## Research Article

# Nonlinear Integrable Couplings of Levi Hierarchy and WKI Hierarchy 

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With the help of the known Lie algebra, a type of new 8 -dimensional matrix Lie algebra is constructed in the paper. By using the 8 -dimensional matrix Lie algebra, the nonlinear integrable couplings of the Levi hierarchy and the Wadati-Konno-Ichikawa (WKI) hierarchy are worked out, which are different from the linear integrable couplings. Based on the variational identity, the Hamiltonian structures of the above hierarchies are derived.

## 1. Introduction

The notion of integrable couplings was introduced when the study of Virasoro symmetric algebras [1, 2]. To find as many new integrable systems and their integrable couplings as possible and to elucidate in depth their algebraic and geometric properties are of both theoretical and practical value. During the past few years, some interesting integrable couplings and associated properties of some known interesting integrable hierarchies, such as the Ablowitz-Kaup-Newell-Segur (AKNS) hierarchy and the Kaup-Newell (KN) hierarchy, were obtained [3-13]. Here it is necessary to point out that the above mentioned integrable couplings are linear for the supplementary variable, so they are called linear integrable couplings.

Recently, Professor Ma proposed the notion of nonlinear integrable couplings and gave the general scheme to construct nonlinear integrable couplings of hierarchies [14]. Based on the general scheme of constructing nonlinear integrable couplings, Professor Zhang introduced some new explicit Lie algebras and obtained the nonlinear integrable couplings of the Giachetti-Johnson (GJ) hierarchy, the Yang hierarchy, and the classical Boussinesq-Burgers (CBB) hierarchy $[15,16]$.

The aim of the paper is to seek the nonlinear integrable couplings of the Levi hierarchy and the WKI hierarchy as well as their Hamiltonian structures. The plan of the paper is as follows. In Section 2, with the help of the Lie algebra $G=\left\{\left.\left(\begin{array}{cc}g_{1} & g_{2} \\ 0 & g_{1}+g_{2}\end{array}\right) \right\rvert\, g_{1}, g_{2} \in \operatorname{sl}(2)\right\}$, an 8-dimensional matrix Lie algebra is presented. It is different from the Lie algebras given in [14-16]. By employing the 8 -dimensional matrix Lie algebra, the nonlinear integrable couplings of the Levi hierarchy and the WKI hierarchy are derived in Section 3. Furthermore, the corresponding Hamiltonian structures are worked out by virtue of the variational identity in Section 4. Finally, some conclusions are obtained in Section 5.

## 2. 8-Dimensional Matrix Lie Algebra

The Lie algebra is presented as $H=\operatorname{span}\left\{h_{1}, h_{2}, h_{3}, h_{4}\right\}$ with the basis as follows:

$$
\begin{array}{ll}
h_{1}=\left(\begin{array}{ll}
1 & 0 \\
0 & 0
\end{array}\right), & h_{2}=\left(\begin{array}{ll}
0 & 0 \\
0 & 1
\end{array}\right),  \tag{1}\\
h_{3}=\left(\begin{array}{ll}
0 & 1 \\
0 & 0
\end{array}\right), & h_{4}=\left(\begin{array}{ll}
0 & 0 \\
1 & 0
\end{array}\right),
\end{array}
$$

equipped with the commutators

$$
\left.\begin{array}{ll}
{\left[h_{1}, h_{2}\right]=0,} & {\left[h_{1}, h_{3}\right]=h_{3},}
\end{array}\left[h_{1}, h_{4}\right]=-h_{4}, ~ 子 h_{3}, h_{3}, h_{4}\right]=h_{1}-h_{2} . ~ \$
$$

By virtue of the Lie algebra $H$, we construct an 8-dimensional matrix Lie algebra

$$
\begin{equation*}
G=\operatorname{span}\left\{g_{1}, g_{2}, g_{3}, g_{4}, g_{5}, g_{6}, g_{7}, g_{8}\right\} \tag{3}
\end{equation*}
$$

with the basis as follows:

$$
\begin{array}{ll}
g_{1}=\left(\begin{array}{cc}
h_{1} & 0 \\
0 & h_{1}
\end{array}\right), & g_{2}=\left(\begin{array}{cc}
h_{2} & 0 \\
0 & h_{2}
\end{array}\right), \\
g_{3}=\left(\begin{array}{cc}
h_{3} & 0 \\
0 & h_{3}
\end{array}\right), & g_{4}=\left(\begin{array}{cc}
h_{4} & 0 \\
0 & h_{4}
\end{array}\right), \\
g_{5}=\left(\begin{array}{ll}
0 & h_{1} \\
0 & h_{1}
\end{array}\right), & g_{6}=\left(\begin{array}{cc}
0 & h_{2} \\
0 & h_{2}
\end{array}\right),  \tag{4}\\
g_{7}=\left(\begin{array}{ll}
0 & h_{3} \\
0 & h_{3}
\end{array}\right), & g_{8}=\left(\begin{array}{ll}
0 & h_{4} \\
0 & h_{4}
\end{array}\right),
\end{array}
$$

which have the commutative relations

$$
\begin{array}{ccc}
{\left[g_{1}, g_{2}\right]=0,} & {\left[g_{1}, g_{3}\right]=g_{3},} & {\left[g_{1}, g_{4}\right]=-g_{4},} \\
{\left[g_{2}, g_{3}\right]=-g_{3},} & {\left[g_{2}, g_{4}\right]=g_{4},} & {\left[g_{3}, g_{4}\right]=g_{1}-g_{2},} \\
{\left[g_{1}, g_{5}\right]=0,} & {\left[g_{1}, g_{6}\right]=0,} & {\left[g_{1}, g_{7}\right]=g_{7},} \\
{\left[g_{1}, g_{8}\right]=-g_{8},} & {\left[g_{2}, g_{5}\right]=0,} & {\left[g_{2}, g_{6}\right]=0,} \\
{\left[g_{2}, g_{7}\right]=-g_{7},} & {\left[g_{2}, g_{8}\right]=g_{8},} & {\left[g_{3}, g_{5}\right]=-g_{7},} \\
{\left[g_{3}, g_{6}\right]=g_{7},} & {\left[g_{3}, g_{7}\right]=0,} & {\left[g_{3}, g_{8}\right]=g_{5}-g_{6},} \\
{\left[g_{4}, g_{5}\right]=g_{8},} & {\left[g_{4}, g_{6}\right]=-g_{8},} & {\left[g_{4}, g_{7}\right]=g_{6}-g_{5},} \\
{\left[g_{4}, g_{8}\right]=0,} & {\left[g_{5}, g_{6}\right]=0,} & {\left[g_{5}, g_{7}\right]=g_{7},} \\
{\left[g_{5}, g_{8}\right]=-g_{8},} & {\left[g_{6}, g_{7}\right]=-g_{7},} & {\left[g_{6}, g_{8}\right]=g_{8},} \\
& {\left[g_{7}, g_{8}\right]=g_{5}-g_{6} .} & \tag{5}
\end{array}
$$

Denoting $G_{1}=\operatorname{span}\left\{g_{1}, g_{2}, g_{3}, g_{4}\right\}$ and $G_{2}=\operatorname{span}\left\{g_{5}, g_{6}, g_{7}\right.$, $\left.g_{8}\right\}$, then we have

$$
\begin{equation*}
G=G_{1} \oplus G_{2}, \quad G_{1} \cong H, \quad\left[G_{1}, G_{2}\right] \subset G_{2} . \tag{6}
\end{equation*}
$$

Here we need to emphasize that the subalgebras $G_{1}$ and $G_{2}$ are both nonsemisimple, which is very important for deriving nonlinear integrable couplings of hierarchies. By using the Lie algebra $G$, we can construct a few kinds of loop algebras $\widetilde{G}=$ $G \otimes \lambda^{N n+j}, N$ and $j$ stand for natural numbers. Among these loop algebras, the simplest one is

$$
\begin{equation*}
\widetilde{G}=\operatorname{span}\left\{g_{i}(n)\right\}_{i=1}^{8}, \quad g_{i}(n)=g_{i} \lambda^{n}, \tag{7}
\end{equation*}
$$

along with the commutators $\left[g_{i}(m), g_{j}(n)\right]=\left[g_{i}, g_{j}\right] \lambda^{m+n}$, $\operatorname{deg}\left(g_{i}(n)\right)=n, m, n \in Z, 1 \leq i$, and $j \leq 8$.

In this section, by virtue of the Lie algebra $H$, we construct an 8 -dimensional matrix Lie algebra $G$ and corresponding loop algebra $\widetilde{G}$; in what follows we will generate the nonlinear integrable couplings of hierarchies by using the loop algebra $\widetilde{G}$.

## 3. Nonlinear Integrable Couplings of Hierarchies

In this section, based on the loop algebra $\widetilde{G}$, we construct two isospectral problems to generate the nonlinear integrable couplings of the Levi hierarchy and the WKI hierarchy, respectively.
3.1. Nonlinear Integrable Couplings of Levi Hierarchy. Take the following isospectral problem:

$$
\begin{gather*}
\phi_{x}=U \phi, \quad \lambda_{t}=0 \\
U=\frac{1}{2}\left(-\lambda+u_{1}-u_{2}\right)\left(g_{1}(0)-g_{2}(0)\right)+u_{1} g_{3}(0)+u_{2} g_{4}(0) \\
+\frac{1}{2}\left(u_{3}-u_{4}\right)\left(g_{5}(0)-g_{6}(0)\right)+u_{3} g_{7}(0)+u_{4} g_{8}(0) \tag{8}
\end{gather*}
$$

Set $V=v_{1}\left(g_{1}(0)-g_{2}(0)\right)+v_{2} g_{3}(0)+v_{3} g_{4}(0)+v_{4}\left(g_{5}(0)-\right.$ $\left.g_{6}(0)\right)+v_{5} g_{7}(0)+v_{6} g_{8}(0)$, where $v_{i}=\sum_{m \geq 0} v_{i m} \lambda^{-m}, i=$ $1,2,3,4,5,6$. Solving the stationary zero curvature equation $V_{x}=[U, V]$ gives rise to the recursion relation as follows:

$$
\begin{gathered}
v_{1 m x}=u_{1} v_{3 m}-u_{2} v_{2 m}, \\
v_{2 m x}=-v_{2 m+1}+\left(u_{1}-u_{2}\right) v_{2 m}-2 u_{1} v_{1 m}, \\
v_{3 m x}=v_{3 m+1}-\left(u_{1}-u_{2}\right) v_{3 m}+2 u_{2} v_{1 m}, \\
v_{4 m x}=u_{1} v_{6 m}-u_{4} v_{2 m}-u_{2} v_{5 m}+u_{3} v_{3 m}+u_{3} v_{6 m}-u_{4} v_{5 m}, \\
v_{5 m x}=\left(u_{1}-u_{2}\right) v_{5 m}-2 u_{3} v_{1 m}-v_{5 m+1}-2 u_{1} v_{4 m} \\
+\left(u_{3}-u_{4}\right)\left(v_{2 m}+v_{5 m}\right)-2 u_{3} v_{4 m}, \\
v_{6 m x}=2 u_{4} v_{1 m}-\left(u_{1}-u_{2}\right) v_{6 m}+v_{6 m+1}+2 u_{2} v_{4 m} \\
-\left(u_{3}-u_{4}\right)\left(v_{3 m}+v_{6 m}\right)+2 u_{4} v_{4 m}, \\
v_{10}=-\frac{\alpha}{2} \neq 0, \quad v_{20}=v_{30}=v_{40}=v_{50}=v_{60}=0, \\
v_{11}=0, \quad v_{21}=\alpha u_{1}, \quad v_{31}=\alpha u_{2}, \\
v_{41}=0, \quad v_{51}=\alpha u_{3}, \quad v_{61}=\alpha u_{4}, \quad v_{12}=\alpha u_{1} u_{2},
\end{gathered}
$$

$$
\begin{gather*}
v_{22}=\alpha u_{1}\left(u_{1}-u_{2}\right)-\alpha u_{1 x}, \\
v_{32}=\alpha u_{2}\left(u_{1}-u_{2}\right)+\alpha u_{2 x}, \\
v_{42}=\alpha\left(u_{1} u_{4}+u_{2} u_{3}+u_{3} u_{4}\right), \\
v_{52}=\alpha u_{3}\left(u_{1}-u_{2}\right)-\alpha u_{3 x}+\alpha\left(u_{1}+u_{3}\right)\left(u_{3}-u_{4}\right), \\
v_{62}=\alpha u_{4}\left(u_{1}-u_{2}\right)+\alpha u_{4 x}+\alpha\left(u_{2}+u_{4}\right)\left(u_{3}-u_{4}\right) . \tag{9}
\end{gather*}
$$

Denoting $V_{+}^{(n)}=\sum_{m=0}^{n}\left(v_{1 m}, v_{2 m}, v_{3 m}, v_{4 m}, v_{5 m}, v_{6 m}\right)^{T} \lambda^{n-m}$ and $V_{-}^{(n)}=\lambda^{n} V-V_{+}^{(n)}$, it is easy to compute

$$
\begin{align*}
-V_{+x}^{(n)}+\left[U, V_{+}^{(n)}\right]= & v_{2 n+1} g_{3}(0)-v_{3 n+1} g_{4}(0)  \tag{10}\\
& +v_{5 n+1} g_{7}(0)-v_{6 n+1} g_{8}(0)
\end{align*}
$$

Take

$$
\begin{gather*}
V^{(n)}=V_{+}^{(n)}+\Delta_{n} \\
\Delta_{n}=\frac{1}{2}\left(v_{2 n}-v_{3 n}-2 v_{1 n}\right)\left(g_{1}(0)-g_{2}(0)\right)  \tag{11}\\
+\frac{1}{2}\left(v_{5 n}-v_{6 n}-2 v_{4 n}\right)\left(g_{5}(0)-g_{6}(0)\right)
\end{gather*}
$$

Thus, the zero curvature equation

$$
\begin{equation*}
U_{t}-V_{x}^{(n)}+\left[U, V^{(n)}\right]=0 \tag{12}
\end{equation*}
$$

leads to the following integrable system:
$U_{t}$

$$
\begin{aligned}
& =\left(\begin{array}{l}
u_{1} \\
u_{2} \\
u_{3} \\
u_{4}
\end{array}\right)_{t} \\
& =\left(\begin{array}{c}
-v_{2 n+1}+\left(v_{2 n}-v_{3 n}-2 v_{11}\right) u_{1} \\
v_{3 n+1}-\left(v_{2 n}-v_{3 n}-2 v_{1 n}\right) u_{2} \\
-v_{5 n+1}+\left(v_{2 n}-v_{3 n}-2 v_{1 n}\right) u_{3}+\left(v_{5 n}-v_{6 n}-2 v_{4 n}\right)\left(u_{1}+u_{3}\right) \\
v_{6 n+1}-\left(v_{2 n}-v_{3 n}-2 v_{1 n}\right) u_{4}-\left(v_{5 n}-v_{6 n}-2 v_{4 n}\right)\left(u_{2}+u_{4}\right)
\end{array}\right)
\end{aligned}
$$

$$
=\left(\begin{array}{l}
v_{2 n x}-v_{1 n x} \\
v_{3 n x}+v_{1 n x} \\
v_{5 n x}-v_{4 n x} \\
v_{6 n x}+v_{4 n x}
\end{array}\right)
$$

$$
=\left(\begin{array}{cccc}
0 & 0 & 0 & \partial  \tag{13}\\
0 & 0 & \partial & 0 \\
0 & \partial & 0 & -\partial \\
\partial & 0 & -\partial & 0
\end{array}\right)\left(\begin{array}{c}
v_{1 n}+v_{3 n}+v_{4 n}+v_{6 n} \\
-v_{1 n}+v_{2 n}-v_{4 n}+v_{5 n} \\
v_{1 n}+v_{3 n} \\
-v_{1 n}+v_{2 n}
\end{array}\right)=J_{1} P_{n}
$$

where $J_{1}$ is a Hamiltonian operator and $P_{n+1}=L_{1} P_{n}$, the recurrence operator $L_{1}$ is given from (9) by

$$
L_{1}=\left(\begin{array}{cccc}
L_{11} & L_{12} & L_{13} & L_{14}  \tag{14}\\
L_{21} & L_{22} & L_{23} & L_{24} \\
0 & 0 & L_{33} & L_{34} \\
0 & 0 & L_{43} & L_{44}
\end{array}\right)
$$

where

$$
\begin{align*}
& L_{11}=\partial-\left(u_{2}+u_{4}\right)+\partial^{-1}\left(u_{1}+u_{3}\right) \partial \\
& L_{12}=\left(u_{2}+u_{4}\right)+\partial^{-1}\left(u_{2}+u_{4}\right) \partial \\
& L_{13}=-u_{4}+\partial^{-1} u_{3} \partial \\
& L_{14}=u_{4}+\partial^{-1} u_{4} \partial \\
& L_{21}=-\left(u_{1}+u_{3}\right)-\partial^{-1}\left(u_{1}+u_{3}\right) \partial \\
& L_{22}=-\partial+\left(u_{1}+u_{3}\right)-\partial^{-1}\left(u_{2}+u_{4}\right) \partial  \tag{15}\\
& L_{23}=-u_{3}-\partial^{-1} u_{3} \partial \\
& L_{24}=u_{3}-\partial^{-1} u_{4} \partial \\
& L_{33}=\partial-u_{2}+\partial^{-1} u_{1} \partial \\
& L_{34}=u_{2}+\partial^{-1} u_{2} \partial \\
& L_{43}=-u_{1}-\partial^{-1} u_{1} \partial \\
& L_{44}=u_{1}-\partial^{-1} u_{2} \partial-\partial \tag{16}
\end{align*}
$$

Therefore, the system (13) can be written as

$$
\left(\begin{array}{l}
u_{1}  \tag{17}\\
u_{2} \\
u_{3} \\
u_{4}
\end{array}\right)_{t}=J_{1} L_{1}^{n-1}\left(\begin{array}{c}
v_{11}+v_{31}+v_{41}+v_{61} \\
-v_{11}+v_{21}-v_{41}+v_{51} \\
v_{11}+v_{31} \\
-v_{11}+v_{21}
\end{array}\right) .
$$

When $u_{3}=u_{4}=0$, the system (13) reduces to the Levi hierarchy; therefore, in terms of the definition of integrable coupling, we conclude that the system (13) is an integrable coupling of the Levi hierarchy. Especially taking $n=2$, we have the following reduced equations:

$$
\begin{align*}
& u_{1 t}=\alpha\left(u_{1}^{2}-2 u_{1} u_{2}\right)_{x}-\alpha u_{1 x x} \\
& u_{2 t}=\alpha\left(-u_{2}^{2}+2 u_{1} u_{2}\right)_{x}+\alpha u_{2 x x} \\
& u_{3 t}=2 \alpha\left(u_{1} u_{3}-u_{2} u_{3}-u_{1} u_{4}-u_{3} u_{4}\right)_{x}-\alpha u_{3 x x}+\alpha\left(u_{3}^{2}\right)_{x} \\
& u_{4 t}=2 \alpha\left(u_{1} u_{4}-u_{2} u_{4}+u_{3} u_{4}+u_{2} u_{3}\right)_{x}+\alpha u_{4 x x}-\alpha\left(u_{4}^{2}\right)_{x} \tag{18}
\end{align*}
$$

Obviously, (18) are nonlinear equations in $u_{3}$ and $u_{4}$, so we call (13) the nonlinear integrable coupling of the Levi hierarchy.
3.2. Nonlinear Integrable Couplings of WKI Hierarchy. Consider an isospectral problem

$$
\phi_{x}=U \phi, \quad \lambda_{t}=0
$$

$$
\begin{align*}
U= & i\left[g_{2}(1)-g_{1}(1)\right]+u_{1} g_{3}(1)+u_{2} g_{4}(1) \\
& +u_{3} g_{7}(1)+u_{4} g_{8}(1) \tag{19}
\end{align*}
$$

Set $V=\sum_{m \geq 0} \widetilde{V}$, where

$$
\begin{align*}
\widetilde{V}= & {\left[\lambda v_{1 m} g_{1}(-m)-\lambda v_{1 m} g_{2}(-m)+\left(v_{2 m x}+i \lambda u_{1} v_{1 m}\right)\right.} \\
& \times g_{3}(-m)+\left(v_{3 m x}+i \lambda u_{2} v_{1 m}\right) g_{4}(-m) \\
& +\lambda v_{4 m} g_{5}(-m)-\lambda v_{4 m} g_{6}(-m) \\
& +\left(v_{5 m x}+i \lambda u_{3} v_{1 m}+i \lambda u_{1} v_{4 m}+i \lambda u_{3} v_{4 m}\right) g_{7}(-m) \\
& \left.+\left(v_{6 m x}+i \lambda u_{4} v_{1 m}+i \lambda u_{2} v_{4 m}+i \lambda u_{4} v_{4 m}\right) g_{8}(-m)\right] \tag{20}
\end{align*}
$$

Because every term in $U$ includes $\lambda, V$ is different from the common form and includes potentials $u_{1}, u_{2}, u_{3}$, and $u_{4}$ and $v_{2 m x}, v_{3 m x}, v_{5 m x}, v_{6 m x}$, and so on. Then the zero curvature equation $V_{x}=[U, V]$ yields

$$
\begin{gathered}
v_{1 m x}=u_{1} v_{3 m x}-u_{2} v_{2 m x} \\
i\left(u_{1} v_{1 m+1}\right)_{x}+v_{2 m x x}=-2 i v_{2 m+1 x}, \\
i\left(u_{2} v_{1 m+1}\right)_{x}+v_{3 m x x}=2 i v_{3 m+1 x}, \\
v_{4 m x}=u_{1} v_{6 m x}-u_{2} v_{5 m x}+u_{3} v_{3 m x}-u_{4} v_{2 m x} \\
+u_{3} v_{6 m x}-u_{4} v_{5 m x}
\end{gathered}
$$

$$
i\left(u_{3} v_{1 m+1}+u_{1} v_{4 m+1}+u_{3} v_{4 m+1}\right)_{x}+v_{5 m x x}=-2 i v_{5 m+1 x}
$$

$$
i\left(u_{4} v_{1 m+1}+u_{2} v_{4 m+1}+u_{4} v_{4 m+1}\right)_{x}+v_{6 m x x}=2 i v_{6 m+1 x}
$$

$$
v_{10}=\alpha_{1}, \quad v_{20}=\alpha_{2}, \quad v_{30}=\alpha_{3},
$$

$$
v_{40}=\alpha_{4}, \quad v_{50}=\alpha_{5}, \quad v_{60}=\alpha_{6},
$$

$$
v_{11}=\frac{2}{p}, \quad v_{21}=\frac{-u_{1}}{p}, \quad v_{31}=\frac{u_{2}}{p},
$$

$$
v_{41}=-\frac{2}{p}-\frac{2}{p^{\prime}}, \quad v_{51}=\frac{u_{1}}{p}+\frac{u_{1}+u_{3}}{p^{\prime}}
$$

$$
v_{61}=-\frac{u_{2}}{p}-\frac{u_{2}+u_{4}}{p^{\prime}}, \quad p=\sqrt{1-u_{1} u_{2}}
$$

$$
p^{\prime}=\sqrt{1-\left(u_{1}+u_{3}\right)\left(u_{2}+u_{4}\right)}
$$

Denoting $V_{+}^{(n)}=\sum_{m=0}^{n} \widetilde{V}=\lambda^{n} V-V_{-}^{(n)}$, then we have $-V_{+x}^{(n)}+$ $\left[U, V_{+}^{(n)}\right]=V_{-x}^{(n)}-\left[U, V_{-}^{(n)}\right]$. A direct calculation reads

$$
\begin{align*}
-V_{+x}^{(n)}+\left[U, V_{+}^{(n)}\right]= & -\lambda v_{2 n-1 x x} g_{3}(0)-\lambda v_{3 n-1 x x} g_{4}(0) \\
& -\lambda v_{5 n-1 x x} g_{7}(0)-\lambda v_{6 n-1 x x} g_{8}(0) \tag{22}
\end{align*}
$$

Therefore, the zero curvature equation

$$
\begin{equation*}
U_{t}-V_{x}^{(n)}+\left[U, V^{(n)}\right]=0 \tag{23}
\end{equation*}
$$

admits

$$
\begin{align*}
U_{t}= & \left(\begin{array}{l}
u_{1} \\
u_{2} \\
u_{3} \\
u_{4}
\end{array}\right)_{t}=\left(\begin{array}{l}
v_{2 n-1 x x} \\
v_{3 n-1 x x} \\
v_{5 n-1 x x} \\
v_{6 n-1 x x}
\end{array}\right)=\left(\begin{array}{cccc}
0 & 0 & 0 & \partial^{2} \\
0 & 0 & -\partial^{2} & 0 \\
0 & \partial^{2} & 0 & -\partial^{2} \\
-\partial^{2} & 0 & \partial^{2} & 0
\end{array}\right) \\
& \times\left(\begin{array}{c}
-v_{3 n-1}-v_{6 n-1} \\
v_{2 n-1}+v_{5 n-1} \\
-v_{3 n-1} \\
v_{2 n-1}
\end{array}\right)=J_{2} Q_{n-1} . \tag{24}
\end{align*}
$$

Here $J_{2}$ is a Hamiltonian operator and $Q_{n}=L_{2} Q_{n-1}$, the recurrence operator $L_{2}$ is given from (21) by

$$
L_{2}=\left(\begin{array}{cccc}
L_{11} & L_{12} & L_{13} & L_{14}  \tag{25}\\
L_{21} & L_{22} & L_{23} & L_{24} \\
0 & 0 & L_{33} & L_{34} \\
0 & 0 & L_{43} & L_{44}
\end{array}\right)
$$

where

$$
\begin{aligned}
& L_{11}=-\frac{i}{2} \partial-\frac{i}{4} \frac{u_{2}+u_{4}}{p^{\prime}} \partial^{-1} \frac{u_{1}+u_{3}}{p^{\prime}} \partial^{2}, \\
& L_{12}= \frac{i}{4} \frac{u_{2}+u_{4}}{p^{\prime}} \partial^{-1} \frac{u_{2}+u_{4}}{p^{\prime}} \partial^{2}, \\
& L_{13}=-\frac{i}{4}\left[\frac{u_{2}+u_{4}}{p^{\prime}} \partial^{-1} \frac{1}{p^{\prime}}\left(-u_{1} \partial^{2}+q \partial \frac{q}{p} \partial^{-1} \frac{u_{1}}{p} \partial^{2}\right)\right. \\
&\left.+\frac{u_{2}+u_{4}}{p} \partial^{-1} \frac{u_{1}}{p} \partial^{2}\right], \\
& L_{14}=\frac{i}{4}\left[\frac{u_{2}+u_{4}}{p^{\prime}} \partial^{-1} \frac{1}{p^{\prime}}\left(-u_{2} \partial^{2}+q \partial \frac{q}{p} \partial^{-1} \frac{u_{2}}{p} \partial^{2}\right)\right. \\
&\left.+\frac{u_{2}+u_{4}}{p} \partial^{-1} \frac{u_{2}}{p} \partial^{2}\right],
\end{aligned}
$$

$$
\begin{align*}
L_{21}= & -\frac{i}{4} \frac{u_{1}+u_{3}}{p^{\prime}} \partial^{-1} \frac{u_{1}+u_{3}}{p^{\prime}} \partial^{2}, \\
L_{22}= & \frac{i}{2} \partial+\frac{i}{4} \frac{u_{1}+u_{3}}{p^{\prime}} \partial^{-1} \frac{u_{2}+u_{4}}{p^{\prime}} \partial^{2}, \\
L_{23}= & -\frac{i}{4}\left[\frac{u_{1}+u_{3}}{p^{\prime}} \partial^{-1} \frac{1}{p^{\prime}}\left(-u_{1} \partial^{2}+q \partial \frac{q}{p} \partial^{-1} \frac{u_{1}}{p} \partial^{2}\right)\right. \\
L_{24}= & \frac{i}{4}\left[\frac{u_{1}+u_{3}}{p^{\prime}} \partial^{-1} \frac{1}{p^{\prime}} \partial^{2} \frac{1}{p^{\prime}} \partial^{-1}\right. \\
& \left.+\frac{u_{1}+u_{3}}{p} \partial^{-1} \frac{u_{1}}{p} \partial^{2}\right], \\
& \times \frac{1}{p^{\prime}}\left(-u_{2} \partial^{2}+q \partial \frac{q}{p} \partial^{-1} \frac{u_{2}}{p} \partial^{2}\right) \\
& \left.+\frac{u_{1}+u_{3}}{p} \partial^{-1} \frac{u_{2}}{p} \partial^{2}\right], \\
L_{33}= & -\frac{i}{2} \partial-\frac{i}{4} \frac{u_{2}}{p} \partial^{-1} \frac{u_{1}}{p} \partial^{2}, \\
L_{34}= & \frac{i}{4} \frac{u_{2}}{p} \partial^{-1} \frac{u_{2}}{p} \partial^{2}, \\
L_{43}= & -\frac{i}{4} \frac{u_{1}}{p} \partial^{-1} \frac{u_{1}}{p} \partial^{2} \\
L_{44}= & \frac{i}{2} \partial+\frac{i}{4} \frac{u_{1}}{p} \partial^{-1} \frac{u_{2}}{p} \partial^{2} . \tag{26}
\end{align*}
$$

Here $p, p^{\prime}$ are given in (21) and $q=\sqrt{u_{1} u_{4}+u_{2} u_{3}+u_{3} u_{4}}$. Hence, the system (24) can be written as

$$
\left(\begin{array}{c}
u_{1}  \tag{27}\\
u_{2} \\
u_{3} \\
u_{4}
\end{array}\right)_{t}=J_{2} L_{2}^{n-2}\left(\begin{array}{c}
v_{31}+v_{61} \\
v_{21}+v_{51} \\
v_{31} \\
v_{21}
\end{array}\right)
$$

where $a=\left(a_{1}, \ldots, a_{8}\right)^{T}$ and $b=\left(b_{1}, \ldots, b_{8}\right)^{T}$. From (29), we have

$$
R(b)=\left(\begin{array}{cccccccc}
0 & 0 & b_{3} & -b_{4} & 0 & 0 & b_{7} & -b_{8}  \tag{30}\\
0 & 0 & -b_{3} & b_{4} & 0 & 0 & -b_{7} & b_{8} \\
b_{4} & -b_{4} & b_{2}-b_{1} & 0 & b_{8} & -b_{8} & b_{6}-b_{5} & 0 \\
-b_{3} & b_{3} & 0 & b_{1}-b_{2} & -b_{7} & b_{7} & 0 & b_{5}-b_{6} \\
0 & 0 & 0 & 0 & 0 & 0 & b_{3}+b_{7} & -b_{4}-b_{8} \\
0 & 0 & 0 & 0 & 0 & 0 & -b_{3}-b_{7} & b_{4}+b_{8} \\
0 & 0 & 0 & 0 & b_{4}+b_{8} & -b_{4}-b_{8} & b_{2}-b_{1}-b_{5}+b_{6} & 0 \\
0 & 0 & 0 & 0 & -b_{3}-b_{7} & b_{3}+b_{7} & 0 & b_{1}-b_{2}+b_{5}-b_{6}
\end{array}\right) .
$$

Solving the matrix equation for the constant matrix $F$, $R(b) F=-(R(b) F)^{T}, F^{T}=F$,

$$
F=\left(\begin{array}{llllllll}
1 & 0 & 0 & 0 & 1 & 0 & 0 & 0  \tag{31}\\
0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\
1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 1 & 0 & 0 & 0 & 0 & 0
\end{array}\right)
$$

Then in terms of $F$, define a linear functional in the $R^{8}$

$$
\begin{align*}
\{a, b\}= & a^{T} F b=\left(a_{1}+a_{5}\right) b_{1}+\left(a_{2}+a_{6}\right) b_{2}+\left(a_{4}+a_{8}\right) b_{3} \\
& +\left(a_{3}+a_{7}\right) b_{4}+a_{1} b_{5}+a_{2} b_{6}+a_{4} b_{7}+a_{3} b_{8} . \tag{32}
\end{align*}
$$

It is easy to find that $\{a, b\}$ satisfies the variational identity

$$
\begin{equation*}
\frac{\delta}{\delta u} \int\left\{V, U_{\lambda}\right\} d x=\lambda^{-\gamma} \frac{\partial}{\partial \lambda} \lambda^{\gamma}\left\{V, U_{u}\right\} \tag{33}
\end{equation*}
$$

Rewrite the Lax pair of nonlinear integrable coupling of the Levi hierarchy as follows:

$$
\begin{align*}
& U=\left(\frac{1}{2}\left(u_{1}-u_{2}-\lambda\right), \frac{1}{2}\left(\lambda-u_{1}+u_{2}\right), u_{1}, u_{2}\right. \\
&\left.\frac{1}{2}\left(u_{3}-u_{4}\right), \frac{1}{2}\left(u_{4}-u_{3}\right), u_{3}, u_{4}\right)^{T}  \tag{34}\\
& V=\left(v_{1},-v_{1}, v_{2}, v_{3}, v_{4},-v_{4}, v_{5}, v_{6}\right)^{T}
\end{align*}
$$

By using (32), we have

$$
\begin{gather*}
\left\{V, U_{\lambda}\right\}=-v_{1}-v_{4}, \quad\left\{V, U_{u_{1}}\right\}=v_{1}+v_{3}+v_{4}+v_{6} \\
\left\{V, U_{u_{2}}\right\}=-v_{1}+v_{2}-v_{4}+v_{5}  \tag{35}\\
\left\{V, U_{u_{3}}\right\}=v_{1}+v_{3}, \quad\left\{V, U_{u_{4}}\right\}=-v_{1}+v_{2}
\end{gather*}
$$

According the variational identity (33), we have

$$
\begin{align*}
& \frac{\delta}{\delta u} \int\left(-v_{1}-v_{4}\right) d x \\
& =\lambda^{-\gamma} \frac{\partial}{\partial \lambda} \lambda^{\gamma}\left(v_{1}+v_{3}+v_{4}+v_{6},-v_{1}+v_{2}\right.  \tag{36}\\
& \left.\quad-v_{4}+v_{5}, v_{1}+v_{3},-v_{1}+v_{2}\right)^{T}
\end{align*}
$$

Comparing the coefficients of $\lambda^{-n-2}$ yields

$$
\begin{align*}
\frac{\delta}{\delta u} \int\left(-v_{1 n+1}-v_{4 n+1}\right) d x= & (\gamma-n) \\
& \times\left(\begin{array}{c}
v_{1 n}+v_{3 n}+v_{4 n}+v_{6 n} \\
-v_{1 n}+v_{2 n}-v_{4 n}+v_{5 n} \\
v_{1 n}+v_{3 n} \\
-v_{1 n}+v_{2 n}
\end{array}\right) \tag{37}
\end{align*}
$$

Taking $n=1$ gives rise to $\gamma=0$. Therefore,

$$
\begin{array}{r}
P_{n}=\frac{\delta H_{n}}{\delta u}, \quad H_{n}=\int \frac{a_{n+1}+d_{n+1}}{n} d x,  \tag{38}\\
n \geq 1 .
\end{array}
$$

Hence, the nonlinear integrable coupling of the Levi hierarchy has the following Hamiltonian structure:

$$
\begin{equation*}
U_{t}=J_{1} \frac{\delta H_{n}}{\delta u}, \quad n \geq 1 \tag{39}
\end{equation*}
$$

Similar to (34), in order to deduce to the Hamiltonian structure of the nonlinear integrable coupling of the WKI hierarchy, we rewrite the Lax pair as follows:

$$
\begin{align*}
& U=\left(-i \lambda, i \lambda, \lambda u_{1}, \lambda u_{2}, 0,0, \lambda u_{3}, \lambda u_{4}\right)^{T} \\
& V=\left(\lambda v_{1},-\lambda v_{1}, v_{2 x}+i \lambda u_{1} v_{1}, v_{3 x}+i \lambda u_{2} v_{1}, \lambda v_{4}\right. \\
&  \tag{40}\\
& - \\
& \quad \lambda v_{4}, v_{5 x}+i \lambda u_{3}\left(v_{1}+v_{4}\right) \\
& \\
& \left.+i \lambda u_{1} v_{4}, v_{6 x}+i \lambda u_{4}\left(v_{1}+v_{4}\right)+i \lambda u_{2} v_{4}\right)^{T}
\end{align*}
$$

Repeat the above procedure; we have

$$
\begin{gather*}
\left\{V, U_{\lambda}\right\}=-2 i\left(v_{1}+v_{4}\right)+2 i u_{1}\left(v_{3}+v_{6}\right) \\
-2 i u_{2}\left(v_{2}+v_{5}\right)+2 i u_{3} v_{3}-2 i u_{4} v_{2}, \\
\left\{V, U_{u_{1}}\right\}=2 i\left(v_{3}+v_{6}\right), \quad\left\{V, U_{u_{2}}\right\}=-2 i\left(v_{2}+v_{5}\right), \\
\left\{V, U_{u_{3}}\right\}=2 i v_{3}, \quad\left\{V, U_{u_{4}}\right\}=-2 i v_{2}, \\
\frac{\delta}{\delta u} \int 2 i\left[-\left(v_{1 n-1}+v_{4 n-1}\right)+u_{1}\left(v_{3 n-1}+v_{6 n-1}\right)\right.  \tag{41}\\
\left.-u_{2}\left(v_{2 n-1}+v_{5 n-1}\right)+u_{3} v_{3 n-1}-u_{4} v_{2 n-1}\right] d x \\
=2 i(2+\gamma-n)\left(\begin{array}{c}
-v_{3 n-1}-v_{6 n-1} \\
v_{2 n-1}+v_{5 n-1} \\
-v_{3 n-1} \\
v_{2 n-1}
\end{array}\right)
\end{gather*}
$$

Taking $n=2$ in above equation gives $\gamma=-1$. Therefore, $Q_{n-1}=\left(\delta \widetilde{H}_{n-1} / \delta u\right), n \geq 2$, where

$$
\begin{align*}
\widetilde{H}_{n-1}=\int & \left(\left(v_{1 n-1}-v_{4 n-1}\right)-u_{1}\left(v_{3 n-1}-v_{6 n-1}\right)\right. \\
& +u_{2}\left(v_{2 n-1}-v_{5 n-1}\right)-u_{3} v_{3 n-1}  \tag{42}\\
& \left.+u_{4} v_{2 n-1}\right) \\
& \times(n-1)^{-1} d x
\end{align*}
$$

Hence, the nonlinear integrable coupling of the WKI hierarchy has the following Hamiltonian structure:

$$
\begin{equation*}
U_{t}=J_{2} \frac{\delta \widetilde{H}_{n-1}}{\delta u}, \quad n \geq 2 \tag{43}
\end{equation*}
$$

## 5. Conclusions

In this paper, we presented a set of new 8-dimensional matrix Lie algebra by virtue of the Lie algebra given in [14-16]. With the help of the Lie algebra, we obtain the nonlinear integrable couplings of the Levi hierarchy and the WKI hierarchy. Their Hamiltonian structures are also worked out by the variational identity. The Lie algebra constructed in this paper can be used to generate the nonlinear integrable couplings of other hierarchies. We will study these problems in the future.

## Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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