(X, G)$ is called a $G$-metric space.

Definition 2. Let $(X, G)$ be a $G$-metric space, $\left\{x_{n}\right\}$ a sequence in $X$, and $x \in X$. One says that $\left\{x_{n}\right\}$ is
(i) a $G$-Cauchy sequence if, for any $\varepsilon>0$, there exists a natural number $N$ such that, for all $n, m, l \geq N$, $G\left(x_{n}, x_{m}, x_{l}\right)<\varepsilon ;$
(ii) a G-convergent sequence if, for any $\varepsilon>0$, there exists a natural number $N$ such that, for all $n, m \geq$ $N, G\left(x_{n}, x_{m}, x\right)<\varepsilon$ for some $x$ in $X$.

A $G$-metric space $X$ is said to be complete if every $G$-Cauchy sequence in $X$ is convergent in $X$. It is known that $\left\{x_{n}\right\}$ converges to $x \in(X, G)$ if and only if $G\left(x_{m}, x_{n}, x\right) \rightarrow 0$ as $n, m \rightarrow \infty$.

Proposition 3. Let $(X, G)$ be a $G$-metric space; then the following are equivalent.
(1) $\left\{x_{n}\right\}$ converges to $x \in X$.
(2) $G\left(x_{n}, x_{m}, x\right) \rightarrow 0$, as $m, n \rightarrow \infty$.
(3) $G\left(x_{n}, x_{n}, x\right) \rightarrow 0$, as $n \rightarrow \infty$.
(4) $G\left(x_{n}, x, x\right) \rightarrow 0$, as $n \rightarrow \infty$.

Definition 4. A $G$-metric on $X$ is said to be symmetric if $G(x, y, y)=G(y, x, x)$ for all $x, y \in X$.

Proposition 5. Every $G$-metric on $X$ will define a metric $d_{G}$ on $X$ by

$$
\begin{equation*}
d_{G}(x, y)=G(x, y, y)+G(y, x, x), \quad \forall x, y \in X \tag{1}
\end{equation*}
$$

Remark 6. Let $\left\{x_{n}\right\}$ be a sequence in $G$-metric space $X$. If $\left\{G\left(x_{n}, x_{n+1}, x_{n+1}\right)\right\} \rightarrow 0$ and $\left\{x_{n}\right\}$ is not a Cauchy sequence, then there exist $\epsilon_{0}>0$ and two subsequences $\left\{x_{m(k)}\right\}$ and $\left\{x_{n(k)}\right\}$ such that, for all $k \in \mathbb{N}, k \leq m(k)<n(k)$, $G\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right) \geq \epsilon_{0}$, and $G\left(x_{m(k)}, x_{l}, x_{l}\right)<\epsilon_{0}$ for all $l \in\{m(k)+1, m(k)+2, \ldots, n(k)-2, n(k)-1\}$. If $\lim _{k \rightarrow \infty} G\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right)=\epsilon_{0}$, then

$$
\begin{gather*}
\lim _{k \rightarrow \infty} G\left(x_{m(k)-1}, x_{n(k)-1}, x_{n(k)-1}\right)=\epsilon_{0} \\
\lim _{k \rightarrow \infty} G\left(x_{m(k)}, x_{n(k)+l}, x_{n(k)+l}\right)=\epsilon_{0} \tag{2}
\end{gather*}
$$

for all $l \geq 0$. Indeed, if $\left\{G\left(x_{n}, x_{n+1}, x_{n+1}\right)\right\} \rightarrow 0$, then, for all $k \in \mathbb{N}$, we have

$$
\begin{align*}
G( & \left.x_{m(k)-1}, x_{n(k)-1}, x_{n(k)-1}\right) \\
\quad \leq & G\left(x_{m(k)-1}, x_{m(k)}, x_{m(k)}\right)+G\left(x_{m(k)}, x_{n(k)-1}, x_{n(k)-1}\right) \\
\leq & G\left(x_{m(k)-1}, x_{m(k)}, x_{m(k)}\right)+G\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right) \\
& +G\left(x_{n(k)}, x_{n(k)-1}, x_{n(k)-1}\right), \\
G( & \left.x_{m(k)}, x_{n(k)}, x_{n(k)}\right) \\
\leq & G\left(x_{m(k)-1}, x_{m(k)}, x_{m(k)}\right)+G\left(x_{m(k)-1}, x_{n(k)-1}, x_{n(k)-1}\right) \\
& +G\left(x_{n(k)}, x_{n(k)-1}, x_{n(k)-1}\right) . \tag{3}
\end{align*}
$$

From (3) we have

$$
\begin{align*}
& G( \left.x_{m(k)}, x_{n(k)}, x_{n(k)}\right)-G\left(x_{m(k)-1}, x_{m(k)}, x_{m(k)}\right) \\
&-G\left(x_{n(k)}, x_{n(k)-1}, x_{n(k)-1}\right) \\
& \leq G\left(x_{m(k)-1}, x_{n(k)-1}, x_{n(k)-1}\right)  \tag{4}\\
& \leq G\left(x_{m(k)-1}, x_{m(k)}, x_{m(k)}\right)+G\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right) \\
& \quad+G\left(x_{n(k)}, x_{n(k)-1}, x_{n(k)-1}\right) .
\end{align*}
$$

Taking limit as $k \rightarrow \infty$, we obtain that $\lim _{k \rightarrow \infty} G\left(x_{m(k)-1}\right.$, $\left.x_{n(k)-1}, x_{n(k)-1}\right)=\epsilon_{0}$. To prove

$$
\begin{equation*}
\lim _{k \rightarrow \infty} G\left(x_{m(k)}, x_{n(k)+l+1}, x_{n(k)+l+1}\right)=\epsilon_{0} \tag{5}
\end{equation*}
$$

for all $l \geq 0$, we use induction on $l$. Equation (5) for $l=0$ holds obviously. Suppose that (5) holds for some $l>0$. Consider

$$
\begin{align*}
G\left(x_{m(k)}, x_{n(k)+l+1}, x_{n(k)+l+1}\right) \leq & G\left(x_{m(k)}, x_{n(k)+l}, x_{n(k)+l}\right) \\
& +G\left(x_{n(k)+1}, x_{n(k)+l+1}, x_{n(k)+l+1}\right) \tag{6}
\end{align*}
$$

Also,

$$
\begin{align*}
G\left(x_{m(k)}, x_{n(k)+l}, x_{n(k)+l}\right) \leq & G\left(x_{m(k)}, x_{n(k)+l+1}, x_{n(k)+l+1}\right) \\
& +G\left(x_{n(k)+l+1}, x_{n(k)+1}, x_{n(k)+1}\right) . \tag{7}
\end{align*}
$$

From (6) and (7), we obtain that

$$
\begin{align*}
& G\left(x_{m(k)}, x_{n(k)+l}, x_{n(k)+l}\right)-G\left(x_{n(k)+l+1}, x_{n(k)+1}, x_{n(k)+1}\right) \\
& \quad \leq G\left(x_{m(k)}, x_{n(k)+l+1}, x_{n(k)+l+1}\right) \\
& \quad \leq G\left(x_{m(k)}, x_{n(k)+l}, x_{n(k)+l}\right)+G\left(x_{n(k)+l+1}, x_{n(k)+1}, x_{n(k)+1}\right) . \tag{8}
\end{align*}
$$

Taking limit as $k \rightarrow \infty$, we have $\lim _{k \rightarrow \infty} G\left(x_{m(k)}, x_{n(k)+l+1}\right.$, $\left.x_{n(k)+l+1}\right)=\epsilon_{0}$.

Definition 7. Let $X$ be a $G$-metric space and $A$ and $B$ two nonempty subsets of $X$. Define
$\Delta_{A B}^{G}=G(A, B, B)=\inf \{G(a, b, b): a \in A, b \in B\}$,
$A_{0}=\{a \in A:$ there exists some $b \in B$ such that $G(a, b, b)$,

$$
\left.=\Delta_{A B}^{G}\right\}
$$

$B_{0}=\{b \in B:$ there exists some $a \in A$ such that $G(a, b, b)$

$$
\begin{equation*}
\left.=\Delta_{A B}^{G}\right\} \tag{9}
\end{equation*}
$$

Now we define the concept of $g$-best proximity point of a mapping in the setup of $G$-metric spaces.

Definition 8. Let $X$ be a $G$-metric space and $A$ and $B$ two nonempty subsets of $X$. Suppose that $T: A \rightarrow B$, and $g: A \rightarrow A$. A point $x \in A$ is called $g$-best proximity point of $T$ if $G(g x, T x, T x)=\Delta_{A B}^{G}$.

Note that if $g$ is an identity mapping on $A$, then $x$ in above definition becomes the best proximity point of $T$.

Consistent with [41], we consider the following classes of mappings.
$\Psi=\{\varphi:[0, \infty) \rightarrow[0, \infty)$ such that, for all $t>0$, the series $\sum_{n \geq 1} \varphi^{n}(t)$ converges $\}$. Elements in $\Psi$ are called (c)comparison functions.
$\Phi=\{\phi:[0, \infty) \rightarrow[0, \infty)$ such that $\phi(t)<t$ and $\lim _{r \rightarrow t^{+}} \phi(r)<t$ for all $\left.t>0\right\}$.
$\Theta=\left\{\theta:[0, \infty)^{4} \rightarrow[0, \infty)\right.$ such that $\theta(a, b, c, d)=$ 0 if one or more arguments take the value zero and $\theta$ is continuous $\}$.
$\Omega_{1}=\left\{\theta:[0, \infty)^{4} \rightarrow[0, \infty)\right.$ such that $\theta(a, b, c, d)=0$ if one or more arguments take the value zero\}.
$\Omega_{1}=\left\{\theta:[0, \infty)^{4} \rightarrow[0, \infty)\right.$ such that $\left.\theta(0, b, c, d)=0\right\}$.
$\Omega_{2}=\left\{\theta:[0, \infty)^{4} \rightarrow[0, \infty)\right.$ such that $\lim _{n \rightarrow \infty} \theta\left(t_{n}^{1}, t_{n}^{2}, t_{n}^{3}, t_{n}^{4}\right)=0$, whenever the sequences $\left\{t_{n}^{1}\right\}$, $\left\{t_{n}^{1}\right\},\left\{t_{n}^{1}\right\},\left\{t_{n}^{1}\right\} \subset[0, \infty)$ are such that at least one of them is convergent to zero\}.

Definition 9. Let $X$ be a $G$-metric space and $A$ and $B$ two nonempty subsets of $X, g: A \rightarrow A$, and $\alpha: X \times X \rightarrow$ $[0, \infty)$. A mapping $T: A \rightarrow B$ is said to be $(\varphi, \theta, \alpha, g)$ contraction if, for all $x, y \in A_{0}$ with $G(g y, T x, T x)=\Delta_{A B}^{G}$ and $\alpha(g x, g y) \geq 1$, one has

$$
\begin{align*}
& \alpha(g x, g y) G(T x, T y, T y) \\
& \leq \varphi\left(M^{g}(x, y, y)\right) \\
& \quad+\theta\left(G(g y, T x, T x)-\Delta_{A B}^{G}, G(g x, T y, T y)-\Delta_{A B}^{G}\right. \\
& \left.\quad G(g x, T x, T x)-\Delta_{A B}^{G}, G(g y, T y, T y)-\Delta_{A B}^{G}\right), \tag{10}
\end{align*}
$$

where

$$
\begin{align*}
M^{g}(x, y, y)=\max ( & G(g x, g y, g y), G(g x, T x, T x)-\Delta_{A B}, \\
& G(g y, T y, T y)-\Delta_{A B}^{G}, \\
& \left.\frac{G(g x, T y, T y)+G(g y, T y, T y)}{2}-\Delta_{A B}^{G}\right), \tag{11}
\end{align*}
$$

$\psi \in \Psi$ and $\theta \in \Theta$.
Definition 10. Let $X$ be a $G$-metric space and $A$ and $B$ two nonempty subsets of $X, g: A \rightarrow A$, and $\alpha: X \times$ $X \rightarrow[0, \infty)$. A mapping $T: A \rightarrow B$ is said to be $(\alpha, g)$ proximinal and admissible if $a_{1}, a_{2}, b_{1}, b_{2} \in A_{0}, \alpha\left(g b_{1}, g b_{2}\right) \geq$ $1, G\left(g a_{1}, T b_{1}, T b_{1}\right)=\Delta_{A B}^{G}, G\left(g a_{2}, T b_{2}, T b_{2}\right)=\Delta_{A B}^{G}$, and

$$
\begin{equation*}
\Longrightarrow \alpha\left(g a_{1}, g a_{2}\right) \geq 1 \tag{12}
\end{equation*}
$$

Definition 11. Let $X$ be a $G$-metric space and $A$ and $B$ two subsets of $X$ such that $A_{0}$ is nonempty, $T: A \rightarrow B$, and $g: A \rightarrow A$. For $a_{1}, a_{2}, a_{3}, a_{4} \in A_{0}$, the quadruple $(A, B, T, g)$ has
(1) weak $P$-property of the first kind if

$$
G\left(g a_{1}, T a_{3}, T a_{3}\right)=\Delta_{A B}^{G}, \quad G\left(g a_{2}, T a_{4}, T a_{4}\right)=\Delta_{A B}^{G}
$$

implies that $G\left(g a_{1}, g a_{2}, g a_{2}\right) \leq G\left(T a_{3}, T a_{4}, T a_{4}\right)$;
(2) weak $P$-property of the second kind if

$$
G\left(g a_{1}, T a_{3}, T a_{3}\right)=\Delta_{A B}^{G}, \quad G\left(g a_{2}, T a_{4}, T a_{4}\right)=\Delta_{A B}^{G}
$$

implies that $G\left(g a_{1}, g a_{2}, g a_{2}\right)=G\left(T a_{3}, T a_{4}, T a_{4}\right)$;
(3) weak $P$-property of the third kind if

$$
G\left(g a_{1}, T a_{3}, T a_{3}\right)=\Delta_{A B}^{G}, \quad G\left(g a_{2}, T a_{4}, T a_{4}\right)=\Delta_{A B}^{G}
$$

implies that $G\left(g a_{1}, g a_{2}, g a_{2}\right) \leq G\left(T b_{1}, T b_{2}, T b_{2}\right)$.

Definition 12 (see [41]). Let $g: A \rightarrow A$ and $\alpha: X \times X \rightarrow$ $[0,1)$ be two mappings and let $N \in \mathbb{N}, N \geq 2$. One will say that $\alpha$ is $(N, g)$-transitive on $A_{0}$ if $x_{1}, x_{2}, \ldots, x_{N+1} \in A_{0}$, $\alpha\left(g x_{i}, g x_{i+1}\right) \geq 1 \forall i \in\{1,2, \ldots, N\} \Rightarrow \alpha\left(g x_{1}, g x_{N+1}\right) \geq 1$.

Indeed, we will only use the notion of $(2, g)$-transitive mapping on $A_{0}$; that is, $x_{1}, x_{2}, x_{3} \in A_{0}, \alpha\left(g x_{1}, g x_{2}\right) \geq 1$, $\alpha\left(g x_{2}, g x_{3}\right) \geq 1$, and

$$
\begin{equation*}
\Longrightarrow \alpha\left(g x_{1}, g x_{3}\right) \geq 1 \tag{16}
\end{equation*}
$$

## 2. Coincidence Best Proximity Point Results

In this section, we obtain several coincidence best proximity results in the setup of generalized metric spaces.

Theorem 13. Let $X$ be a complete $G$-metric space, $A$ and $B$ two closed subsets of $X$, and $g$ a continuous self-mapping on $A$ such that $\phi \neq A_{0} \subseteq g A_{0}$. Suppose that $T: A \rightarrow B$ is continuous $(\alpha, g)$-proximal and admissible and $(\varphi, \theta, \alpha, g)$ contraction, where $\varphi \in \Psi, \theta \in \Omega_{1}$, and $T\left(A_{0}\right) \subseteq B_{0}$. If the following conditions hold:
(a) quadruple $(A, B, T, g)$ satisfies weak $P$-property of the first kind;
(b) if a sequence $\left\{z_{n}\right\}$ in $A_{0}$ such that $\left\{g z_{n}\right\} \subseteq A_{0}$ is Cauchy, then $\left\{z_{n}\right\}$ is also a Cauchy;
(c) there exists $\left(x_{0}, x_{1}\right) \in A_{0} \times A_{0}$ such that $G\left(g x_{1}\right.$, $\left.T x_{0}, T x_{0}\right)=\Delta_{A B}^{G}$ and $\alpha\left(g x_{0}, g x_{1}\right) \geq 1$.

Then there exists a convergent sequence $\left\{x_{n}\right\} \subseteq A_{0}$ which satisfies

$$
\begin{equation*}
G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}^{G} \quad \forall n \geq 0 \tag{17}
\end{equation*}
$$

and the limit of $\left\{x_{n}\right\}$ is a $g$-best proximity point of $T$.
Proof. Let $x_{1} \in A_{0}$. Then $T x_{1} \in T\left(A_{0}\right) \subseteq B_{0}$. Hence there is $z_{2} \in A$ such that $G\left(z_{2}, T x_{1}, T x_{1}\right)=\Delta_{A B}^{G}$ which implies that $z_{2} \in A_{0}$. As $A_{0} \subseteq g A_{0}$, there is $x_{2} \in A_{0}$ such that $g\left(x_{2}\right)=z_{2}$, so $G\left(g x_{2}, T x_{1}, T x_{1}\right)=G\left(z_{2}, T x_{1}, T x_{1}\right)=\Delta_{A B}^{G}$. In a similar way, there is $x_{3} \in A_{0}$ such that $G\left(g x_{3}, T x_{2}, T x_{2}\right)=\Delta_{A B}^{G}$. Inductively we construct a sequence $\left\{x_{n}\right\} \subseteq A_{0}$ such that

$$
\begin{equation*}
G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}^{G} \quad \forall n \geq 0 \tag{18}
\end{equation*}
$$

If there exists some $n_{0} \in N$, such that $g x_{n_{0}}=g x_{n_{0}+1}$, then $G\left(g x_{n_{0}}, T x_{n_{0}}, T x_{n_{0}}\right)=G\left(g x_{n_{0}+1}, T x_{n_{0}}, T x_{n_{0}}\right)=\Delta_{A B}^{G}$ implies that $x_{n_{0}}$ is a $g$-best proximity point of $T$. If we define $x_{m}=x_{n_{0}}$ for all $m \geq n_{0}$, then $\left\{x_{n}\right\}$ converges to a $g$-best proximity point of $T$. The proof is complete. Assume that

$$
\begin{equation*}
G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right)>0 \quad \forall n \geq 0 . \tag{19}
\end{equation*}
$$

Note that $x_{n}, g x_{n+1} \in A_{0}$ and $T x_{n} \in B_{0}$ for all $n \geq 0$. We claim that

$$
\begin{equation*}
\alpha\left(g x_{n}, g x_{n+1}\right) \geq 1 \quad \forall n \geq 0 \tag{20}
\end{equation*}
$$

If $n=0$, then $\alpha\left(g x_{n}, g x_{n+1}\right) \geq 1$ holds by given hypothesis. Suppose that $\alpha\left(g x_{n}, g x_{n+1}\right) \geq 1$ for some $n>0$. As $T$ is $(\alpha, g)$-proximal and admissible, for $x_{n}, x_{n+1}, x_{n+2} \in$ $A_{0}, \alpha\left(g x_{n}, g x_{n+1}\right) \geq 1, G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}^{G}$, and $G\left(g x_{n+2}, T x_{n+1}, T x_{n+1}\right)=\Delta_{A B}^{G}$, we have $\alpha\left(g x_{n+1}, g x_{n+2}\right) \geq 1$. Thus (20) holds.

Use weak $P$-property of the first kind, for all $n>0$, $x_{n}, x_{n+1}, x_{n+2} \in A_{0}, G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}^{G}, G\left(g x_{n+2}\right.$, $\left.T x_{n+1}, T x_{n+1}\right)=\Delta_{A B}^{G}$ imply the following inequality:

$$
\begin{equation*}
\Longrightarrow G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right) \leq G\left(T x_{n}, T x_{n+1}, T x_{n+1}\right) \tag{21}
\end{equation*}
$$

Now by (20), (21), and ( $\varphi, \theta, \alpha, g$ )-contractive property of $T$, we have

$$
\begin{align*}
& G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right) \\
& \quad \leq G\left(T x_{n}, T x_{n+1}, T x_{n+1}\right) \\
& \leq \\
& \leq \alpha\left(g x_{n}, g x_{n+1}\right) G\left(T x_{n}, T x_{n+1}, T x_{n+1}\right) \\
& \leq
\end{aligned} \quad \begin{aligned}
& \quad\left(M^{g}\left(x_{n}, x_{n+1}, x_{n+1}\right)\right)  \tag{22}\\
& \quad \\
& \quad \theta\left(G\left(g x_{n+1}, T x_{n}, T x_{n}\right)\right. \\
& \quad-\Delta_{A B}^{G}, G\left(g x_{n}, T x_{n+1}, T x_{n+1}\right) \\
& \quad-\Delta_{A B}^{G}, G\left(g x_{n}, T x_{n}, T x_{n}\right)-\Delta_{A B}^{G} \\
& \left.\quad \quad G\left(g x_{n+1}, T x_{n+1}, T x_{n+1}\right)-\Delta_{A B}^{G}\right) \\
& =
\end{align*}
$$

for all $n>0$, where

$$
\begin{aligned}
& \varphi\left(M^{g}\left(x_{n}, x_{n+1}, x_{n+1}\right)\right) \\
& =\max \left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right), G\left(g x_{n}, T x_{n}, T x_{n}\right)-\Delta_{A B}^{G},\right. \\
& G\left(g x_{n+1}, T x_{n+1}, T x_{n+1}\right)-\Delta_{A B}^{G}, \\
& \frac{G\left(g x_{n}, T x_{n+1}, T x_{n+1}\right)+G\left(x_{n+1}, T x_{n}, T x_{n}\right)}{2} \\
& \left.\quad-\Delta_{A B}^{G}\right) \\
& \leq \max \left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right), G\left(x_{n}, x_{n+1}, x_{n+1}\right)\right. \\
& \quad+G\left(g x_{n+1}, T x_{n}, T x_{n}\right)-\Delta_{A B}^{G}, \\
& \quad G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right) \\
& \quad+G\left(g x_{n+2}, T x_{n+1}, T x_{n+1}\right)-\Delta_{A B}^{G}, \\
& \frac{1}{2}\left[G\left(x_{n}, g x_{n+1}, g x_{n+1}\right)\right. \\
& \quad+G\left(g x_{n+1}, T x_{n+1}, T x_{n+1}\right) \\
& \quad+G\left(x_{n+1}, g x_{n+2}, g x_{n+2}\right) \\
& \left.\left.\quad+G\left(g x_{n+2}, T x_{n}, T x_{n}\right)\right]-\Delta_{A B}^{G}\right) \\
& =\max \left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right), G\left(x_{n}, x_{n+1}, x_{n+1}\right)\right. \\
& +\Delta_{A B}^{G}-\Delta_{A B}^{G}, \\
& G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right)+\Delta_{A B}^{G}-\Delta_{A B}^{G} \\
& \left(\left(G\left(x_{n}, g x_{n+1}, g x_{n+1}\right)+G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right)\right.\right. \\
& \\
& \left.\left.\left.\quad 2 \Delta_{A B}^{G}\right) \times(2)^{-1}\right)-\Delta_{A B}^{G}\right)
\end{aligned}
$$

$$
\begin{align*}
& =\max \left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right), G\left(x_{n}, x_{n+1}, x_{n+1}\right),\right. \\
& \quad G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right) \\
& \left.\quad \frac{G\left(x_{n}, g x_{n+1}, g x_{n+1}\right)+G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right)}{2}\right) \\
& =\max \left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right), G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right)\right) . \tag{23}
\end{align*}
$$

That is,

$$
\begin{align*}
& \varphi\left(M^{g}\left(x_{n}, x_{n+1}, x_{n+1}\right)\right) \\
& \quad \leq \max \left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right), G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right)\right) \tag{24}
\end{align*}
$$

From (22) and (24), we have

$$
\begin{align*}
& G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right) \\
& \leq \varphi\left(\max \left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right), G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right)\right)\right) \tag{25}
\end{align*}
$$

for all $n>0$.
If there exists some $n_{0} \in N$ such that

$$
\begin{align*}
& \max \left(G\left(g x_{n_{0}}, g x_{n_{0}+1}, g x_{n_{0}+1}\right), G\left(g x_{n_{0}+1}, g x_{n_{0}+2}, g x_{n_{0}+2}\right)\right) \\
& \quad=G\left(g x_{n_{0}+1}, g x_{n_{0}+2}, g x_{n_{0}+2}\right) \tag{26}
\end{align*}
$$

then, using (19) and the fact that $\varphi(t)<t$ for all $t>0$, we have

$$
\begin{align*}
G\left(g x_{n_{0}+1}, g x_{n_{0}+2}, g x_{n_{0}+2}\right) & \leq \varphi\left(G\left(g x_{n_{0}+1}, g x_{n_{0}+2}, g x_{n_{0}+2}\right)\right) \\
& <G\left(g x_{n_{0}+1}, g x_{n_{0}+2}, g x_{n_{0}+2}\right) \tag{27}
\end{align*}
$$

which is a contradiction. Hence

$$
\begin{align*}
& \max \left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right), G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right)\right)  \tag{28}\\
& \quad=G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right)
\end{align*}
$$

for all $n>0$. Now (25) implies that

$$
\begin{equation*}
G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right) \leq \varphi\left(G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right)\right) \tag{29}
\end{equation*}
$$

for all $n>0$.
In particular, for all $n \geq 1$, we have

$$
\begin{align*}
& G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right) \\
& \quad \leq \varphi\left(G\left(g x_{n-1}, g x_{n}, g x_{n}\right)\right) \\
& \quad \leq \varphi^{2}\left(G\left(g x_{n-2}, g x_{n-1}, g x_{n-1}\right)\right)  \tag{30}\\
& \quad \leq \cdots \leq \varphi^{n}\left(G\left(g x_{0}, g x_{1}, g x_{1}\right)\right) .
\end{align*}
$$

Fix $\epsilon>0$ and $t_{0}=G\left(g x_{0}, g x_{1}, g x_{1}\right)>0$. Since $\varphi \epsilon$ $\Psi, \sum_{n \geq 1} \varphi^{n}\left(t_{0}\right)$ converges. In particular, there exists some
$m_{0} \in N$ such that $\sum_{k=m_{0}}^{\infty} \varphi^{n}\left(t_{0}\right)<\epsilon$. Hence, for $m>n \geq m_{0}$, we have

$$
\begin{align*}
G\left(g x_{n}, g x_{m}, g x_{m}\right) & \leq \sum_{k=n}^{m-1} G\left(g x_{k}, g x_{k+1}, g x_{k+1}\right) \\
& \leq \sum_{k=n}^{m-1} \varphi^{k} G\left(g x_{0}, g x_{1}, g x_{1}\right)  \tag{31}\\
& \leq \sum_{k=m_{0}}^{\infty} \varphi^{n}\left(t_{0}\right)<\epsilon
\end{align*}
$$

This implies that $\left\{g x_{n}\right\}$ is a Cauchy sequence. By given hypothesis, $\left\{x_{n}\right\}$ is a Cauchy sequence. By completeness of $X$, there exists $z \in X$ such that $\left\{x_{n}\right\} \rightarrow z$. As $x_{n} \in A_{0} \subseteq A$ for all $n$, so $z \in A$. Since $T$ and $g$ are continuous mappings, $\left\{T x_{n}\right\} \rightarrow T z$ and $\left\{g x_{n}\right\} \rightarrow g z$. Taking limit in (18) as $n \rightarrow$ $\infty$, we conclude that $z$ is a $g$-best proximity point of $T$.

Remark 14. If $g$ is an identity map in Theorem 13, then we obtain the best proximity point of mapping $T$.

Corollary 15. Let $X$ be a complete G-metric space, $A$ and $B$ two closed subsets of $X$, and $g$ a continuous self-mapping on $A$ such that $\phi \neq A_{0} \subseteq g A_{0}$. Suppose that $T: A \rightarrow B$ is continuous $(\alpha, g)$-proximal and admissible and $(\varphi, \theta, \alpha, g)$ contraction, where $\varphi \in \Psi, \theta \in \Omega_{1}$, and $T\left(A_{0}\right) \subseteq B_{0}$. If following conditions hold:
(a) quadruple $(A, B, T, g)$ satisfies weak $P$-property of the first kind,
(b) for $x, y, z \in A_{0}$ with $G(g y, T x, T x)=\Delta_{A B}^{G}$ and $\alpha(g x$, $g y) \geq 1$, the following holds:

$$
\begin{align*}
& \alpha(g x, g y) G(T x, T y, T z) \\
& \quad \leq k M^{g}(x, y, z) \\
& \quad+\theta\left(G(g y, T x, T x)-\Delta_{A B}^{G},\right. \\
& \quad \\
& \quad G(g x, T y, T y)-\Delta_{A B}^{G}, G(g x, T x, T x)-\Delta_{A B}^{G},  \tag{32}\\
& \quad \\
& \left.\quad G(g y, T y, T y)-\Delta_{A B}^{G}\right),
\end{align*}
$$

(c) if a sequence $\left\{z_{n}\right\}$ in $A_{0}$ with $\left\{g z_{n}\right\} \subseteq A_{0}$ is Cauchy, then $\left\{z_{n}\right\}$ is Cauchy,
(d) there is $\left(x_{0}, x_{1}\right) \in A_{0} \times A_{0}$ such that $G\left(g x_{1}, T x_{0}\right.$, $\left.T x_{0}\right)=\Delta_{A B}^{G}$ and $\alpha\left(g x_{0}, g x_{1}\right) \geq 1$.

Then there exists a convergent sequence $\left\{x_{n}\right\} \subseteq A_{0}$ which satisfies

$$
\begin{equation*}
G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}^{G} \quad \forall n \geq 0 \tag{33}
\end{equation*}
$$

and $\left\{x_{n}\right\}$ converges to $g$-best proximity point of $T$.

Example 16. Let $X=\{0,1,2,3, \ldots\}$ and $G: X \times X \times X \rightarrow \mathbb{R}^{+}$ defined by

$$
G(x, y, z)= \begin{cases}x+y+z & \text { if } x \neq y \neq z \neq 0  \tag{34}\\ x+y & \text { if } x=y \neq z, x, y, z \neq 0 \\ y+z+1 & \text { if } x=0, y \neq z, y, z \neq 0 \\ y+2 & \text { if } x=0, y=z \neq 0 \\ z+1 & \text { if } x=y=0, z \neq 0 \\ 0 & \text { if } x=y=z\end{cases}
$$

It is known that $X$ is a complete $G$-metric space. Let $A=$ $\{0,2,4\}$ and $B=\{1,3,5, \ldots\}$. Obviously $A$ and $B$ are closed subsets of $X$ and $\Delta_{A B}^{G}=G(A, B, B)=G(0,1,1)=3$. Take $A_{0}=\{0,2\}$. Define the mapping $g: A \rightarrow A$ by

$$
g(x)= \begin{cases}x & \text { if } x=0,2  \tag{35}\\ \frac{x}{2} & \text { if } x=4\end{cases}
$$

Obviously $g$ is continuous and $A_{0} \subseteq g\left(A_{0}\right)$. A mapping $T$ : $A \rightarrow B$ defined by $T(x)=1$ is continuous. Define $\alpha: X \times$ $X \rightarrow[0, \infty)$ by $\alpha(x, y)=x+y$. Clearly

$$
\begin{align*}
\alpha(g(0), g(2)) & =\alpha(0,2)=2>1, \\
G(g(0), T(2), T(2)) & =G(0,1,1)=3,  \tag{36}\\
G(g(2), T(0), T(0)) & =G(2,1,1)=3 .
\end{align*}
$$

As $\alpha(0,2)=2>1$, so $T$ is $(\alpha, g)$-proximal and admissible. Since

$$
\begin{equation*}
\alpha(g(0), g(2)) G(T(0), T(2), T(2))=2 G(1,1,1)=0 \tag{37}
\end{equation*}
$$

and $M^{g}(0,2,2)=4$, therefore $T$ is $(\varphi, \theta, \alpha, g)$-contraction. Now

$$
\begin{align*}
& G(g(0), T(2), T(2))=G(0,1,1)=3=\Delta_{A B}^{G}  \tag{38}\\
& G(g(2), T(0), T(0))=G(2,1,1)=3=\Delta_{A B}^{G}
\end{align*}
$$

imply that $G(g(0), g(0), g(0))=G(0,0,0)=0=G(T(2)$, $T(0), T(0))=G(1,1,1)$. Hence quadruple $(A, B, T, g)$ has weak $P$-property of the first kind. Note that $(0,2) \in A_{0} \times A_{0}$ with $G(g(2), T(0), T(0))=3=\Delta_{A B}^{G}$ and $\alpha(g(0), g(2))>1$. Thus $T$ has $g$-best proximity point ( 0 and 2 are $g$-best proximity point of $T$ ).

Lemma 17. Let $\phi \in \Phi$ be a mapping and let $\left\{a_{m}\right\} \subset \mathbb{R}^{+}$be a sequence. If $a_{m+1} \leq \phi\left(a_{m}\right)$ and $a_{m} \neq 0$ for all $m$, then $\left\{a_{m}\right\} \rightarrow$ 0.

Theorem 18. If condition (h) in Theorem 13 is replaced by the following:
$\left(h^{\prime}\right) \varphi \in \Phi, \theta \in \Omega_{2}$ and $\alpha$ is $(2, g)$-transitive, then there exists a sequence $\left\{x_{n}\right\} \subseteq A_{0}$ which satisfies

$$
\begin{equation*}
G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}^{G} \quad \forall n \geq 0 \tag{39}
\end{equation*}
$$

and converges to a g-best proximity point of $T$.

Proof. Following arguments similar to those in the proof of Theorem 13, we have

$$
\begin{align*}
& G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}, \\
& G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right)>0, \\
& \alpha\left(g x_{n}, g x_{n+1}\right) \geq 1,  \tag{40}\\
& \quad x_{n} \in A_{0}, \\
& G\left(g x_{n+1}, g x_{n+2}, g x_{n+2}\right) \leq \varphi\left(G\left(g x_{n}, g x_{n+1}, g x_{n+2}\right)\right) \\
& \forall n \geq 0 .
\end{align*}
$$

By Lemma 17, we have

$$
\begin{equation*}
\left\{G\left(g x_{n}, g x_{n+1}, g x_{n+1}\right)\right\} \longrightarrow 0 \tag{41}
\end{equation*}
$$

Next, we show that $\left\{g x_{n}\right\}$ is a Cauchy sequence. Assume on the contrary that $\left\{g x_{n}\right\}$ is not a Cauchy sequence. Then, by Remark 6, there exist $\epsilon_{0}>0$ and two subsequences $\left\{x_{m(k)}\right\}$ and $\left\{x_{n(k)}\right\}$ such that the following hold:

$$
\begin{align*}
& k \leq m(k)<n(k), \quad G\left(g x_{m(k)}, g x_{n(k)}, g x_{n(k)}\right)>\epsilon_{0}, \\
& \forall k \in \mathbb{N}, \\
& G\left(g x_{m(k)}, g x_{p}, g x_{p}\right) \leq \epsilon_{0} \\
& \forall p \in\{m(k)+1, m(k)+2, \ldots, n(k)-2, n(k)-1\}, \tag{42}
\end{align*}
$$

$$
\begin{align*}
& \lim _{k \rightarrow \infty} G\left(g x_{m(k)-1}, g x_{n(k)-1}, g x_{n(k)-1}\right)=\epsilon_{0}, \\
& \lim _{k \rightarrow \infty} G\left(g x_{m(k)-1}, g x_{n(k)+p}, g x_{n(k)+p}\right)=\epsilon_{0} \tag{43}
\end{align*}
$$

$\forall p \geq 0$. Note that

$$
\begin{align*}
0 \leq & G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G} \\
\leq & G\left(g x_{n(k)}, g x_{n(k)+1}, g x_{n(k)+1}\right)  \tag{44}\\
& +G\left(g x_{n(k)+1}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G} \\
= & G\left(g x_{n(k)}, g x_{n(k)+1}, g x_{n(k)+1}\right) .
\end{align*}
$$

Therefore

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left[G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G}\right]=0 \tag{45}
\end{equation*}
$$

Similarly,

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left[G\left(g x_{m(k)}, T x_{m(k)}, T x_{m(k)}\right)-\Delta_{A B}^{G}\right]=0 \tag{46}
\end{equation*}
$$

Furthermore,

$$
\begin{equation*}
\epsilon_{0}<G\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right) \leq M^{g}\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right) \quad \forall k \geq 0 \tag{47}
\end{equation*}
$$

where

$$
\begin{align*}
& M^{g}\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right) \\
& =\max \left(G\left(g x_{m(k)}, g x_{n(k)}, g x_{n(k)}\right), G\left(g x_{m(k)}, T x_{m(k)}, T x_{m(k)}\right)\right. \\
& -\Delta_{A B}^{G}, G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G}, \\
& \frac{G\left(g x_{m(k)}, T x_{n(k)}, T x_{n(k)}\right)+G\left(g x_{n(k)}, T x_{n(k)}, T x_{m(k)}\right)}{2} \\
& \left.-\Delta_{A B}^{G}\right) .  \tag{48}\\
& \frac{G\left(g x_{m(k)}, T x_{n(k)}, T x_{n(k)}\right)+G\left(g x_{n(k)}, T x_{n(k)}, T x_{m(k)}\right)}{2} \\
& -\Delta_{A B}^{G} \\
& \leq \frac{1}{2}\left[G\left(g x_{m(k)}, g x_{n(k)+1}, g x_{n(k)+1}\right)\right. \\
& +G\left(g x_{n(k)+1}, T x_{n(k)}, T x_{n(k)}\right) \\
& +G\left(g x_{n(k)}, g x_{m(k)+1}, g x_{m(k)+1}\right) \\
& \left.+G\left(g x_{m(k)+1}, T x_{n(k)}, T x_{m(k)}\right)\right] \\
& -\Delta_{A B}^{G} \\
& =\left(G\left(g x_{m(k)}, g x_{n(k)+1}, g x_{n(k)+1}\right)+\Delta_{A B}\right. \\
& \left.+G\left(g x_{n(k)}, g x_{m(k)+1}, g x_{m(k)+1}\right)+\Delta_{A B}\right) \times(2)^{-1} \\
& -\Delta_{A B} \\
& =\left(G\left(g x_{m(k)}, g x_{n(k)+1}, g x_{n(k)+1}\right)\right. \\
& \left.+G\left(g x_{n(k)}, g x_{m(k)+1}, g x_{m(k)+1}\right)\right) \times(2)^{-1} . \tag{49}
\end{align*}
$$

Taking limit as $k \rightarrow \infty$ in (49) and using (45), we obtain that

$$
\begin{align*}
\lim _{k \rightarrow \infty}( & \frac{G\left(g x_{m(k)}, T x_{n(k)}, T x_{n(k)}\right)+G\left(g x_{n(k)}, T x_{n(k)}, T x_{m(k)}\right)}{2} \\
& \left.-\Delta_{A B}^{G}\right) \leq \frac{\epsilon+\epsilon}{2}=\epsilon_{0} \tag{50}
\end{align*}
$$

Taking limit as $k \rightarrow \infty$ in (48) and using (43), (45), (46), and (50), we have

$$
\begin{equation*}
\lim _{k \rightarrow \infty} M^{g}\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right)=\max \left(\epsilon_{0}, 0,0, \epsilon_{0}\right)=\epsilon_{0} \tag{51}
\end{equation*}
$$

Thus a sequence $\left\{M^{g}\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right)\right\}$ converges to $\epsilon_{0}$ and terms of this sequence are strictly greater than $\epsilon_{0}$. ln particular, since $\varphi \in \Phi$,

$$
\begin{equation*}
\lim _{k \rightarrow \infty} \varphi\left(\left\{M^{g}\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right)\right\}\right)=\lim _{t \rightarrow \epsilon_{0}^{+}} \varphi(t)<\epsilon_{0} . \tag{52}
\end{equation*}
$$

From the fact that $\alpha\left(g x_{n}, g x_{n+1}\right) \geq 1$ for all $n \geq 0$ and $\alpha$ is $(2, g)$-transitive, we deduce that

$$
\begin{equation*}
\alpha\left(g x_{m(k)}, g x_{n(k)}\right) \geq 1 \quad \forall k \geq 0 \tag{53}
\end{equation*}
$$

As $(A, B, T, g)$ has the weak $P$-property of the first kind, so, for all $k \geq 0$,

$$
\begin{align*}
& x_{m(k)}, x_{m(k)+1}, x_{n(k)}, x_{n(k)+1} \in A_{0}, \\
& G\left(g x_{m(k)+1}, T x_{m(k)}, T x_{m(k)}\right)=\Delta_{A B}^{G},  \tag{54}\\
& G\left(g x_{n(k)+1}, T x_{n(k)}, T x_{n(k)}\right)=\Delta_{A B}^{G} .
\end{align*}
$$

This implies that

$$
\begin{equation*}
G\left(g x_{m(k)+1}, g x_{n(k)+1}, g x_{n(k)+1}\right) \leq G\left(T x_{m(k)}, T x_{n(k)}, T x_{n(k)}\right) . \tag{55}
\end{equation*}
$$

As $T$ is $(\varphi, \theta, \alpha, g)$-contraction, so we have

$$
\begin{align*}
& G\left(g x_{m(k)+1}, g x_{n(k)+1}, g x_{n(k)+1}\right) \\
& \leq G\left(g x_{m(k)}, T x_{n(k)}, T x_{n(k)}\right) \\
& \leq \alpha\left(T x_{m(k)}, T x_{n(k)}, T x_{n(k)}\right) G\left(g x_{m(k)}, T x_{n(k)}, T x_{n(k)}\right) \\
& \leq \varphi\left(M^{g}\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right)\right. \\
& \quad+\theta\left(G\left(g x_{n(k)}, T x_{m(k)}, T x_{m(k)}\right)\right.  \tag{56}\\
& \quad-\Delta_{A B}, G\left(g x_{m(k)}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}, \\
& \quad G\left(g x_{m(k)}, T x_{m(k)}, T x_{m(k)}\right)-\Delta_{A B}, \\
& \left.\left.\quad G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}\right)\right) .
\end{align*}
$$

Using (45), the third and the fourth arguments of $\theta$ converge to zero as $k \rightarrow \infty$. Since $\theta \in \Omega_{2}$, all the terms tend to zero as $k \rightarrow \infty$. Taking limit as $k \rightarrow \infty$ in (56), using (45) and (52), we have

$$
\begin{align*}
\epsilon_{0} & =\lim _{k \rightarrow \infty} G\left(g x_{m(k)+1}, g x_{n(k)+1}, g x_{n(k)+1}\right) \\
& \leq \lim _{k \rightarrow \infty} \varphi\left(M^{g}\left(x_{m(k)}, x_{n(k)}, x_{n(k)}\right)\right)<\epsilon_{0} \tag{57}
\end{align*}
$$

which is an absurd statement. Hence $\left\{g x_{n}\right\}$ is a Cauchy sequence. The rest follows from Theorem 13.

Theorem 19. Theorem 13 also holds if contractive condition (10) is valid for all $x \in A_{0}$ and $y \in A$; conditions (b) and $(g)$ are replaced by the following:
$\left(b^{\prime}\right)$ quadruple $(A, B, T, g)$ has the weak $P$-property of the second kind;
$\left(g^{\prime}\right)$ for a sequence $\left\{x_{n}\right\} \subseteq A_{0}$ converging to $x \in A$ and $\alpha\left(g x_{n}, g x_{n+1}\right) \geq 1$ for all $n \geq 0$, there exists a subsequence $\left\{x_{n(k)}\right\}$ of $\left\{x_{n}\right\}$ such that $\alpha\left(g x_{n(k)}, g x\right) \geq 1$ for all $k \geq 0$.

Proof. Following similar arguments to those given in proof of Theorem 13, we deduce that $\left\{g x_{n}\right\}$ and $\left\{x_{n}\right\}$ are Cauchy sequences in closed subset $A$ of $X$. So we obtain an $x$ in $A$ such that $\left\{x_{n}\right\} \rightarrow x$ and $\left\{g x_{n}\right\} \rightarrow g x$. We show that $x$ is a $g$-best proximity point of $T$.

Given that $(A, B, T, g)$ has the weak $P$-property of the second kind, for all $n, m \in \mathbb{N}$,

$$
\begin{gather*}
x_{m}, x_{m+1}, x_{n}, x_{n+1} \in A_{0}, \\
G\left(g x_{m+1}, T x_{m}, T x_{m}\right)=\Delta_{A B}^{G},  \tag{58}\\
G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}^{G}
\end{gather*}
$$

imply that

$$
\begin{equation*}
G\left(g x_{m+1}, g x_{n+1}, g x_{n+1}\right) \leq G\left(T x_{m}, T x_{n}, T x_{n}\right) \tag{59}
\end{equation*}
$$

It follows that $\left\{T x_{n}\right\}$ is also a Cauchy sequence in $B$. Hence, there is $z \in B$ such that $\left\{T x_{n}\right\} \rightarrow z$. Thus

$$
\begin{equation*}
G\left(g x_{n}, g x, g x\right) \longrightarrow 0, \quad G\left(T x_{n}, z, z\right) \longrightarrow 0 \tag{60}
\end{equation*}
$$

Since $G\left(g x_{n+1}, T x_{n}, T x_{n}\right)=\Delta_{A B}^{G}$ for all $n \geq 0$, we deduce that

$$
\begin{equation*}
G(g x, z, z)=\Delta_{A B}^{G} \tag{61}
\end{equation*}
$$

that is, $g x \in A_{0}$ and $z \in B_{0}$. Using condition $\left(g^{\prime}\right)$, we conclude that there exists a subsequence $\left\{x_{n(k)}\right\}$ of $\left\{x_{n}\right\}$ such that

$$
\begin{equation*}
\alpha\left(g x_{n(k)}, g x\right) \geq 1 \quad \forall k \geq 0 \tag{62}
\end{equation*}
$$

Note that

$$
\begin{align*}
0 \leq & G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G} \\
\leq & G\left(g x_{n(k)}, g x_{n(k)+1}, g x_{n(k)+1}\right) \\
& +G\left(g x_{n(k)+1}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G}  \tag{63}\\
= & G\left(g x_{n(k)}, g x_{n(k)+1}, g x_{n(k)+1}\right) .
\end{align*}
$$

Therefore

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left[G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G}\right]=0 . \tag{64}
\end{equation*}
$$

The first and the second arguments of

$$
\begin{align*}
& M^{g}\left(x_{n(k)}, x, x\right) \\
& =\max \left(G\left(g x_{n(k)}, g x, g x\right), G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)\right. \\
& \quad-\Delta_{A B}^{G}, G(g x, T x, T x)-\Delta_{A B}^{G}, \\
& \left.\quad \frac{G\left(g x_{n(k)}, T x, T x\right)+G\left(g x, T x_{n(k)}, T x_{n(k)}\right)}{2}-\Delta_{A B}^{G}\right) \tag{65}
\end{align*}
$$

tend to zero, while the last argument gives

$$
\begin{align*}
& \lim _{k \rightarrow \infty} \frac{G\left(g x_{n(k)}, T x, T x\right)+G\left(g x, T x_{n(k)}, T x_{n(k)}\right)}{2}-\Delta_{A B}^{G} \\
& \leq \lim _{k \rightarrow \infty}\left(G\left(g x_{n(k)}, T x, T x\right)+G\left(g x, g x_{n(k)+1}, g x_{n(k)+1}\right)\right. \\
& \\
& \left.\quad+G\left(g x_{n(k)+1}, T x_{n(k)}, T x_{n(k)}\right)\right) \times(2)^{-1} \\
& \\
& \quad-\Delta_{A B}^{G} \\
& =\lim _{k \rightarrow \infty}\left(G\left(g x_{n(k)}, T x, T x\right)+G\left(g x, g x_{n(k)+1}, g x_{n(k)+1}\right)\right. \\
& \left.\quad+\Delta_{A B}\right) \times(2)^{-1} \\
& \quad-\Delta_{A B}^{G}  \tag{66}\\
& = \\
& =\frac{G(g x, T x, T x)+0+\Delta_{A B}}{2}-\Delta_{A B}^{G} \\
& =
\end{align*}
$$

Therefore,

$$
\begin{equation*}
\lim _{k \rightarrow \infty} M^{g}\left(x_{n(k)}, x, x\right)=G(g x, T x, T x)-\Delta_{A B}^{G} . \tag{67}
\end{equation*}
$$

Suppose that $G(g x, T x, T x) \neq \Delta_{A B}^{G}$; that is,

$$
\begin{equation*}
t_{0}=G(g x, T x, T x)-\Delta_{A B}^{G}>0 \tag{68}
\end{equation*}
$$

Since the first and the second terms in (65) tend to zero, and the fourth term tends to $t_{0} / 2$, there exists $k_{0} \in \mathbb{N}$ such that

$$
\begin{equation*}
M^{g}\left(x_{n(k)}, x, x\right)=G(g x, T x, T x)-\Delta_{A B}^{G}=t_{0}>0 \quad \forall k \geq k_{0} \tag{69}
\end{equation*}
$$

Using the contractivity condition, we have

$$
\begin{aligned}
& G\left(T x_{n(k)}, T x, T x\right) \\
& \leq \alpha\left(g x_{n(k)}, g x, g x\right) G\left(T x_{n(k)}, T x, T x\right) \\
& \leq \varphi\left(M^{g}\left(x_{n(k)}, x, x\right)\right) \\
& \quad+\theta\left(G\left(g x, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G}\right. \\
& \quad G\left(g x_{n(k)}, T x, T x\right)-\Delta_{A B}^{G}, \\
& \left.\quad G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G}\right),
\end{aligned}
$$

$$
\begin{align*}
& G(g x, T x, T x)-\Delta_{A B}^{G} \\
& \qquad \begin{array}{l}
=\varphi\left(G(g x, T x, T x)-\Delta_{A B}^{G}\right) \\
\quad+\theta\left(G\left(g x, T x_{n(k)}, T x_{n(k)}\right)-\Delta_{A B}^{G}\right. \\
\quad G\left(g x_{n(k)}, T x, T x-\Delta_{A B}^{G}, G\left(g x_{n(k)}, T x_{n(k)}, T x_{n(k)}\right)\right. \\
\left.\left.\quad \quad-\Delta_{A B}^{G}, G(g x, T x, T x)-\Delta_{A B}^{G}\right)\right) .
\end{array}
\end{align*}
$$

Since the third argument of $\theta$ in (70) tends to zero and $\theta \in \Omega_{2}$, its limit as $k \rightarrow \infty$ is zero. Therefore, we have

$$
\begin{align*}
G(z, T x, T x) & =\lim _{k \rightarrow \infty} G\left(T x_{n(k)}, T x, T x\right)  \tag{71}\\
& \leq \varphi\left(G(g x, T x, T x)-\Delta_{A B}^{G}\right) .
\end{align*}
$$

As $G(g x, T x, T x)-\Delta_{A B}^{G}>0$, then $\varphi\left(G(g x, T x, T x)-\Delta_{A B}\right)<$ $G(g x, T x, T x)-\Delta_{A B}^{G}$. Thus,

$$
\begin{align*}
G & (z, T x, T x) \\
& \leq \varphi\left(G(g x, T x, T x)-\Delta_{A B}^{G}\right)<G(g x, T x, T x)-\Delta_{A B} \\
& \leq G(g x, z, z)+G(z, T x, T x)-\Delta_{A B}^{G} \\
& \leq \Delta_{A B}+G(g x, z, z)-\Delta_{A B}^{G} \\
& =G(z, T x, T x) \tag{72}
\end{align*}
$$

which is a contradiction. Hence $G(g x, T x, T x)=\Delta_{A B}$ and the result follows.
2.1. Uniqueness of $g$-Best Proximity Points. In this section, we study sufficient conditions in order to prove the uniqueness of $g$-best proximity point.

Definition 20. Let $T: A \rightarrow B, g: A \rightarrow A$, and $\alpha: X \times X \rightarrow$ $[0, \infty)$ be three mappings. A mapping $T$ is called $(\alpha, g)$ regular if, for all $x, y \in A_{0}$, such that $\alpha(g x, g y)<1$, there exists $z \in A_{0}$ such that $\alpha(g x, g z) \geq 1$ and $\alpha(g y, g z) \geq 1$.

Theorem 21. Under the hypothesis of Theorem 13, assume that $\theta \in \Theta$ and $T$ is $(\alpha, g)$-regular. Then for all $g$-best proximity points $x$ and $y$ of $T$ in $A_{0}$ we have that $g x=g y$. In particular, if $g$ is injective on the set of all $g$-best proximity points of $T$ in $A_{0}$, then $T$ has a unique $g$-best proximity point.

Proof. Let $x, y \in A_{0}$ be two $g$-best proximity points of $T$ in $A_{0}$. Since $G(g x, T x, T x)=G(g y, T y, T y)=\Delta_{A B}^{G}$ and $T$ is a $(\alpha, g)$-proximal and admissible, we deduce that

$$
\begin{equation*}
G(g x, g y, g y) \leq G(T x, T y, T y) . \tag{73}
\end{equation*}
$$

We always have $\alpha(g x, g y) \geq 1$ or $\alpha(g x, g y)<1$. If $\alpha(g x$, $g y) \geq 1$, then we obtain that

$$
\begin{align*}
& G(g x, g y, g y) \\
& \left.\qquad \begin{array}{l}
\leq G(T x, T y, T y) \leq \alpha(g x, g y) G(T x, T y, T y) \\
\leq \\
\quad \varphi\left(M^{g}(x, y, y)\right) \\
\quad \theta\left(G(g y, T x, T x)-\Delta_{A B}^{G},\right. \\
\quad G(g x, T y, T y)-\Delta_{A B}^{G}, G(g x, T x, T x)-\Delta_{A B}^{G}, \\
\quad \\
\quad G(g y, T y, T y)) \\
=
\end{array} \varphi^{( } M^{g}(x, y, y)\right) .
\end{align*}
$$

The last equality holds since $\theta \in \Theta$ and the last two arguments of $\theta$ are zero. Note that

$$
\begin{align*}
& \frac{G(g x, T y, T y)+G(g y, T x, T x)}{2}-\Delta_{A B}^{G} \\
& \quad \leq((G(g x, g y, g y)+G(g y, T y, T y) \\
& \quad \\
& \left.\quad+G(g y, g x, g x)+G(g x, T x, T x)) \times(2)^{-1}\right)-\Delta_{A B}^{G} \\
& = \\
& =\frac{G(g x, g y, g y)+\Delta_{A B}^{G}+G(g y, g x, g x)+\Delta_{A B}^{G}}{2}-\Delta_{A B}^{G}  \tag{75}\\
& = \\
& = \\
& =G(g x, g y, g y)+G(g y, g x, g x) \\
& 2
\end{align*}
$$

Hence

$$
\begin{align*}
& M^{g}(x, y, y) \\
& =\max \left(G(g x, g y, g y), G(g x, T x, T x)-\Delta_{A B}^{G},\right. \\
& \quad G(g y, T y, T y)-\Delta_{A B}^{G},  \tag{76}\\
& \\
& \left.\quad \frac{G(g x, T y, T y)+G(g y, T x, T x)}{2}-\Delta_{A B}^{G}\right) .
\end{align*}
$$

Therefore

$$
\begin{equation*}
G(g x, g y, g y) \leq \varphi\left(M^{g}(x, y, y)\right)=\varphi(G(g x, g y, g y)) \tag{77}
\end{equation*}
$$

gives the fact that $G(g x, g y, g y)=0$; that is, $g x=g y$.
Now, if $\alpha(g x, g y)<1$, then, by the $(\alpha, g)$-regularity of $T$, there exists $z_{0} \in A_{0}$ such that $\alpha\left(g x, g z_{0}\right) \geq 1$ and $\alpha\left(g y, g z_{0}\right) \geq 1$. Based on $z_{0}$, we define a sequence $\left\{z_{n}\right\}$ such that $\left\{g z_{n}\right\}$ converges to $g x$ and $g y$ which proves the uniqueness. First, we will prove that $\left\{g z_{n}\right\}$ converges to $g x$.

Indeed, $T z_{0} \in T A_{0} \subseteq B_{0}$ implies that $s_{0} \in A_{0}$ such that $G\left(s_{0}, T z_{0}, T z_{0}\right)=\Delta_{A B}^{G}$, and, for $s_{0} \in A_{0} \subseteq g A_{0}$, there is
$z_{1} \in A_{0}$ verifying $g z_{1}=s_{0}$. Therefore, $G\left(g z_{1}, T z_{0}, T z_{0}\right)=$ $\Delta_{A B}^{G}$. Following the similar arguments, there exists a sequence $\left\{z_{n}\right\} \subseteq A_{0}$ such that $G\left(g z_{n+1}, T z_{n}, T z_{n}\right)=\Delta_{A B}^{G}$ for all $n \geq 0$. In particular, $g z_{n+1} \in A_{0}$ and $T z_{n} \in B_{0}$. We claim that

$$
\begin{equation*}
\alpha\left(g x, g z_{n}\right) \geq 1 \quad \forall n \geq 0 . \tag{78}
\end{equation*}
$$

If $n=0, \alpha\left(g x, g z_{0}\right) \geq 1$ by the choice of $z_{0}$. Suppose that $\alpha\left(g x, g z_{n}\right) \geq 1$ for some $n \geq 0$. As $T$ is $(\alpha ; g)$-proximal and admissible, so we have

$$
\begin{align*}
& \alpha\left(g x, g z_{n}\right) \geq 1, \\
& G(g x, T x, T x)=\Delta_{A B}^{G},  \tag{79}\\
& G\left(g z_{n+1}, T z_{n}, T z_{n}\right)=\Delta_{A B}^{G} \\
& \quad x, z_{n}, z_{n+1} \in A_{0},
\end{align*}
$$

which imply that $\alpha\left(g x, g z_{n+1}\right) \geq 1$. Hence (78) holds. For all $n \geq 0$, we have

$$
\begin{align*}
& \frac{G\left(g x, T z_{n}, T z_{n}\right)+G\left(g z_{n}, T x, T x\right)}{2}-\Delta_{A B}^{G} \\
& \quad \leq\left(\left(G\left(g x, g z_{n+1}, g z_{n+1}\right)+G\left(g z_{n+1}, T z_{n}, T z_{n}\right)\right.\right. \\
& \quad \\
& \left.\left.\quad+G\left(g z_{n}, g x, g x\right)+G(g x, T x, T x)\right) \times(2)^{-1}\right)-\Delta_{A B}^{G} \\
& = \\
& \quad \frac{G\left(g x, g z_{n+1}, g z_{n+1}\right)+\Delta_{A B}+G\left(g z_{n}, g x, g x\right)+\Delta_{A B}}{2} \\
& \quad-\Delta_{A B}^{G}  \tag{80}\\
& = \\
& \quad \frac{G\left(g x, g z_{n+1}, g z_{n+1}\right)+G\left(g z_{n}, g x, g x\right)}{2} \\
& \quad \leq \max \left(G\left(g x, g z_{n}, g z_{n}\right), G\left(g x, g z_{n+1}, g z_{n+1}\right)\right),
\end{align*}
$$

which implies that

$$
\begin{align*}
& M^{g}\left(x, z_{n}, z_{n}\right) \\
& =\max \left(G\left(g x, g z_{n}, g z_{n}\right), G(g x, T x, T x)-\Delta_{A B}^{G},\right. \\
& \\
& \quad G\left(g z_{n}, T z_{n}, T z_{n}\right)-\Delta_{A B}^{G}, \\
&  \tag{81}\\
& \left.\quad \frac{G\left(g x, T z_{n}, T z_{n}\right)+G\left(g z_{n}, T x, T x\right)}{2}-\Delta_{A B}^{G}\right) \\
& \leq \max \left(G\left(g x, g z_{n}, g z_{n}\right), G\left(g x, g z_{n+1}, g z_{n+1}\right)\right) .
\end{align*}
$$

By weak $P$-property of the first kind,

$$
\begin{align*}
& G(g x, T x, T x)=\Delta_{A B} \\
& G\left(g z_{n+1}, T z_{n}, T z_{n}\right)=\Delta_{A B}^{G}  \tag{82}\\
& x, z_{n}, z_{n+1} \in A_{0}
\end{align*}
$$

imply that $G\left(g x, g z_{n+1}, g z_{n+1}\right) \leq G\left(T x, T z_{n}, T z_{n}\right)$.

For all $n \geq 0$, we have

$$
\begin{align*}
& G\left(g x, g z_{n+1}, g z_{n+1}\right) \\
& \leq G\left(T x, T z_{n}, T z_{n}\right) \\
& \leq \varphi\left(M^{g}\left(x, z_{n}, z_{n}\right)\right) \\
& +\theta\left(G\left(g z_{n}, T x, T x\right)-\Delta_{A B}^{G}, G\left(g x, T z_{n}, T z_{n}\right)-\Delta_{A B},\right. \\
& \left.G(g x, T x, T x)-\Delta_{A B}^{G}, G\left(g z_{n}, T z_{n}, T z_{n}\right)\right) \\
& \leq \varphi\left(M^{g}\left(x, z_{n}, z_{n}\right)\right) \\
& \leq \varphi\left(\max \left(G\left(g x, T z_{n}, T z_{n}\right), G\left(g x, g z_{n+1}, g z_{n+1}\right)\right)\right) . \tag{83}
\end{align*}
$$

Suppose that there is $n_{0} \in \mathbb{N}$ such that $g z_{n_{0}}=g x$. In this case, we have

$$
\begin{align*}
& G\left(g x, g z_{n+1}, g z_{n_{0}+1}\right) \\
& \quad \leq \varphi\left(\max \left(G\left(g x, T z_{n_{0}}, T z_{n_{0}}\right), G\left(g x, g z_{n_{0}+1}, g z_{n_{0}+1}\right)\right)\right), \tag{84}
\end{align*}
$$

but this is possible only when $G\left(g x, g z_{n_{0}+1}, g z_{n_{0}+1}\right)$; that is, $g z_{n_{0}+1}=g x$. Following the similar arguments, we have $g z_{n}=$ $g x$ for all $n \geq n_{0}$. Hence $\left\{g z_{n}\right\}$ converges to $g x$.

Suppose that $g z_{n} \neq g x$ for all $n \geq 0$; that is, $G\left(g x, g z_{n}, g z_{n}\right)>0$ for all $n \geq 0$. Suppose that

$$
\begin{align*}
& \max \left(G\left(g x, g z_{n}, g z_{n}\right), G\left(g x, g z_{n+1}, g z_{n+1}\right)\right) \\
& \quad=G\left(g x, g z_{n+1}, g z_{n+1}\right) \tag{85}
\end{align*}
$$

for some $n$. Then (83) would yield

$$
\begin{align*}
& G\left(g x, g z_{n+1}, g z_{n+1}\right) \\
& \quad \leq \varphi\left(\max \left(G\left(g x, g z_{n}, g z_{n}\right), G\left(g x, g z_{n+1}, g z_{n+1}\right)\right)\right) \\
& \quad=\varphi\left(G\left(g x, g z_{n+1}, g z_{n+1}\right)\right) \\
& \quad<G\left(g x, g z_{n+1}, g z_{n+1}\right), \tag{86}
\end{align*}
$$

which is a contradiction. Therefore, $\max \left(G\left(g x, g z_{n}, g z_{n}\right)\right.$, $\left.G\left(g x, g z_{n+1}, g z_{n+1}\right)\right)=G\left(g x, g z_{n}, g z_{n}\right)$; that is, for all $n \geq 0$,

$$
\begin{align*}
G\left(g x, g z_{n+1}, g z_{n+1}\right) & \leq \varphi\left(M^{g}\left(x, z_{n}, z_{n}\right)\right)  \tag{87}\\
& =\varphi\left(G\left(g x, g z_{n, g z_{n}}\right)\right)
\end{align*}
$$

Recursively, for all $n \geq 0$,

$$
\begin{align*}
& G\left(g x, g z_{n}, g z_{n}\right) \\
& \quad \leq \varphi\left(G\left(g x, g z_{n-1}, g z_{n-1}\right)\right) \\
& \quad \leq \varphi^{2}\left(G\left(g x, g z_{n-2}, g z_{n-2}\right)\right) \leq \cdots \leq \varphi^{n}\left(G\left(g x, g z_{0}, g z_{0}\right)\right) . \tag{88}
\end{align*}
$$

Fix $\epsilon>0$ arbitrary and consider $t_{0}=G\left(g x, g z_{0}, g z_{0}\right)>0$. Since $\varphi \in \Psi$, the series $\sum_{n \geq 1} \varphi^{n}\left(t_{0}\right)$ converges. In particular, there exists $m_{0} \in \mathbb{N}$ such that $\sum_{k=m_{0}^{\infty}} \varphi^{n}\left(t_{0}\right)<\epsilon$. More precisely, $\varphi^{n}\left(t_{0}\right)<\epsilon$ for all $n \geq m_{0}$. Therefore, if $n \geq m_{0}$, we have that

$$
\begin{equation*}
G\left(g x, g z_{n}, g z_{n}\right) \leq \varphi^{n}\left(G\left(g x, g z_{0}, g z_{0}\right)\right)=\varphi^{n}\left(t_{0}\right)<\epsilon . \tag{89}
\end{equation*}
$$

This means that $\left\{g x_{n}\right\}$ converges to $g x$. Similarly, it can be shown that $\left\{g x_{n}\right\}$ converges to $g y$ and this completes the proof.

## Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

## Acknowledgments

The third author was supported by the Commission on Higher Education, the Thailand Research Fund, and the King Mongkut's University of Technology Thonburi (Grant no. MRG550085).

## References

[1] M. A. Alghamdi, N. Shahzad, and F. Vetro, "Best proximity points for some classes of proximal contractions," Abstract and Applied Analysis, vol. 2013, Article ID 713252, 10 pages, 2013.
[2] M. Jleli, E. Karapınar, and B. Samet, "Best proximity points for generalized $\alpha-\psi$-proximal contractive type mappings," Journal of Applied Mathematics, vol. 2013, Article ID 534127, 10 pages, 2013.
[3] M. Jleli and B. Samet, "Best proximity points for $\alpha-\psi$ proximal contractive type mappings and applications," Bulletin des Sciences Mathématiques, vol. 137, no. 8, pp. 977-995, 2013.
[4] C. Mongkolkeha and P. Kumam, "Some common best proximity points for proximity commuting mappings," Optimization Letters, vol. 7, no. 8, pp. 1825-1836, 2013.
[5] C. Mongkolkeha and P. Kumam, "Best proximity point theorems for generalized cyclic contractions in ordered metric spaces," Journal of Optimization Theory and Applications, vol. 155, no. 1, pp. 215-226, 2012.
[6] C. Mongkolkeha and P. Kumam, "Best proximity points for asymptotic proximal pointwise weaker Meir-Keeler-type $\psi$ contraction mappings," Journal of the Egyptian Mathematical Society, vol. 21, no. 2, pp. 87-90, 2013.
[7] C. Mongkolkeha, Y. J. Cho, and P. Kumam, "Best proximity points for generalized proximal $C$-contraction mappings in metric spaces with partial orders," Journal of Inequalities and Applications, vol. 2013, article 94, 2013.
[8] C. Mongkolkeha, Y. J. Cho, and P. Kumam, "Best proximity points for Geraghty's proximal contraction mappings," Fixed Point Theory and Applications, vol. 2013, article 180, 2013.
[9] H. K. Nashine, P. Kumam, and C. Vetro, "Best proximity point theorems for rational proximal contractions," Fixed Point Theory and Applications, vol. 2013, article 95, 2013.
[10] S. S. Basha, "Best proximity points: global optimal approximate solutions," Journal of Global Optimization, vol. 49, no. 1, pp. 1521, 2011.
[11] J. Zhang, Y. Su, and Q. Cheng, "A note on "a best proximity point theorem for Geraghty-contractions,"' Fixed Point Theory and Applications, vol. 2013, article 99, 2013.
[12] Z. Mustafa and B. Sims, "A new approach to generalized metric spaces," Journal of Nonlinear and Convex Analysis, vol. 7, no. 2, pp. 289-297, 2006.
[13] Z. Mustafa and B. Sims, "Fixed point theorems for contractive mappings in complete $G$-metric spaces," Fixed Point Theory and Applications, vol. 2009, Article ID 917175, 10 pages, 2009.
[14] Z. Mustafa and B. Sims, "Some remarks concerning $D$-metric spaces," in Proceedings of the International Conference on Fixed Point Theory and Applications, pp. 189-198, Valencia, Spain, July 2003.
[15] Z. Mustafa, H. Obiedat, and F. Awawdeh, "Some fixed point theorem for mapping on complete $G$-metric spaces," Fixed Point Theory and Applications, vol. 2008, Article ID 189870, 12 pages, 2008.
[16] Z. Mustafa and B. Sims, "Fixed point theorems for contractive mappings in complete G-metric spaces," Fixed Point Theory and Applications, Art. ID 917175, 10 pages, 2009.
[17] Z. Mustafa, "Common fixed points of weakly compatible mappings in G-metric spaces," Applied Mathematical Sciences, vol. 6, no. 89-92, pp. 4589-4600, 2012.
[18] Z. Mustafa and B. Sims, "Fixed point theorems for contractive mappings in complete $G$-metric spaces," Fixed Point Theory and Applications, vol. 2009, Article ID 917175, 10 pages, 2009.
[19] Z. Mustafa and B. Sims, "Some remarks concerning $D$-metric spaces," in Proceedings of the International Conferenceon Fixed Point Theory and Applications, pp. 189-198, Valencia, Spain, 2003.
[20] R. Chugh, T. Kadian, A. Rani, and B. E. Rhoades, "Property P in G-metric spaces," Fixed Point Theory and Applications, vol. 2010, Article ID 401684, 12 pages, 2010.
[21] R. Saadati, S. M. Vaezpour, P. Vetro, and B. E. Rhoades, "Fixed point theorems in generalized partially ordered Gmetric spaces," Mathematical and Computer Modelling, vol. 52, no. 5-6, pp. 797-801, 2010.
[22] W. Shatanawi, "Fixed point theory for contractive mappings satisfying $\phi$-maps in $G$-metric spaces," Fixed Point Theory and Applications, vol. 2010, Article ID 181650, 9 pages, 2010.
[23] M. Abbas, S. H. Khan, and T. Nazir, "Common fixed points of $R$-weakly commuting maps in generalized metric spaces," Fixed Point Theory and Applications, vol. 2011, article 41, 2011.
[24] M. Abbas, A. R. Khan, and T. Nazir, "Coupled common fixed point results in two generalized metric spaces," Applied Mathematics and Computation, vol. 217, no. 13, pp. 6328-6336, 2011.
[25] M. Abbas, T. Nazir, and S. Radenović, "Some periodic point results in generalized metric spaces," Applied Mathematics and Computation, vol. 217, no. 8, pp. 4094-4099, 2010.
[26] M. Abbas, T. Nazir, and S. Radenović, "Common fixed point of generalized weakly contractive maps in partially ordered Gmetric spaces," Applied Mathematics and Computation, vol. 218, no. 18, pp. 9383-9395, 2012.
[27] M. Abbas and B. E. Rhoades, "Common fixed point results for noncommuting mappings without continuity in generalized metric spaces," Applied Mathematics and Computation, vol. 215, no. 1, pp. 262-269, 2009.
[28] H. Aydi, B. Damjanović, B. Samet, and W. Shatanawi, "Coupled fixed point theorems for nonlinear contractions in partially ordered G-metric spaces," Mathematical and Computer Modelling, vol. 54, no. 9-10, pp. 2443-2450, 2011.
[29] H. Aydi, W. Shatanawi, and C. Vetro, "On generalized weak Gcontraction mapping in $G$-metric spaces," Computers \& Mathematics with Applications, vol. 62, no. 11, pp. 4223-4229, 2011.
[30] Y. J. Cho, B. E. Rhoades, R. Saadati, and W. Shatanawi, "Nonlinear coupled fixed point theorems in ordered generalized metric spaces with integral type," Fixed Point Theory and Applications, vol. 2012, article 8, 14 pages, 2012.
[31] Z. Mustafa, F. Awawdeh, and W. Shatanawi, "Fixed point theorem for expansive mappings in $G$-metric spaces," International Journal of Contemporary Mathematical Sciences, vol. 5, no. 4952, pp. 2463-2472, 2010.
[32] Z. Mustafa, H. Aydi, and E. Karapınar, "On common fixed points in $G$-metric Spaces using (E.A) property," Computers \& Mathematics with Applications, vol. 64, no. 6, pp. 1944-1956, 2012.
[33] Z. Mustafa, M. Khandagji, and W. Shatanawi, "Fixed point results on complete $G$-metric spaces," Studia Scientiarum Mathematicarum Hungarica, vol. 48, no. 3, pp. 304-319, 2011.
[34] Z. Mustafa, H. Obiedat, and F. Awawdeh, "Some fixed point theorem for mapping on complete $G$-metric spaces," Fixed Point Theory and Applications, vol. 2008, Article ID 189870, 12 pages, 2008.
[35] Z. Mustafa, W. Shatanawi, and M. Bataineh, "Existence of fixed point results in G-metric spaces," International Journal of Mathematics and Mathematical Sciences, vol. 2009, Article ID 283028, 10 pages, 2009.
[36] H. Obiedat and Z. Mustafa, "Fixed point results on a nonsymmetric G-metric spaces," Jordanian Journal of Mathematics and Statistics, vol. 3, no. 2, pp. 65-79, 2010.
[37] B. Samet, C. Vetro, and F. Vetro, "Remarks on G-metric spaces," International Journal of Analysis, vol. 2013, Article ID 917158, 6 pages, 2013.
[38] W. Shatanawi, "Some fixed point theorems in ordered G-metric spaces and applications," Abstract and Applied Analysis, vol. 2011, Article ID 126205, 11 pages, 2011.
[39] W. Shatanawi and M. Postolache, "Some fixed-point results for a $G$-weak contraction in $G$-metric spaces," Abstract and Applied Analysis, vol. 2012, Article ID 815870, 19 pages, 2012.
[40] N. Hussain, A. Latif, and P. Salimi, "Best proximity point results in G-metric spaces," Abstract and Applied Analysis, vol. 2014, Article ID 837943, 8 pages, 2014.
[41] P. Kumam and A. F. Roldán López de Hierro, "On existence and uniqueness of $g$-best proximity points under $(\varphi, \theta, \alpha, g)$ contractivity conditions and consequences," Abstract and Applied Analysis, vol. 2014, Article ID 234027, 14 pages, 2014.

