Research Article

Convergence Properties and Fixed Points of Two General Iterative Schemes with Composed Maps in Banach Spaces with Applications to Guaranteed Global Stability

Manuel De la Sen¹ and Asier Ibeas²

¹ Institute of Research and Development of Processes, University of the Basque Country, Campus of Leioa (Bizkaia), P.O. Box 644, Barrio Sarriena, 48940 Leioa, Spain

² Department of Telecommunications and Systems Engineering, Universitat Autònoma de Barcelona (UAB), 08193 Barcelona, Spain

Correspondence should be addressed to Manuel De la Sen; manuel.delasen@ehu.es

Received 29 January 2014; Revised 27 May 2014; Accepted 28 May 2014; Published 22 June 2014

Academic Editor: Haydar Akca

Copyright © 2014 M. De la Sen and A. Ibeas. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

This paper investigates the boundedness and convergence properties of two general iterative processes which involve sequences of self-mappings on either complete metric or Banach spaces. The sequences of self-mappings considered in the first iterative scheme are constructed by linear combinations of a set of self-mappings, each of them being a weighted version of a certain primary self-mapping on the same space. The sequences of self-mappings of the second iterative scheme are powers of an iteration-dependent scaled version of the primary self-mapping. Some applications are also given to the important problem of global stability of a class of extended nonlinear polytopic-type parameterizations of certain dynamic systems.

1. Introduction

The problems of boundedness and convergence of sequences of iterative schemes are very important in numerical analysis and the numerical implementation of discrete schemes; see [1-4] and references therein. In particular, [1] describes in detail and with rigor the associated problems linked to the theory of fixed points in various types of spaces like metric spaces, complete and compact metric spaces, and Banach spaces, while it also contains, discusses, and compares results of a number of relevant background references on the subject. In other papers, related problems of fixed point theory or stability are focused on approximations including, in some cases, issues from a computational point of view eventually involving modified numerical methods like, for instance, Aitken's delta-squared methods or Steffensen's method [4–11]. Also, a counterpart theory has been also formulated in the framework of common fixed points and coincidence points for several mappings and in the framework of multivalued

functions. An important background on fixed, best proximity, and proximal points concerned with nonexpansive, contractive, weakly contractive, and strictly contractive mappings has been developed; see, for instance, [1-4, 8-25] and references therein. In particular, a relevant effort has been also focused on the formulations of extensions of the above problems to the study of existence and uniqueness of fixed and best proximity points in cyclic self-mappings as well to proximal contractions [12-14, 17-20, 24, 25] and to the characterization of approximate fixed and coincidence points [21, 22]. Direct applications of fixed point theory to the study of the stability of dynamic systems including the property of ultimate boundedness for the trajectory solutions having mixed nonexpansive and expansive properties through time or being subject to impulsive controls have been given in [21, 24, 25]. This paper is focused on the study of boundedness and convergence of sequences of distances and iterated points and the characterization of fixed points of a class of composite self-maps in metric spaces. Such maps are built with combinations of sets of elementary self-maps which can be expansive or nonexpansive and the last ones can be contractive (including the case of strict contractions). The composite maps are defined by switching rules which select some self-map (the "active" self-map) on a certain interval of definition of the running index of the sequence of iterates being built. The above-mentioned properties concerning the sequences of iterates being generated from given initial points are investigated under particular constraints for the switching rule. Note, on the other hand, that the properties of controllability, observability, and stability of differential or difference equations as well as the various kinds of dynamic systems are of a wide interest in theory and applications including the cases of presence of disturbances and/or unmodeled dynamics [23-45]; see, for instance, related problems associated with continuous-time, discrete-time, digital, and hybrid systems and those involving delayed dynamics [27, 30, 33, 37–39], hybrid [34-36, 41], and switched dynamic systems [31, 32, 38-43] and references therein. The above problems are often studied in an integrated or combined fashion in the sense that the presence of uncertainties of any nature (basically unmeasurable noise or unmodeled dynamics) is incorporated to the description of differential, difference, or hybrid systems with eventual external delays or delayed dynamics. The stability is studied with different tools as Lyapunov theory, matrix inequalities, or fixed point theory. Fractional calculus has also been widely used in the investigation of the solutions of differential, functional-differential, and dynamic systems; see, for instance, [44, 45] and some references therein.

This paper is firstly devoted to giving a framework for the contractive properties of two general iterative schemes which are constructed via combinations of elementary self-maps in appropriate metric or Banach spaces. The sequences of self-mappings of the first scheme are constructed by linear combinations of a set of self-mappings, each of them being a weighted version of a certain primary self-mapping on the same space. Such weights are nonnegative real sequences in general. The single parameterizations of the first iterative scheme include polytopic-type ones, where a set of real scalar sequences define both the sequence of self-mappings of interest and the individual parameterizations as a particular case. The second iterative scheme is a generalization of De Figueiredo scheme [8], where the sequences of self-mappings are integer powers of a scaled version of a primary elementary self-mapping. Such powers are iteration-dependent, while the scaling weights can be iteration-dependent. A second objective is to describe an application of the developed theoretical framework to study the stability properties of (in general) nonlinear switched dynamic systems under appropriate stabilizing switching rules. The obtained formal results can also be useful to investigate the stability of dynamic systems under combinations of single parameterizations.

1.1. Notation. $\{T_n\} \Rightarrow T^*$ (i.e., $\limsup_{n \to \infty} \{ \|T_n x - T^* x\| : x \in \text{Dom } T_n \} = 0; \forall x \in \text{Dom } T)$ and $\{T_n\} \to T^*$ (i.e., $\lim_{n \to \infty} T_n x = T^* x; \forall x \in \text{Dom } T_n)$ for $T^*, T_n : X \to X$, $\forall n \in \mathbb{Z}_{0+}$; denote, respectively, uniform and point-wise convergence in X of $T_n : X \to X$ to $T^* : X \to X$ provided that all of them have the same domain.

Fix(*T*) denotes the set of fixed points of $T: X \to X$ and $\overline{k} = \{0, 1, \dots, k\}.$

2. Iterative Scheme 1

Consider the following iterative scheme under a sequence of self-mappings $T_n: X \to X, \forall n \in \mathbb{Z}_{0+}$, on a vector space X:

$$x_{n+1} = T_n x_n = \sum_{i=0}^k \alpha_i^{(n)} T^i x_n, \quad \forall n \in \mathbb{Z}_{0+},$$
(1)

for any given $x_0 \in X$ with $T: X \to X$ and $T_n: X \to X, \forall n \in \mathbb{Z}_{0+}$, being defined by $T_n x = (\sum_{i=0}^k \alpha_i^{(n)} T^i) x$ for any $x \in X$ and the nonnegative real parameterization sequences being subject to $\sum_{i=0}^k \alpha_i^{(n)} > 0, \forall i \in \overline{k} = \{0, 1, \dots, k\}, \forall n \in \mathbb{Z}_{0+}.$

Theorem 1. Consider the iterative scheme (1) on a vector space X, with $0 \in X$, under the following assumptions.

- (1) Either (X, ||||) is a normed space endowed with a norm |||| or, respectively, (X, d) is a metric space endowed with a homogeneous translation-invariant metric $d : X \times X \rightarrow \mathbf{R}_{0+}$.
- (2) $\sum_{i=0}^{k} \alpha_{i}^{(n)} > 0$ and $0 \le \alpha_{i}^{(n+1)} = (1 + \tilde{\alpha}_{i}^{(n)})\alpha_{i}^{(n)}, \forall i \in \overline{k} = \{0, 1, \dots, k\}, \forall n \in \mathbb{Z}_{0+}, and \inf_{n \in \mathbb{Z}_{0+}} \max_{1 \le i \le k} \alpha_{i}^{(n)} > 0,$ with the nonnegative real sequences $\{\alpha_{i}^{(n)}\}, \forall i \in \overline{k},$ being subject to the constraints $|\tilde{\alpha}_{i}^{(n)}| \le \tilde{\alpha}_{n} \le m_{n}(d(x_{n}, x_{n+1})/d(x_{n+1}, 0))$ and $m_{n} = o[d(x_{n+1}, 0)], \forall i \in \overline{k}, \forall n \in \mathbb{Z}_{0+},$ where the relative one-step increment parameterization sequences are $\tilde{\alpha}_{i}^{(n)} = (\alpha_{i}^{(n+1)} - \alpha_{i}^{(n)})/\alpha_{i}^{(n)},$ $\forall i \in \overline{k}, \forall n \in \mathbb{Z}_{0+}.$
- (3) $T: X \to X$ possesses the (nonnecessarily contractive) condition $d(Tx, Ty) \leq Kd(x, y), \forall x, y \in X$, for some $K \in \mathbf{R}_+$.
- (4) $(1 + m_n)(\sum_{i=0}^k \alpha_i^{(n)} K^i) \le \rho < 1, \forall n \in \mathbb{Z}_{0+}.$

Then, the following properties hold.

- (i) There exists the limit $\lim_{n\to\infty} d(x_n, x_{n+1}) = 0$ for any given initial point $x_0 \in X$ of the iterative scheme (1) and the sequence $\{x_n\}$ is bounded.
- (ii) If, in addition, {T_n} ⇒ T* for some limit T* : X → X and if either (X, ||||) is a Banach space or (X, d) is complete, then {x_n} is a Cauchy sequence and thus convergent to some z in X which is the unique fixed point of T* : X → X and thus independent of the initial point x₀ ∈ X of the iterative scheme (1). All the self-mappings of the sequence {T_n} as well as T* : X → X are strict contractions.
- (iii) If either (X, ||||) is a Banach space or (X, d) is complete and {α_i⁽ⁿ⁾} → α_i as n → ∞, ∀i ∈ k̄, for some selfmapping T* on X, then there is a unique z* ∈ Fix(T*) in X such that z* = z for any given initial point x₀ ∈ X of the iterative scheme (1). Also, T* : X → X is a strict contraction and thus a strict Picard self-mapping with a unique fixed point z* (=z) ∈ X such that T*ⁿx₀ → z*,

 $\widehat{T}_n x_0 \to z^* \text{ as } n \to \infty \text{ for any given initial point } x_0 \in X, \text{ where } \widehat{T}_n : \mathbf{Z}_{0+} \times X \to X \text{ is the composite mapping } \widehat{T}_n = T_n T_{n-1} \cdots T_0, \forall n \in \mathbf{Z}_{0+}.$

(iv) The "a priori" and "a posteriori" error estimates and the convergence rate are, respectively, given by the subsequent relations:

$$d\left(x_{n},z\right) \leq \frac{\rho^{n}}{1-\rho}d\left(x_{0},x_{1}\right),$$
(2)

$$d(x_n, z) \le \frac{\rho}{1-\rho} d(x_{n-1}, x_n), \qquad (3)$$

$$d(x_n, z) \le \rho^n d(x_0, z).$$
(4)

Proof. Define the (k + 1) error sequences $\{\widetilde{\alpha}_i^{(n)}\}$ by $\widetilde{\alpha}_i^{(n)} = \alpha_i^{(n+1)} - \alpha_i^{(n)}, \forall i \in \overline{k} = \{0, 1, ..., k\}, \forall n \in \mathbb{Z}_{0+}.$ If $(X, \|\|)$ is a normed space, then there is always a metric-induced norm $d(x, y) = \|x - y\|, \forall x, y \in X$. On the other hand, if (X, d) is a metric space endowed with a homogeneous translation-invariant metric $d : X \times X \to \mathbb{R}_{0+}$ then there is a metric-induced norm $\|x\| = d(x, 0), \forall x, y \in X$. Both spaces $(X, \|\|)$ and (X, d) are formally identical and they can both deal with a metric-induced norm by using the standard metric properties. Thus, one gets via recursive calculations that

$$d(x_{n+2}, x_{n+1}) = d\left(\sum_{i=0}^{k} \left(\alpha_{i}^{(n)}T^{i}x_{n+1} + \tilde{\alpha}_{i}^{(n)}T^{i}x_{n+1}\right), \\ \sum_{i=0}^{k} \alpha_{i}^{(n)}T^{i}x_{n}\right) \\ \leq d\left(\alpha_{0}^{(n)}x_{n+1}, \alpha_{0}^{(n)}x_{n}\right) \\ + d\left(\alpha_{1}^{(n)}Tx_{n+1}, \alpha_{1}^{(n)}Tx_{n}\right) \\ + d\left(\sum_{i=2}^{k} \alpha_{i}^{(n)}T^{i}x_{n+1}, \sum_{i=2}^{k} \alpha_{i}^{(n)}T^{i}x_{n}\right) \\ + d\left(\tilde{\alpha}_{0}^{(n)}x_{n+1}, 0\right) + d\left(\tilde{\alpha}_{1}^{(n)}Tx_{n+1}, 0\right)$$
(5)
$$+ d\left(\sum_{i=2}^{k} \tilde{\alpha}_{i}^{(n)}T^{i}x_{n+1}, 0\right) \\ \leq \dots \leq \sum_{i=0}^{k} d\left(\alpha_{i}^{(n)}T^{i}x_{n+1}, \alpha_{i}^{(n)}T^{i}x_{n}\right) \\ + \sum_{i=0}^{k} d\left(\tilde{\alpha}_{i}^{(n)}T^{i}x_{n+1}, 0\right) \\ \leq (1 + m_{n}) \left(\sum_{i=0}^{k} \alpha_{i}^{(n)}K^{i}\right) d(x_{n}, x_{n+1}); \\ \forall n \in \mathbb{Z}_{0+}.$$

Thus,

$$d\left(x_{n+1}, x_{n}\right)$$

$$\leq \left(\prod_{j=0}^{n-1} \left[\left(1+m_{j}\right)\left(\sum_{i=0}^{k} \alpha_{i}^{(j)} K^{i}\right)\right]\right) d\left(T_{0} x_{0}, x_{0}\right) \quad (6)$$

$$\leq \rho d\left(x_{n}, x_{n-1}\right) \leq \rho^{n} d\left(x_{1}, x_{0}\right); \quad \forall n \in \mathbb{Z}_{+},$$

so that $\lim_{n\to\infty} d(x_n, x_{n+1}) = 0$ for any given $x_0 \in X$. It follows from (6) that, for any given initial $x_0 \in X$,

$$d(x_{n}, x_{0}) \leq \sum_{j=0}^{n-1} d(x_{j+1}, x_{j}) \leq \frac{1-\rho^{n}}{1-\rho} d(T_{0}x_{0}, x_{0}) < +\infty,$$

$$\limsup_{n \to \infty} d(x_{n}, x_{0}) \leq d(x_{1}, x_{0}) \left(\sum_{j=0}^{\infty} \rho^{j}\right)$$

$$\leq \frac{d(T_{0}x_{0}, x_{0})}{1-\rho} < +\infty,$$
(7)

since $\rho < 1$ so that $\{x_n\}$ is bounded for any given $x_0 \in X$ and $\{d(x_{n+1}, x_n)\} \rightarrow 0$ from (6). All the self-mappings $T_n : X \rightarrow X$, $\forall n \in \mathbb{Z}_{0+}$, are strict contractions by construction from assumption 4. On the other hand, note that, since $\{T_n\} \Rightarrow T^*$, one gets

$$d(T^*x, T^*y) = \lim_{n \to \infty} d(T_n x, T_n y)$$
$$= d\left(\lim_{n \to \infty} (T_n) x, \lim_{n \to \infty} (T_n) x\right)$$
(8)
$$\leq \rho d(x, y); \quad \forall x, y \in X,$$

so that $T^*: X \to X$ is a strict contraction. Since $T_n: X \to X$, $\forall n \in \mathbb{Z}_{0+}$, are all strict ρ -contractions, $\{T_n\} \Rightarrow T^*$, Fix $(T^*) = \{z\}$, and Fix $(T_n) = \{z_n\}$, $\forall n \in \mathbb{Z}_{0+}$, so that $d(T_nx, T^*x) < \varepsilon(1-\rho), \forall x \in X$, so that

$$d(z_n, z) = d(T_n z_n, T^* z)$$

$$\leq d(T_n z_n, T^* z_n) + d(T^* z_n, T^* z) \qquad (9)$$

$$< \varepsilon (1 - \rho) + \rho d(z_n, z),$$

and then $d(z_n, z) < \varepsilon$, $\forall n \ge n_0$, so that $\{z_n\} \to z$. Also, $\{d(T_nx_n, x_n)\} \to 0$ from (6) implies $\{d(T_nx_n, z_n)\} \to 0$ and $\{T_nz_n\} \to \{T_nz\}$ (since $\{T_nx_n\} \to z_n$ and $\{z_n\} \to z$ with Fix $(T_n) = \{z_n\}, \forall n \in \mathbb{Z}_{0+}$), $\{d(T_nx_n, z)\} \to 0, \{T_nx_n\} \to z$ (since $\{z_n\} \to z$), and $\{T_nx_n\} \to \{T^*x_n\}$ (since $\{T_n\} \rightrightarrows T^*$). Thus, it follows that $\{T^*x_n\} \to T^*z$ (=z) which implies that $\{x_n\} \to z$. Also, $\{x_n\}$ is a Cauchy sequence convergent to $z \in X$ if $(X, \|\|)$ is a Banach space and if (X, d) is a complete metric space, respectively.

On the other hand, $x_{n+1} = T_n x_n = \hat{T}_n x_0 \rightarrow z \ (\in X)$ as $n \rightarrow \infty, \forall x_0 \in X$, where $\hat{T}_n : \mathbb{Z}_{0+} \times X \rightarrow X$ is the composite mapping $\hat{T}_n = T_n T_{n-1} \cdots T_0, \forall n \in \mathbb{Z}_{0+}$. From (6), the self-mappings $T_n : X \rightarrow X, \forall n \in \mathbb{Z}_+$, are all strict contractions. Now, we prove that the limit point z is independent of

the initial condition x_0 and thus unique. Assume two distinct initial values $x_0, y_0 \in X$ such that $\hat{T}_n x_0 \rightarrow z(=z(x_0))$, $\hat{T}_n y_0 \rightarrow \omega(=\omega(y_0))$ as $n \rightarrow \infty$ for some $z, \omega(\neq z) \in X$. Note from (6) that, since $\rho \in (0, 1)$ is independent of the sequences $\{\hat{T}_n x_0\}$ and $\{\hat{T}_n y_0\}$, one gets

$$d\left(\widehat{T}_{n}x_{0},\widehat{T}_{n}y_{0}\right) \leq \rho^{n}d\left(x_{0},y_{0}\right); \quad \forall n \in \mathbb{Z}_{+};$$

$$\lim_{n \to \infty} d\left(\widehat{T}_{n}x_{0},\widehat{T}_{n}y_{0}\right) = 0.$$
 (10)

Since $\omega \neq z$, one has the following from the triangle inequality:

$$0 < d(\omega, z) \le d\left(\widehat{T}_n y_0, \widehat{T}_n x_0\right) \le d\left(\omega, \widehat{T}_n y_0\right) + d\left(\widehat{T}_n x_0, \widehat{T}_n y_0\right) + d\left(\widehat{T}_n x_0, z\right); \quad \forall n \in \mathbf{Z}_+,$$
(11)

and then one gets the contradiction below to the assumption $\omega \neq z$:

$$0 < \lim_{n \to \infty} \left[d\left(\omega, \widehat{T}_n y_0\right) + d\left(\widehat{T}_n x_0, \widehat{T}_n y_0\right) + d\left(\widehat{T}_n x_0, z\right) \right] = 0,$$
(12)

so that $\omega = z$ and $\hat{T}_n x_0 \rightarrow z$ as $n \rightarrow \infty$ with z being independent of the initial point x_0 of the iterative scheme (1). Hence, properties (i)-(ii) have been proven.

To prove property (iii), note that the assumption of uniform convergence $\{T_n\} \Rightarrow T^*$ in X is weakened to point-wise convergence $\{T_n\} \to T^*$ in X since $\{\alpha_i^{(n)}\} \to \alpha_i$ and then $\{\tilde{\alpha}_i^{(n)}\} \to 0; \forall i \in \overline{k} \text{ and } T^* : X \to X \text{ is a } \rho\text{-contraction from assumption 4. Thus, <math>\{d(x_{n+1}, x_n)\} \to 0 \text{ implies } \{d(T_n x_n, z)\} \to 0 \text{ and } \{x_n\} \to z \text{ implies } \{T_n x_n\} \to T^* z(=).$ Since (X, d) is complete and $T_n : X \to X$ is a strict contraction then T^* is also a strict contraction and thus a strict Picard self-mapping on X and there is a unique $z^* \in \text{Fix}(T^*)$ in X. Assume that $\widehat{T}_n x_0 \to z$ as $n \to \infty$ for any given $x_0 \in X$ and $z^* \neq z$. Take the sequence $\{T_n x_n\} \equiv \{\widehat{T}_n x_0\}$. Define $\delta T_n = \widehat{T}_n - T^{*n+1}$ by $(\delta T_n)x = (\widehat{T}_n - T^{*n+1})x$ for $x \in X$. Then, note that

$$d\left(\hat{T}_{m+n}x_{n+1}, T^{*^{n+m+1}}z^{*}\right)$$

= $d\left(\hat{T}_{m}x_{n+1}, T^{*^{m+1}}z^{*}\right)$
= $d\left(\left[T^{*^{m+1}} + \delta T_{m}\right]x_{n+1}, T^{*^{m+1}}z^{*}\right)$
 $\leq d\left(T^{*^{m+1}}x_{n+1}, T^{*^{m+1}}z^{*}\right) + \left\|\left(\delta T_{m}\right)x_{n+1}\right\|,$ (13)

and since $\{x_n\}$ is bounded, $T^{*m}z^* = z^*$, $\delta T_m \to 0$ as $m \to \infty$, $x_m \to z$, $T^{*m}x_n \to z^*$, and $T^{*m}z \to z^*$ as $m \to \infty$ then the following contradiction holds if $z^* \neq z$:

$$\lim_{n,m\to\infty} d\left(T^{*m+1}x_{n+1}, T^{*m+1}z^{*}\right) + \lim_{n,m\to\infty} \left\| \left(\delta T_{m}\right)x_{n+1} \right\| = 0$$

$$\geq \lim_{n,m\to\infty} d\left(\widehat{T}_{m+n}x_{n+1}, T^{*n+m+1}z^{*}\right) = d\left(\lim_{n,m\to\infty}\widehat{T}_{m+n}x_{n+1}, z^{*}\right) = d\left(z, z^{*}\right) > 0,$$
(14)

and then $z^* = z$. As a result, $T^* : X \to X$ is a strict contraction and thus a strict Picard self-mapping with a unique fixed point $z^* \in X$ such that $T^{*n}x_0 \to z^*$ and $\hat{T}_nx_0 \to z^*$ as $n \to \infty$ for any given initial point $x_0 \in X$, where $\hat{T}_n : \mathbb{Z}_{0+} \times X \to X$ is the composite mapping $\hat{T}_n = T_n T_{n-1} \cdots T_0$, $\forall n \in \mathbb{Z}_{0+}$.

Property (iv) is well known for Picard iterations. \Box

Remark 2. Note that the parameterization sequences $0 \le \alpha_i^{(n)} \le 1$, $\forall i \in \overline{k} = \{0, 1, \dots, k\}$, $\forall n \in \mathbb{Z}_{0+}$, are not necessarily constant in Theorem 1 and $\alpha_1^{(n)}$ can be zero for some $n \in \mathbb{Z}_{0+}$ and the positive amount $\sum_{i=0}^{n} \alpha_i^{(n)}$ is not necessarily identically equal to one. Furthermore, the constant *K* can be equal to or greater than unity in assumption 3 of Theorem 1. Thus, the iterative scheme generalizes that proposed and analyzed by Cho et al. [1].

Remark 3. Note also that if $\{T_n\} \to T^*$ (or if the stronger condition $\{T_n\} \Rightarrow T^*$ holds) then $T^{*n}x_0 \to z^* (\in \operatorname{Fix}(T^*) =$ $\{z^*\}$) and $\widehat{T}_n x_0 \to z^*$ as $n \to \infty$ irrespective of the given $x_0 \in X$. However, if the property $(T_n - T^*) \to 0$ as $n \to \infty$ does not hold then $T_m^n x_0 \to z_m (\in \operatorname{Fix}(T_m^n) = \{z_m\})$ as $n \to \infty, \forall m \in \mathbb{Z}_{0+}$, for the given $x_0 \in X$ since all the self-mappings T_m on X are strict contractions but z_m can be distinct of z^* .

The following result relaxes condition (3) of strict contraction mappings in the sequence $\{T_n\}$ of Theorem 1 to weaker condition in terms of those mappings to be contractive in compact metric spaces.

Theorem 4. Consider the iterative scheme (1) on a compact metric space (X, d) endowed with a homogeneous translationinvariant metric $d:X \times X \rightarrow \mathbf{R}_{0+}$, where X is a vector space, with $0 \in X$, under the following assumptions:

- (1) $\sum_{i=0}^{k} \alpha_{i}^{(n)} > 0, \ \alpha_{i}^{(n)} \ge 0, \ \forall i \in \overline{k} = \{0, 1, \dots, k\}, \ \forall n \in \mathbb{Z}_{0+}, \ and \ \inf_{n \in \mathbb{Z}_{0+}} \max_{1 \le i \le k} \alpha_{i}^{(n)} > 0, \ with \ the \ nonnegative \ real sequences \ \{\alpha_{i}^{(n)}\}, \ \forall i \in \overline{k}, \ and \ \{m_{n}\} \ being \ subject$ to the constraints $\alpha_{i}^{(n+1)} = (1 + \widetilde{\alpha}_{i}^{(n)})\alpha_{i}^{(n)}, \ |\widetilde{\alpha}_{i}^{(n)}| \le \widetilde{\alpha}_{n} \le m_{n}(d(x_{n}, x_{n+1})/d(x_{n+1}, 0)) \ and \ m_{n} = o[d(x_{n+1}, 0)], \ \forall i \in \overline{k}, \ \forall n \in \mathbb{Z}_{0+}, \ where \ \widetilde{\alpha}_{i}^{(n)} = (\alpha_{i}^{(n+1)} \alpha_{i}^{(n)})/\alpha_{i}^{(n)}, \ \forall i \in \overline{k}, \ \forall n \in \mathbb{Z}_{0+}.$
- (2) $T: X \to X$ possesses the weak contractive condition $d(Tx,Ty) < d(x, y), \forall x, y(\neq x) \in X.$
- (3) $(1 + m_n)(\sum_{i=0}^k \alpha_i^{(n)}) < 1, \forall n \in \mathbb{Z}_{0+}.$

Then, the following properties hold.

- (i) There exists lim_{n→∞}d(x_n, x_{n+1}) = 0 for any given initial point x₀ ∈ X of the iterative scheme (1).
- (ii) If, in addition, {T_n} ⇒ T* for some limit T*:X → X and Fix(T_n) = {z_n*}, ∀n ∈ Z₀₊, then the iterated sequence {x_n} is a Cauchy sequence and thus convergent to some z in X. All the self-mappings of the sequence {T_n} as well as T*: X → X are contractive.

(iii) If {T_n} → T* for some point-wise limit self-mapping T* on X, then there is a unique z* ∈ Fix(T*) in X such that z* = z to which any sequence {x_n} of the iterative scheme (1) converges for any given initial point x₀ ∈ X. Also, T*: X → X is a contractive and thus a Picard self-mapping with a unique fixed point z*(=z) ∈ X such that T*ⁿx₀ → z*, T̂_nx₀ → z* as n → ∞ for any given initial point x₀ ∈ X, where T̂_n: Z₀₊×X → X is the composite mapping T̂_n = T_nT_{n-1}···T₀, ∀n ∈ Z₀₊.

Proof. Note that a metric space is compact if and only if it is complete and totally bounded. Note also that (X, |||) is a Banach space formally identical to the compact (and then complete) metric space (X, d) when endowed with a homogeneous and translation-invariant metric $d: X \times X \to \mathbf{R}_{0+}$ if ||| is the norm-induced metric. Thus, one concludes that

$$d(x_{n+1}, x_n) < d(x_n, x_{n-1}) < \dots < d(x_1, x_0); \quad \forall n \in \mathbb{Z}_+,$$
(15)

which implies that $\{d(x_{n+1}, x_n)\}$ is a convergent sequence with $\lim_{n\to\infty} d(x_n, x_{n+1}) = 0$ for any given $x_0 \in X$. Hence, property (i) follows. On the other hand, since the metric space (X, d) is a compact metric space (and thus complete) then the iterated sequence $\{x_n\}$, with $x_{n+1} = T_n x_n$ and the point-wise convergence of $\{T_n\}$ to $T^* : X \to X$, is a Cauchy sequence $\{T_n\} \Rightarrow T^*$ and $\operatorname{Fix}(T_n) = \{z_n^*\}, \forall n \in \mathbb{Z}_{0+}$. Assume that $\{z_n^*\} \to z^*$ is untrue. Then,

$$d(z_{n}^{*}, z) = d(T_{n}z_{n}^{*}, T^{*}z)$$

$$\leq d(T_{n}z_{n}^{*}, T^{*}z_{n}^{*}) + d(T^{*}z_{n}^{*}, T^{*}z)$$

$$= d(T_{n}z_{n}^{*} - T^{*}z_{n}^{*}, 0) + d(T^{*}z_{n}^{*}, T^{*}z)$$

$$< d(T_{n}z_{n}^{*} - T^{*}z_{n}^{*}, 0) + d(z_{n}^{*}, z)$$
(16)

so that the contradiction $0 = \lim \inf_{n \to \infty} d(T_n z_n^* - T^* z_n^*, 0) > 0$ since the metric is homogeneous and translation-invariant, $\{T_n\} \Rightarrow T^*$, so that $T_n z_n^* \to T^* z_n^*$ as $n \to \infty$ since $z_n^* \in X$, and $T^*: X \to X$ is contractive. Hence, $\{z_n^*\} \to z$ for some z in X and any given $x_0 \in X$, all the self-mappings $T_n : X \to X$; $\forall n \in \mathbb{Z}_{0+}$ in the sequence $\{T_n\}$ are contractive, and then Picard mappings (since (X, d) is a compact metric space) so that the composite mapping $\hat{T}_n: X \to X$ is also a Picard mapping. As a result, $\hat{T}_n x_0 \to z^*$ as $n \to \infty$ for any given initial point $x_0 \in X$ and $T_n^m x_0 \to z_n^*$ as $m \to \infty$, $\forall n \in \mathbb{Z}_{0+}, \forall x_0 \in X$ with $\operatorname{Fix}(T_n) = \{z_n\}, \forall n \in \mathbb{Z}_{0+}, \operatorname{for any} T_n(:X \to X) \in \{T_n\}$. If $\{T_n\} \to T^*$ then $T^* n x_0 \to z^*$, $\hat{T}_n x_0 \to z^*$ as $n \to \infty$, and $\operatorname{Fix}(T^*) = \{z^*\}$. Hence, properties (ii)-(iii) have been proven.

Remark 5. Note that a metric space is compact if and only if it is complete and totally bounded. Equivalently, a metric space is compact if and only if every family of closed subsets of *X* with the finite intersection property (i.e., the intersection of any finite collection of sets in the family is nonempty) has a nonempty intersection.

An extension of Theorem 1 follows below by admitting the failure of the contractive condition of assumption 4 of

Theorem 1 within connected subsets of finite length of Z_{0+} which are adjacent to connected subsets where the contractive condition holds.

Theorem 6. Consider the iterative scheme (1) on a vector space X under the assumptions (1)–(3) and (5) of Theorem 1 and, furthermore,

$$\prod_{n=0}^{m_j} \left[(1+m_n) \left(\sum_{i=0}^k \alpha_i^{(n)} K^i \right) \right] \le \rho < 1;$$

$$\forall p_j \in S \subseteq \mathbf{Z}_{0+}, \quad \forall j \in \mathbf{Z}_{0+},$$
(17)

where $S = \{p_k : k \in \mathbb{Z}_{0+}\}$ is a strictly increasing sequence of nonnegative integer numbers subject to $p_0 \le p^* < +\infty$ and $p_{k+1} - p_k \le p < +\infty, \forall k \in \mathbb{Z}_{0+}.$

- (i) There exists the limit $\lim_{n\to\infty} d(x_n, x_{n+1}) = 0$ for any given initial point $x_0 \in X$ of the iterative scheme (1) and the sequence $\{x_n\}$ is bounded.
- (ii) If, in addition, {T_n} ⇒ T* for some limit self-mapping T* : X → X and if either (X, |||) is a Banach space or (X, d) is complete, then {x_n} is a Cauchy sequence and thus convergent to some z in X which is unique and thus independent of the initial point x₀ ∈ X of the iterative scheme (1). Also, all the self-mappings in the sequence {T_n} and T* : X → X are strict contractions.
- (iii) If either (X, ||||) is a Banach space or (X, d) is complete and {T_n} → T* as n → ∞ for some self-mapping T* on X, then there is a unique z* ∈ Fix(T*) in X such that z* = z for any given initial point x₀ ∈ X of the iterative scheme (1). Also, T* : X → X is a strict contraction and thus a strict Picard self-mapping with a unique fixed point z*(=z) ∈ X such that T*ⁿx₀ → z*, T̂_nx₀ → z* as n → ∞ for any given initial point x₀ ∈ X, where T̂_n: Z₀₊×X → X is the composite mapping T̂_n = T_nT_{n-1}···T₀, ∀n ∈ Z₀₊.
- (iv) The "a priori" and "a posteriori" error estimates and the convergence rate are, respectively, given by the subsequent relations:

$$d(x_{p_{n}},z) \leq \frac{\rho^{n}}{1-\rho}d(x_{p_{0}},x_{p_{1}}) \leq \frac{M\rho^{n}}{1-\rho}d(x_{0},x_{1});$$

$$d(x_{p_{n}+j},z) \leq \frac{M^{2}\rho^{n}}{1-\rho}d(x_{0},x_{1}),$$

$$d(x_{p_{n}},z) \leq \frac{\rho}{1-\rho}d(x_{p_{n-1}},x_{p_{n}}) \leq \frac{M\rho}{1-\rho}d(x_{0},x_{1});$$

$$d(x_{p_{n}+j},z) \leq \frac{M^{2}\rho}{1-\rho}d(x_{0},x_{1}),$$

$$d(x_{p_{n}},z) \leq \rho^{n}d(p_{n_{0}},z) \leq M\rho^{n}d(p_{n_{0}},z);$$

$$d(x_{p_{n}+j},z) \leq M^{2}\rho^{n}d(x_{0},x_{1}),$$
(18)

for some $M \in \mathbf{R}_+$ and any integer $j \in (1, p_{n+1} - p_n), \forall n \in \mathbf{Z}_{0+}$.

Proof. Note from (17) and (6) that since $p_k \to \infty$ as $k \to \infty$, one gets

$$d\left(x_{p_{k+1}+1}, x_{p_{k+1}}\right) \le \rho d\left(x_{p_{k+1}}, x_{p_k}\right); \quad \forall p_k \in S,$$
(19a)

$$d\left(x_{p_{k+2}}, x_{p_{k+1}}\right) \le \left(1 + L + \dots + L^{p-1}\right) \rho d\left(x_{p_{k+1}}, x_{p_k}\right)$$

$$\le \rho_0^{k+1} d\left(x_{p_0}, x_{p_1}\right),$$
(19b)

and, provided that $\rho \in (0, 1)$ is small enough for the given $p \in \mathbb{Z}_+$ so that $\rho_0 = \rho(1 + L + \dots + L^{p-1}) < 1, d(x_{p_{k+2}}, x_{p_{k+1}}) \rightarrow 0$ as $k \rightarrow \infty$ for any given $x_0 \in X$. Then, $\{d(x_{p_{k+1}}, x_{p_k})\}$ is a convergent sequence with $\lim_{k \rightarrow \infty} d(x_{p_{k+1}}, x_{p_k}) = \lim_{p_k \rightarrow \infty} d(x_{p_{k+1}}, x_{p_k}) = 0$ for any given $x_0 \in X$. It follows from (19a), (19b), since $p_1 \leq \overline{p} + p < +\infty$ and $p_{k+1} - p_k \leq p < +\infty$, that for any given initial $x_0 \in X$,

$$d\left(x_{p_{k}}, x_{p_{0}}\right) \leq \frac{1-\rho^{k}}{1-\rho} d\left(x_{p_{1}}, x_{p_{0}}\right) < +\infty; \quad \forall k \in \mathbb{Z}_{+}, \quad (20)$$

$$\limsup_{k \to \infty} d\left(x_{p_{k}}, x_{p_{0}}\right) \leq d\left(x_{p_{1}}, x_{p_{0}}\right) \left(\sum_{j=0}^{\infty} \rho^{j}\right)$$

$$\leq \frac{d\left(x_{p_{1}}, x_{p_{0}}\right)}{1-\rho} < +\infty,$$

$$\begin{split} d\left(x_{p_{k}+j}, x_{p_{k}+j-1}\right) \\ &\leq \prod_{n=0}^{j-1} \left\lfloor \left(1+m_{p_{k}+n}\right) \left(\sum_{i=0}^{k} \alpha_{i}^{(p_{k}+n)} K^{i}\right) \right\rfloor d\left(x_{p_{k}}, x_{p_{k-1}}\right) \\ &< +\infty, \end{split}$$

$$\begin{split} d\left(x_{p_{k}+j}, x_{p_{k}}\right) \\ &\leq \rho^{k} \left(\sum_{i=0}^{j-1} \prod_{n=0}^{i-1} \left\lfloor \left(1 + m_{p_{k}+n}\right) \right. \\ &\left. \times \left(\sum_{\ell=0}^{k} \alpha_{\ell}^{(p_{k}+n)} K^{\ell}\right) \right\rfloor \right) d\left(x_{p_{0}}, x_{p_{1}}\right) \\ &\leq +\infty, \end{split}$$

for $j = 0, 1, ..., p_{k+1} - p_k$, $\forall k \in \mathbb{Z}_+$, and then, since $\{p_k\}$ is strictly increasing with $k, \rho \in [0, 1)$ and $p_1 \le p_0 + p \le p + \overline{p} < +\infty$, one gets $\lim_{k \to \infty} d(x_{p_k+j}, x_{p_k}) = 0$ for $j = 0, 1, ..., p_{k+1} - p_k$, $\forall k \in \mathbb{Z}_+$. Then, $\{d(x_{n+1}, x_n)\} \to 0$ as $n \to \infty$ from (23) and $\{x_n\}$ is bounded for any initial $x_0 \in X$. However, $\{x_n\}$ is not a Cauchy sequence, in general, since the constraint $d(x_{n+2}, x_{n+1}) < d(x_{n+1}, x_n)$ does not necessarily hold for all $n \in \mathbb{Z}_{0+}$.

The variation in the proof development of the concerns derived from the assumption $\{T_n\} \Rightarrow T^*$ of Theorem 1 (ii) is addressed as follows. Since $\{T_n\} \Rightarrow T^*$ and $\operatorname{Fix}(T_n) = \{z_n^*\}$, $\forall n \in \mathbb{Z}_{0+}$, then (17) necessarily leads to $T^* : X \to X$ being a strict contraction, $\{z_n^*\} \to z^*$ with $z^* \in \text{Fix}(T^*)$ (= $\{z^*\}$), and $\lim_{k\to\infty} (p_{k+1} - p_k) = 1$. Therefore, the remaining proofs of properties (i)–(iii) follow in a very close way as their counterparts of Theorem 1. Also, note that

$$d(x_{p_{0}}, x_{p_{0}-1})$$

$$\leq \sum_{i=0}^{p_{0}-1} d(x_{i+1}, x_{i}) \qquad (24)$$

$$\leq \sum_{i=0}^{p_{0}-1} \prod_{n=0}^{i-1} \left[(1+m_{n}) \left(\sum_{\ell=0}^{k} \alpha_{\ell}^{(n)} K^{\ell} \right) \right] d(x_{0}, x_{1}),$$

and then define

$$M = \sup_{k \in \mathbb{Z}_{0+}} \max_{p_k \leq n < p_{k+1}} \left(\sum_{i=0}^{j-1} \prod_{n=0}^{i-1} \left[\left(1 + m_{p_k+n} \right) \times \left(\sum_{\ell=0}^k \alpha_\ell^{(p_k+n)} K^\ell \right) \right] \right),$$
(25)

so that property (iv) follows from (23) and Theorem 1 (iv). $\hfill \Box$

Remark 7. Note that assumption 4 of Theorem 1 is relaxed to the constraint (17) which holds for a set of connected finite intervals within a strictly increasing sequence of points with the difference between any two consecutive ones being upperbounded by a prescribed bound.

Remark 8. Note that Theorems 1 (i), 4 (ii), and 6 (iii) hold irrespective of the convergence of the sequence of self-mappings to a limit.

3. Iterative Scheme 2 and Some Generalizations

(22)

(23)

Now, consider the iterative scheme

$$x_{n+1} = T_n^{f_n} x_n, \quad T_n x = g_n T x; \quad \forall n \in \mathbb{Z}_{0+},$$
(26)

for any given $x_0 \in X$ which is a further generalization of the De Figueiredo iteration [8]. The following result holds.

Theorem 9. Let the iterative scheme (1) with the nonexpansive self-mapping $T : X \rightarrow X$ on a vector space X, with $0 \in X$, under the following additional assumptions.

- (1) Either (X, ||||) is a Banach space endowed with a norm |||| or, respectively, (X, d) is a complete metric space endowed with a homogeneous translation-invariant metric d: X × X → R₀₊.
- (2) $\{g_n\} \in (0, 1) \cap \mathbf{R}_{0+}$ is a real parameterization sequence with $0 < g_n < 1$, $\forall n \in \mathbf{Z}_{0+}$, and $\{f_n\} \subseteq \mathbf{Z}_{0+}$ is an integer sequence with $f_n > 0$; $\forall n \in \mathbf{Z}_+$.
- (3) There exist the following limits: $\lim_{n\to\infty} g_n = 1$, $\lim_{n\to\infty} (f_n/n) = +\infty$, and either $\lim_{n\to\infty} (f_{n+1} \log g_{n+1}/f_n \log g_n) < 1$ or $\lim_{n\to\infty} n(1 - (f_{n+1} \log g_{n+1}/f_n \log g_n))| < +\infty$.

Then, the subsequent properties hold.

- (i) $\{x_n\}$ converges to a fixed point of $T: X \to X$.
- (ii) If $T: X \to X$ is a strict contraction then $\{x_n\}$ converges to the unique fixed point of $T: X \to X$.

Proof. As in the proof of Theorem 1, the following considerations are applicable for the proof.

- (1) If (X, ||||) is a normed space then there is always a metric-induced norm $d(x, y) = ||x y||; \forall x, y \in X$.
- (2) If (X, d) is a metric space endowed with a homogeneous translation-invariant metric d: X × X → R₀₊ then there is a norm-induced metric ||x|| = d(x, 0); ∀x, y ∈ X.

Both spaces (X, |||) and (X, d) are formally identical under assumption 1 and both possess either a metric-induced norm by using the standard metric properties and its homogeneous and translation-invariance properties or a norm-induced metric, respectively. Now, note from (26) that

$$\begin{split} x_{n+k} &= \left(\prod_{i=0}^{k-1} \left[g_{n+i}^{f_{n+i}}\right] T^{\sum_{i=0}^{k-1} f_{n+i}} x_n\right), \\ x_{n+k} - x_{n+k-1} \\ &= \left(\prod_{i=0}^{k-1} \left[g_{n+i}^{f_{n+i}}\right] T^{\sum_{i=0}^{k-1} f_{n+i}} - \prod_{i=0}^{k-2} \left[g_{n+i}^{f_{n+i}}\right] T^{\sum_{i=0}^{k-2} f_{n+i}}\right) x_n \\ &= \prod_{i=0}^{k-1} \left[g_{n+i}^{f_{n+i}}\right] \left(T^{\sum_{i=0}^{k-1} f_{n+i}} - T^{\sum_{i=0}^{k-2} f_{n+i}} + \left(1 - \frac{1}{\left[g_{n+k-1}^{f_{n+k-1}}\right]}\right) T^{\sum_{i=0}^{k-2} f_{n+i}}\right) x_n \\ &\quad \forall n \in \mathbf{Z}_{0+}, \quad \forall k \in \mathbf{Z}_{+} \end{split}$$

$$\begin{split} \|x_{n+k} - x_{n+k-1}\| \\ &\leq \left\| \prod_{i=0}^{k-1} \left[g_{n+i}^{f_{n+i}} \right] \left(I - T^{f_{n+k-1}} \right) \right\| \times \left\| T^{\sum_{i=0}^{k-2} f_{n+i}} x_n \right\| \\ &+ \left\| \prod_{i=0}^{k-1} \left[g_{n+i}^{f_{n+i}} \right] \left(\left| 1 - \frac{1}{\left(g_{n+k-1}^{f_{n+k-1}} \right)} \right| T^{\sum_{i=0}^{k-2} f_{n+i}} \right) x_n \right\|; \\ &\quad \forall n \in \mathbf{Z}_{0+}, \quad \forall k \in \mathbf{Z}_{+}, \end{split}$$

$$\begin{split} \limsup_{n \to \infty} \| x_{n+k} - x_{n+k-1} \| \\ & \leq 2 \left(\prod_{i=0}^{k-1} \left[g_{n+i}^{f_{n+i}} \right] \right) \limsup_{n \to \infty} \left\| T^{\sum_{i=0}^{k-2} f_{n+i}} x_n \right\| \end{split}$$

$$+ \left(\prod_{i=0}^{k-1} \left[g_{n+i}^{f_{n+i}}\right]\right)$$

$$\times \limsup_{n \to \infty} \left(\left\| \left(\left| 1 - \frac{1}{\left(g_{n+k-1}^{f_{n+k-1}}\right)} \right| T^{\sum_{i=0}^{k-2} f_{n+i}} \right) x_n \right\| \right)$$

$$= 2 \left(\limsup_{n \to \infty} L_n(k) \right) \limsup_{n \to \infty} \left\| T^{\sum_{i=0}^{k-2} f_{n+i}} x_n \right\| < +\infty;$$

$$\forall k \in \mathbb{Z}_+,$$
(27)

since $||I - T^{f_{n+k-1}}|| \leq 2$, $\forall n \in \mathbb{Z}_{0+}$, $\forall k \in \mathbb{Z}_+$ because $T: X \to X$ is nonexpansive, $\lim_{n \to \infty} g_{n+k-1}^{f_{n+k-1}} = 1$; $\forall k \in \mathbb{Z}_+$ and $\prod_{i=0}^{k-1} [g_{n+i}^{f_{n+i}}] = L_n(k) \leq L_n(\infty) < +\infty$; $\forall k \in \mathbb{Z}_+$, $\forall n \in \mathbb{Z}_{0+}$ because $\{g_n\} \in (0,1) \cap \mathbb{R}_{0+}$ and either $\lim_{n \to \infty} (f_{n+1} \log g_{n+1}/f_n \log g_n) < 1$ or $|\lim_{n \to \infty} n(1 - (f_{n+1} \log g_{n+1}/f_n \log g_n))| < +\infty$. Then $\prod_{i=0}^{\infty} [g_{n+i}^{f_{n+i}}]$ is convergent since the corresponding logarithmic series of positive numbers converges according to either d'Alembert or Raabe convergence criteria of series of nonnegative real numbers. Then, the sequence $\{x_{n+1} - x_n\}$ is bounded. In the same way, we get

$$\begin{split} \limsup_{k \to \infty} \|x_{k} - x_{k-1}\| \\ \leq 2 \left(\prod_{i=0}^{k-1} \left[g_{i}^{f_{i}} \right] \right) \limsup_{k \to \infty} \|T^{\sum_{i=0}^{k-2} f_{i}} x_{0}\| \\ + \left(\prod_{i=0}^{k-1} \left[g_{i}^{f_{i}} \right] \right) \\ \times \limsup_{k \to \infty} \left(\left\| \left(\left\| 1 - \frac{1}{\left(g_{k-1}^{f_{k-1}} \right)} \right\| T^{\sum_{i=0}^{k-2} f_{i}} \right) x_{0} \right\| \right) \\ = 2 \left(\limsup_{k \to \infty} L_{0} \left(k \right) \right) \limsup_{k \to \infty} \left\| T^{\sum_{i=0}^{k-2} f_{i}} x_{0} \right\| \\ = 2 \left(\limsup_{k \to \infty} L_{0} \left(k \right) \right) x^{*} = 0, \end{split}$$

$$(28)$$

since $\exists \lim_{k \to \infty} L_0(k) = \prod_{i=0}^{k-1} [g_i^{f_i}] = 0$ since $g_n < 1$, $\forall n \in \mathbb{Z}_{0+}$, and $\lim_{n \to \infty} (f_n/n) = +\infty$ so that $\exists \lim_{n \to \infty} \|T^{\sum_{i=0}^{k-2} f_{n+i}} x_n\| = x^* (\in \operatorname{Fix}(T))$. Thus, $\{d(x_{n+1}, x_n)\}$ converges to zero for any given $x_0 \in X$ and

$$d(x_{n+1}, x^*) \le d(x_{n+1}, x_n) + d(x_n, x^*)$$
(29)

so that, since $d(x_{n+1}, x_n) \to 0$ as $n \to \infty$, $\lim_{n\to\infty} (d(x_{n+1}, x^*) - d(x_n, x^*)) = 0$. Then, $\{d(x_n, x^*)\}$ converges and $\{x_n\}$ converges as well to some point of X since (X, d) is complete so that $x_n \to (x^* + q)$ as $n \to \infty$ for some $q \in X$ and

since $T: X \rightarrow X$ is nonexpansive so that it is *K*-Lipschitzcontinuous (i.e., continuous with a Lipschitz constant $K \le 1$), one gets

$$\lim_{n \to \infty} d(x_{n+1}, x_n) = d\left(\lim_{n \to \infty} x_{n+1}, \lim_{n \to \infty} x_n\right) = d(x^* + q, x^* + q) = 0.$$
(30)

Since $\{x_n\}$ converges and (X, d) is a metric space then $\{x_n\}$ is a Cauchy sequence (and a bounded sequence) and there is $a \in \mathbf{R}_{0+}$ such that

$$a = \lim_{n \to \infty} d(x_n, x^*) = d(x^* + q, x^*)$$

=
$$\lim_{n \to \infty} d((g_n T)^{f_n} x_n, x^*)$$

=
$$d(\lim_{n \to \infty} T^{f_n} (x^* + q), x^*) = d(y^*, x^*),$$
 (31)

since the metric is translation-invariant, $g_n \to 1$ as $n \to \infty$, and since $T: X \to X$ is nonexpansive, it is $K(\leq 1)$ -Lipschitzcontinuous and $T^{f_n}(x^* + q) \to y^*$ with $y^*, x^* \in Fix(T)$. If a = 0 then $y^* = x^* (\in Fix(T))$ and we have proven that $\{x_n\}$ converges to the fixed point x^* of $T: X \to X$. Now, assume that $y^*(\neq x^*) \in Fix(T)$. The result is again proven since $\{x_n\}$ converges to a fixed point of $T: X \to X$ which is distinct of x^* . Finally, assume that $y^* \notin Fix(T)$ and proceed by contradiction to prove that this assertion is false. Since $T: X \to$ X is nonexpansive, one gets $d(T^ny^*, T^nx^*) \leq \cdots \leq d(y^*,$ $x^*) = a$ so that $d(T^ny^*, x^*) \to a_1(\leq a)$ as $n \to \infty$; then by everywhere Lipschitz continuity of the nonexpansive selfmapping $T: X \to X$,

$$d\left(\lim_{n \to \infty} T^{n}\left(Ty^{*}\right), x^{*}\right) = d\left(T\left(\lim_{n \to \infty} T^{n}y^{*}\right), x^{*}\right)$$
$$= d\left(\lim_{n \to \infty} T^{n}y^{*}, x^{*}\right) = d\left(y_{1}^{*}, x^{*}\right)$$
$$= a_{1} \leq a,$$
(32)

and $T^n y^* \to y_1^* (\in \operatorname{Fix}(T))$ and $T^{f_n} y^* \to y_1^*$. Since y^* is a limit point of $T^{f_n} x_n$, $a_1 = a$ and then $y^* (= y_1^*) \in \operatorname{Fix}(T)$, a contradiction to $y^* \notin \operatorname{Fix}(T)$. Thus, $\{T^{f_n} x_n\}$ converges to a fixed point of $T: X \to X$. Property (i) has been proven. Also,

$$d\left(T_{n}^{f_{n}}x_{n}, T^{f_{n}}x_{n}\right) = d\left(T_{n}^{f_{n}}x_{n} - T^{f_{n}}x_{n}, 0\right)$$

$$\leq \left\|T_{n}^{f_{n}} - T^{f_{n}}\right\| \left\|x_{n}\right\|; \quad \forall n \in \mathbb{Z}_{0+}.$$
(33)

Since $||T_n^{f_n} - T^{f_n}|| \le (1 - g_n^{f_n}) ||T^{f_n}||$, $\forall n \in \mathbb{Z}_{0+}$ with $(1 - g_n^{f_n}) \to 0$ as $n \to \infty$, it follows that $||T_n^{f_n} - T^{f_n}|| \to 0$ as $n \to \infty$ and since $\{T^{f_n}x_n\}$ converges to a fixed point of $T: X \to X$ then $\{T_n^{f_n}x_n\}$ also converges to the same fixed point of $T: X \to X$. Hence, property (i) follows.

On the other hand, if $T: X \to X$ is a strict contraction then Fix $(T) = \{x^*\}$, since (X, d) is complete so that a = 0 and $y^* = x^*$ in (31) and, hence, property (ii) follows as well. \Box

Theorem 9 has the following derived result.

Corollary 10. Let the iterative scheme (1) be under the nonexpansive self-mapping $T : C \rightarrow C$, where C is a nonempty closed and convex subset of a Hilbert space (X, ||||), with $0 \in$ C, subject to all the assumptions of Theorem 9. Then, the subsequent properties hold.

- (i) $\{x_n\}$ converges strongly to a fixed point of $T: C \to C$.
- (ii) If $T : C \to C$ is a strict contraction then $\{x_n\}$ converges to the unique fixed point of $T : C \to C$.

Proof. Property (i) follows from Theorem 1 since (X, ||||) is uniformly convex since it is a Hilbert space; $T : C \to C$ is nonexpansive and contains a bounded sequence (since *C* is nonempty, closed, and convex) and then it has at least a fixed point. Property (ii) follows since such a fixed point is unique if $T: C \to C$ is a strict contraction.

The iterative scheme (26) is now generalized by using some ideas of Section 2 as follows:

$$x_{n+1} = T_n^{f_n} x_n, \quad T_n x = g_n \left(\sum_{i=0}^k \alpha_i T^i \right) x_n; \quad \forall n \in \mathbb{Z}_{0+}, \quad (34)$$

for any given $x_0 \in X$.

Theorem 11. Let the iterative scheme (34) generated by the selfmapping $T : X \rightarrow X$ on a vector space X, with $0 \in X$, and assumptions 1–3 of Theorem 9 hold as well as the following additional assumptions:

- (1) $\sum_{i=0}^{k} \alpha_i > 0$ for nonnegative real scalars α_i , $\forall i \in \overline{k}$, and $\max_{1 \le i \le k} \alpha_i > 0$;
- (2) $T : X \rightarrow X$ satisfies the condition $d(Tx, Ty) \leq Kd(x, y), \forall x, y \in X$, for some $K \in \mathbf{R}_+$;
- (3) $\sum_{i=0}^{k} \alpha_i K^i \leq 1; \forall n \in \mathbb{Z}_{0+}.$

Then, the subsequent properties hold.

- (i) $\{x_n\}$ converges to a fixed point of the nonexpansive selfmapping $\overline{T}: X \to X$ defined by $\overline{T}x = (\sum_{i=0}^k \alpha_i T^i)x$, $\forall x \in X$.
- (ii) If T: X → X is a strict contraction fulfilling ∑_{i=0}^k α_i
 Kⁱ ≤ ρ < 1 then {x_n} converges to the unique fixed point of T : X → X.

Proof. As in Theorem 1 and Theorem 9, both spaces (X, |||)and (X, d) are formally identical under assumption 1 of Theorem 9 and both possess either a metric-induced norm by using the standard metric properties and its homogeneous and translation-invariance properties or a norm-induced metric, respectively. Now, define the mapping $\overline{T} : X \to X$ by $\overline{T}x = (\sum_{i=0}^{k} \alpha_i T^i)x$, $\forall x \in X$. Thus, (27) in the proof of Theorem 9 still holds with the replacement $T \to \overline{T}$. Note that $||I - \overline{T}^{f_{n+k-1}}|| \leq 2, \forall n \in \mathbb{Z}_{0+}, \forall k \in \mathbb{Z}_{+}, \text{ since } \overline{T} : X \to X \text{ is non$ $expansive (even if <math>T : X \to X$ is expansive with K > 1 in the assumption 2), from assumptions 2-3, and \overline{K} -Lipschitzcontinuous from the assumption 3 with $\overline{K} = \sum_{i=0}^{k} \alpha_i K^i \leq 1$. Note also that $\lim_{n\to\infty} g_{n+k-1}^{f_{n+k-1}} = 1, \forall k \in \mathbb{Z}_+, \text{ and } \prod_{i=0}^{k-1} [g_{n+i}^{f_{n+i}}] \leq L_n(k) \leq L_n(\infty) < +\infty, \forall k \in \mathbb{Z}_+, \forall n \in \mathbb{Z}_{0+}, \text{ and then the sequence } \{x_{n+1} - x_n\}$ obtained from the iterative scheme (34) is bounded for any $x_0 \in X$. In the same way, (28) holds from assumptions 2-3 of Theorem 9, since $g_n < 1, \forall n \in \mathbb{Z}_{0+}, \text{ and } \lim_{n\to\infty} (f_n/n) = +\infty$ so that $\exists \lim_{n\to\infty} \|\overline{T}^{\sum_{i=0}^{k-2} f_{n+i}} x_n\| = x^*$ ($\in \operatorname{Fix}(\overline{T})$). Thus, $\{d(x_{n+1}, x_n)\}$ converges to zero for any given $x_0 \in X$ since (X, d) is complete. Then, it follows (as it is deduced from (30) in the proof of Theorem 9) that $\{x_n\}$ converges to some fixed point \overline{x}^* of the nonexpansive self-mapping $\overline{T}: X \to X$ for each given initial point $x_0 \in X$ is a strict contraction.

In a similar way as Corollary 10 is got from Theorem 9, one gets the following.

Corollary 12. Consider the iterative scheme (34) under the nonexpansive self-mapping $\overline{T} : C \to C$, where C is a nonempty closed and convex subset of a Hilbert space (X, ||||), with $0 \in C$, subject to all the assumptions of Theorem 9. Then, the subsequent properties hold.

- (i) $\{x_n\}$ converges strongly to a fixed point of $\overline{T}: C \to C$.
- (ii) If T: C → C is a strict contraction fulfilling ∑_{i=0}^k α_i
 Kⁱ ≤ ρ < 1 then {x_n} converges to the unique fixed point of T: C → C.

Note that in Theorem 9 (i) and Corollary 10 (i), $T: X \to X$ and $T_n^{f_n} : X \to X$ for $n \in \mathbb{Z}_+$ are not necessarily Picard mappings since the limiting points can be dependent on the initial condition of the iterative schemes. The same conclusion arises for $\overline{T} : X \to X$ and $\overline{T}_n^{f_n} : X \to X$ for $n \in \mathbb{Z}_{0+}$ in Theorem 11 (i) and Corollary 12 (i). However, the above self-mappings are Picard iterations in the corresponding parts (ii) of such results since the relevant mappings are strict contractions.

Note also that Theorem 11 and Corollary 12 still hold by replacing $\alpha_i \rightarrow \alpha_i^{(n)}$ for $i \in \overline{k}$ and the replacement of the constraint $\max_{1 \le i \le k} \alpha_i > 0$ with $\inf_{n \in \mathbb{Z}_{0+}} \max_{1 \le i \le k} \alpha_i^{(n)} > 0$.

4. Simulation Examples towards an Application Perspective on Discrete Nonlinear Dynamic Systems

This section contains two numerical examples. The first one is related to the Iterative Scheme 1 introduced in Section 2 while the second one concerns the Iterative Scheme 2 discussed in Section 3.

4.1. Iterative Scheme 1. Consider the iterative scheme defined by (1) with T(x) = x/2(1 + x) on $[0, +\infty)$ and

$$x_{n+1} = \left(\alpha_3^{(n)}T^3 + \alpha_2^{(n)}T^2 + \alpha_1^{(n)}T^1 + \alpha_0^{(n)}I\right)x_n.$$
 (35)

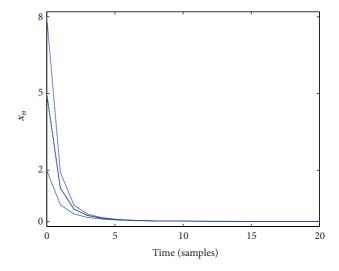


FIGURE 1: Evolution of the iterates for different initial conditions.

T is a strict contraction satisfying the condition d(T(x)), $T(y) \le Kd(x, y)$ with K = 1/2 (for the Euclidean distance) and, hence, it possesses a unique fixed point at x = 0. Note that the above description can also be considered as that of a nonlinear discrete time-varying dynamic system where the state evolves from initial conditions according to the sequence $\{x_n\}$ with initial condition x_0 while the output is defined by the real map $x \to Tx$. Note that the fixed point x = 0is also an equilibrium point of the dynamic system which is suited to be globally asymptotically stable. Consider, firstly, the sequence of constant weights $\alpha^{(n)} = [0.2 \ 0.3 \ 0.8 \ 0.9]$ for all $n \ge 0$. We are now in conditions of applying Theorem 1 since $\sum_{i=0}^{3} \alpha_i^{(n)} = 2.2 > 0$, $\tilde{\alpha}_i^{(n)} = m_n = 0$, and $\sum_{i=0}^{3} \alpha_i^{(n)} K^i = 0.6625 < 1$ for all integers $n \ge 0$. In this case, the system parameterization is close to, but more general than, a polytopic-type time-invariant one but, in particular, the usual constraint $\sum_{i=0}^{3} \alpha_{i}^{(n)} = 1$ is not needed. Accordingly, the sequence of iterates $\{x_n\}$ is bounded for all $n \ge 0$ and converges to the unique fixed point of T, x = 0. Moreover, the iterates converge to the unique fixed point regardless of the initial value x_0 . These claims are verified through a numerical simulation in Figure 1.

Furthermore, Theorem 1 (iv) also provides an upperbound for the rate of convergence of the sequence of iterates to the fixed point. Therefore, one gets from (4) $d(x_n, 0) \le \rho^n d(x_0, 0) = 0.6625^n d(x_0, 0)$. Figure 2 displays the evolution of iterates along with the calculated upper-bound for the case $x_0 = 8$.

Consider the time-varying parameterization under the time-varying weights given by

$$\alpha_i^{(n+1)} = \begin{cases} \lambda_i \alpha_i^{(n)}, & \alpha_i^{(n+1)} \ge 0.1, \\ 0.1, & \text{otherwise,} \end{cases}$$
(36)

for all $n \ge 0$ and $0 \le i \le 3$ with $\alpha^{(0)} = [0.2 \ 0.3 \ 0.8 \ 0.9]$, $\lambda_0 = 0.95$, $\lambda_1 = 0.9$, $\lambda_2 = 0.85$, and $\lambda_3 = 0.8$. The 0.1 lower bound has been included in (36) so as to satisfy the condition $\inf_{n \in \mathbb{Z}_{0+}} \max_{1 \le i \le k} \alpha_i^{(n)} > 0$.

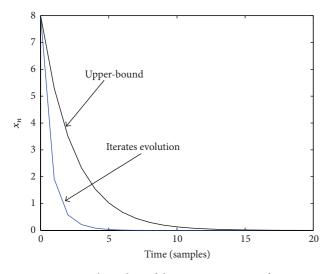


FIGURE 2: Upper-bounding of the convergence rate of iteration.

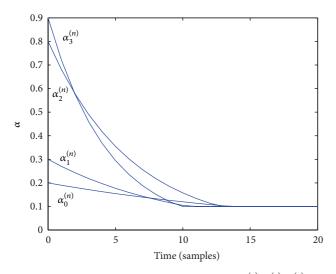


FIGURE 3: Evolution of the time-varying weights $\alpha_0^{(n)}$, $\alpha_1^{(n)}$, $\alpha_2^{(n)}$, and $\alpha_3^{(n)}$ through (36).

As it can be appreciated in Figure 3, the weights are decreasing with time until they reach the constant lower bound of 0.1 where they stop decreasing and become time-invariant. In fact, Figure 3 shows that this happens for $n \ge 14$. Thus, we are in conditions of applying the results stated in Theorem 6 for the case when the stability condition only holds on a subset of the nonnegative integer numbers. In this way, we have $\tilde{\alpha}_i^{(n)} = m_n = 0$ for all $n \ge 14$ and (17) of Theorem 6 is satisfied since

$$\sum_{i=0}^{3} \alpha_i^{(n)} K^i = \sum_{i=0}^{3} 0.1 K^i = 0.1875 < 1,$$
(37)

for all $n \ge 14$. Thus, Theorem 6 guarantees the convergence of iterates to the unique fixed point irrespectively of the initial condition. This fact is shown in Figure 4.

One advantage of the results in Theorem 6 for the sake of generality is that an arbitrary variation in the weights is

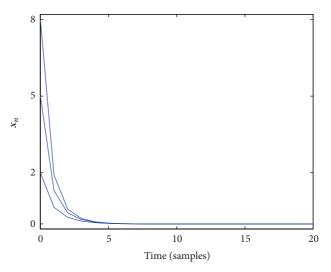


FIGURE 4: Iterates for different initial conditions and weights defined by (36).

admitted on certain subsets of the natural numbers. Thus, the family of admissible time variations for which the stability of the iteration scheme is guaranteed enlarges with respect to other approaches. Consider a time-varying set of weights defined with $m_n = d(x_{n+1}, 0)$ in condition (2) of Theorem 1 so that $\tilde{\alpha}_n \leq d(x_n, x_{n+1}) \leq Kd(x_{n-1}, x_n) = 1/2d(x_{n-1}, x_n)$ while condition (4) becomes

$$(1+m_n)\sum_{i=0}^{3}\alpha_i^{(n)}K^i$$

$$= (1+m_n)\left(\alpha_0^{(n)} + \frac{1}{2}\alpha_1^{(n)} + \frac{1}{2^2}\alpha_2^{(n)} + \frac{1}{2^3}\alpha_3^{(n)}\right) < 1.$$
(38)

Such constraints are satisfied, for instance, if we take $\alpha^{(0)} = [0.05 \ 0.1 \ 0.15 \ 0.2]$ and

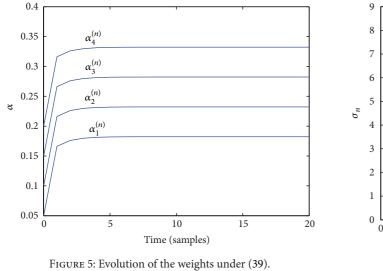
$$\tilde{\alpha}_n = 0.05 \sin(2\pi 0.05n) d(x_{n-1}, x_n).$$
 (39)

The weights evolution is displayed in Figure 5. Note that the weight variation defined by (39) satisfies the condition $\tilde{\alpha}_n \leq d(x_n, x_{n+1}) \leq 1/2d(x_{n-1}, x_n)$ since $0.05 \sin(2\pi 0.05n) \leq 0.05$, $\forall n \in \mathbb{Z}_{0+}$.

Figure 6 displays the sample-by-sample stability condition evaluation, in terms of the left-hand side of (38), showing that it remains smaller than unity. Therefore, according to Theorem 1, the iterates converge to zero as Figure 7 depicts.

Also, $d(x_{n-1}, x_n) \rightarrow 0$ while the weights converge to a real constant according to (39). Thus, the given theoretical results are useful to conclude the convergence of iteration schemes of the form (1).

4.2. Iterative Scheme 2. This second example is concerned with the iterative scheme defined by (26). Note that the first equation can describe, in particular, the state and output of



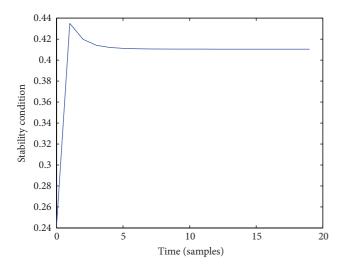


FIGURE 6: Numerical verification of the stability condition (38).

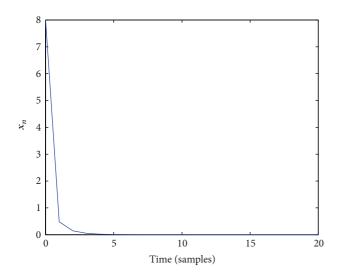


FIGURE 7: Convergence of the iterates to zero for time-varying weights given by (39).

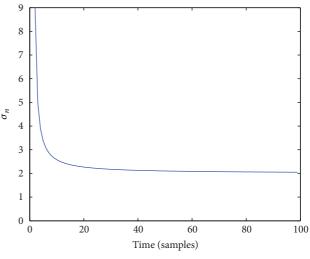


FIGURE 8: Evolution of σ_n with time.

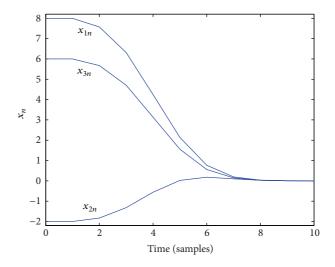


FIGURE 9: Evolution of the iterates through time.

a certain nonlinear discrete dynamic system. Thus, consider the linear discrete-time system given by

$$Tx = Ax = \begin{pmatrix} 0.955 & 0.01 & 0.005\\ 0.005 & 0.96 & 0.005\\ -0.005 & 0.01 & 0.965 \end{pmatrix} x,$$
(40)

with sequences $g_n = 1 - 0.1^{n+1}$ and $f_n = n^2$ for all $n \ge 0.T$ is a strict contraction with eigenvalues {0.95, 0.96, 0.97}, $||A||_{\infty} = 0.98$, and $||A||_2 = 0.9717$. Thus, it has a unique fixed point at x = 0. These sequences satisfy conditions (2) and (3) stated in Theorem 9 since $\lim_{n\to\infty} g_n = 1$, $0 < g_n < 1$ for all $n \ge 0$, $\lim_{n\to\infty} (f_n/n) = \lim_{n\to\infty} n = +\infty$, and $\lim_{n\to\infty} \sigma_n < +\infty$ with $\sigma_n = |n(1 - (f_{n+1} \log g_{n+1}/f_n \log g_n))|$ and $\{\sigma_n\} \to 2$ (see Figure 8).

From Theorem 9, the sequence of iterates converges to the unique fixed point of T, x = 0, as it is confirmed in the numerical simulation displayed in Figure 9.

5. Conclusion

This paper has investigated the boundedness and convergence properties of two general iterative processes built with sequences of self-mappings in either complete metric or Banach spaces. The self-mappings of the first iterative scheme are built with linear combinations of a set of self-mappings each of them being a weighted version of a self-mapping on the same space. Those of the second scheme are powers of an iteration-dependent scaled version of the primary self-mapping. Some applications are given for global stability of a class of nonlinear polytopic-type parameterizations of dynamic systems.

Conflict of Interests

The authors declare that they have no conflict of interests regarding the publication of this paper.

Acknowledgments

The authors are very grateful to the Spanish and Basque Governments and to UPV/EHU for Grants DPI2012-30651, IT378-10, SAIOTEK S-PE13UN039, and UFI 2011/07. They thank the reviewers for their comments.

References

- Y. J. Cho, Z. Kadelburg, R. Saadati, and W. Shatanawi, "Coupled fixed point theorems under weak contractions," *Discrete Dynamics in Nature and Society*, vol. 2012, Article ID 184534, 9 pages, 2012.
- [2] H. K. Nashine and M. S. Khan, "An application of fixed point theorem to best approximation in locally convex space," *Applied Mathematics Letters*, vol. 23, no. 2, pp. 121–127, 2010.
- [3] M. S. Khan, K. P. R. Rao, and K. R. K. Rao, "Some fixed point theorems in D*-cone metric spaces," *Journal of Advanced Studies in Topology*, vol. 2, no. 2, pp. 37–45, 2011.
- [4] Y. H. Yao, Y. C. Liou, and S. M. Kang, "An iterative approach to mixed equilibrium problems and fixed point problems," *Fixed Point Theory and Applications*, vol. 2013, article 183, 2013.
- [5] A. Cordero, J. L. Hueso, E. Martínez, and J. R. Torregrosa, "Increasing the convergence order of an iterative method for nonlinear systems," *Applied Mathematics Letters*, vol. 25, no. 12, pp. 2369–2374, 2012.
- [6] A. Cordero, J. L. Hueso, E. Martínez, and J. R. Torregrosa, "Steffensen type methods for solving nonlinear equations," *Journal of Computational and Applied Mathematics*, vol. 236, no. 12, pp. 3058–3064, 2012.
- [7] J. J. Miñambres and M. de la Sen, "Application of numerical methods to the acceleration of the convergence of the adaptivecontrol algorithms: the one dimensional case," *Computers & Mathematics with Applications*, vol. 12, no. 10, pp. 1049–1056, 1986.
- [8] V. I. Istrăţescu, Fixed Point Theory: An Introduction, vol. 7 of Mathematics and Its Applications, D. Reidel Publishing, Dordrecht, The Netherlands, 1979.
- [9] S. Y. Cho, W. L. Li, and S. M. Kang, "Convergence analysis of an iterative algorithm for monotone operators," *Journal of Inequalities and Applications*, vol. 2013, article 199, 2013.

- [10] I. K. Argyros, Y. J. Cho, and S. K. Khattri, "On a new semilocal convergence analysis for the Jarratt method," *Journal* of *Inequalities and Applications*, vol. 2013, article 194, 2013.
- [11] J. R. Torregrosa, I. K. Argyros, C. B. Chun, A. Cordero, and F. Soleymani, "Iterative methods for nonlinear equations or systems and their applications," *Journal of Applied Mathematics*, vol. 2013, Article ID 656953, 2 pages, 2013.
- [12] M. Jleli, E. Karapınar, and B. Samet, "Best proximity point results for MK-proximal contractions," *Abstract and Applied Analysis*, vol. 2012, Article ID 193085, 14 pages, 2012.
- [13] V. Azhmyakov, M. Basin, and J. Raisch, "A proximal point based approach to optimal control of affine switched systems," *Discrete Event Dynamic Systems*, vol. 22, no. 1, pp. 61–81, 2012.
- [14] M. de la Sen and R. P. Agarwal, "Fixed point-type results for a class of extended cyclic self-mappings under three general weak contractive conditions of rational type," *Fixed Point Theory and Applications*, vol. 2011, article 102, 2011.
- [15] C. Park and T. M. Rassias, "Fuzzy stability of an additive-quartic functional equation: a fixed point approach," in *Functional Equations in Mathematical Analysis*, pp. 247–260, Springer, New York, NY, USA, 2012.
- [16] H. A. Kenary, S. Y. Jang, and C. Park, "A fixed point approach to the Hyers-Ulam stability of a functional equation in various normed spaces," *Fixed Point Theory and Applications*, vol. 2011, article 67, 2011.
- [17] M. de la Sen, "Linking contractive self-mappings and cyclic Meir-Keeler contractions with Kannan self-mappings," *Fixed Point Theory and Applications*, vol. 2010, Article ID 572057, 23 pages, 2010.
- [18] M. Jleli, E. Karapınar, and B. Samet, "A best proximity point result in modular spaces with the Fatou property," *Abstract and Applied Analysis*, vol. 2013, Article ID 329451, 4 pages, 2013.
- [19] H. K. Pathak and N. Shahzad, "Some results on best proximity points for cyclic mappings," *Bulletin of the Belgian Mathematical Society, Simon Stevin*, vol. 20, no. 3, pp. 559–572, 2013.
- [20] M. de la Sen and E. Karapinar, "Best proximity points of generalized semicyclic impulsive self-mappings: applications to impulsive differential and difference equations," *Abstract and Applied Analysis*, vol. 2013, Article ID 505487, 16 pages, 2013.
- [21] D. Dey, A. Kumar Laha, and M. Saha, "Approximate coincidence point of two nonlinear mappings," *Journal of Mathematics*, vol. 2013, Article ID 962058, 4 pages, 2013.
- [22] D. Dey and M. Saha, "Approximate fixed point of Reich operator," *Acta Mathematica Universitatis Comenianae*, vol. 82, no. 1, pp. 119–123, 2013.
- [23] M. de la Sen and A. Ibeas, "Asymptotically non-expansive self-maps and global stability with ultimate boundedness of dynamic systems," *Applied Mathematics and Computation*, vol. 219, no. 22, pp. 10655–10667, 2013.
- [24] M. de la Sen, R. P. Agarwal, and R. Nistal, "Non-expansive and potentially expansive properties of two modified p-cyclic self-maps in metric spaces," *Journal of Nonlinear and Convex Analysis*, vol. 14, no. 4, pp. 661–686, 2013.
- [25] N. Hussain, A. Latif, and P. Salimi, "Best proximity point results for modified Suzuki α - ψ -proximal contractions," *Fixed Point Theory and Applications*, vol. 2014 article 10, 2014.
- [26] A. Ashyralyev and Y. A. Sharifov, "Optimal control problem for impulsive systems with integral boundary conditions," in *Proceedings of the 1st International Conference on Analysis* and Applied Mathematics (ICAAM '12), vol. 1470, pp. 12–15, Gumushane, Turkey, October 2012.

- [27] X. D. Li, H. Akca, and X. L. Fu, "Uniform stability of impulsive infinite delay differential equations with applications to systems with integral impulsive conditions," *Applied Mathematics and Computation*, vol. 219, no. 14, pp. 7329–7337, 2013.
- [28] G. Stamov, H. Akca, and I. Stamova, "Uncertain dynamic systems: analysis and applications," *Abstract and Applied Analysis*, vol. 2013, Article ID 863060, 2 pages, 2013.
- [29] H. Li, X. Sun, H. R. Karimi, and B. Niu, "Dynamic outputfeedback passivity control for fuzzy systems under variable sampling," *Mathematical Problems in Engineering*, vol. 2013, Article ID 767093, 10 pages, 2013.
- [30] Z. Xiang, S. Liu, and M. S. Mahmoud, "Robust H_{∞} reliable control for uncertain switched neutral systems with distributed delays," *IMA Journal of Mathematical Control and Information*, 2013.
- [31] Q. J. A. Khan, E. V. Krishnan, and M. A. Al-Lawatia, "A stage structure model for the growth of a population involving switching and cooperation," *ZAMM-Journal of Applied Mathematics and Mechanics*, vol. 82, no. 2, pp. 125–135, 2002.
- [32] V. Azhmyakov and M. T. Angulo, "Applications of the strong approximability property to a class of affine switched systems and to relaxed differential equations with affine structure," *International Journal of Systems Science*, vol. 42, no. 11, pp. 1899– 1907, 2011.
- [33] M. de la Sen, "On positivity of singular regular linear timedelay time-invariant systems subject to multiple internal and external incommensurate point delays," *Applied Mathematics* and Computation, vol. 190, no. 1, pp. 382–401, 2007.
- [34] M. de la Sen, "About the positivity of a class of hybrid dynamic linear systems," *Applied Mathematics and Computation*, vol. 189, no. 1, pp. 852–868, 2007.
- [35] M. de la Sen, "Total stability properties based on fixed point theory for a class of hybrid dynamic systems," *Fixed Point Theory and Applications*, vol. 2009, Article ID 826438, 2009.
- [36] M. de La Sen, "On the robust adaptive stabilization of a class of nominally first-order hybrid systems," *IEEE Transactions on Automatic Control*, vol. 44, no. 3, pp. 597–602, 1999.
- [37] M. de la Sen, "On some structures of stabilizing control laws for linear and time-invariant systems with bounded point delays and unmeasurable states," *International Journal of Control*, vol. 59, no. 2, pp. 529–541, 1994.
- [38] M. de la Sen and A. Ibeas, "Stability results for switched linear systems with constant discrete delays," *Mathematical Problems in Engineering*, vol. 2008, Article ID 543145, 28 pages, 2008.
- [39] M. de la Sen and A. Ibeas, "On the global asymptotic stability of switched linear time-varying systems with constant point delays," *Discrete Dynamics in Nature and Society*, vol. 2008, Article ID 231710, 31 pages, 2008.
- [40] M. de la Sen, A. Ibeas, and S. Alonso-Quesada, "Asymptotic hyperstability of a class of linear systems under impulsive controls subject to an integral Popovian constraint," *Abstract and Applied Analysis*, vol. 2013, Article ID 382762, 14 pages, 2013.
- [41] V. M. Marchenko, "Observability of hybrid discrete-continuous time system," *Differential Equations*, vol. 49, no. 11, pp. 1389– 1404, 2013.
- [42] P. Niamsup, T. Rojsiraphisa, and M. Rajchakit, "Robust stability and stabilization of uncertain switched discrete-time systems," *Advances in Difference Equations*, vol. 2012, article 134, 2012.
- [43] G. Rajchakit, "Stabilization of switched discrete-time systems with convex polytopic uncertainties," *Journal of Computational Analysis & Applications*, vol. 16, no. 1, pp. 20–29, 2014.

- [44] M. A. Darwish and K. Sadarangani, "On existence and asymptotic stability of solutions of a functional-integral equation of fractional order," *Journal of Convex Analysis*, vol. 17, no. 2, pp. 413–426, 2010.
- [45] M. A. Darwish and J. Henderson, "Existence and asymptotic stability of solutions of a perturbed quadratic fractional integral equation," *Fractional Calculus & Applied Analysis*, vol. 12, no. 1, pp. 71–86, 2009.