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Research Article

Impulsive Boundary Value Problems for Planar Hamiltonian Systems

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We give an existence and uniqueness theorem for solutions of inhomogeneous impulsive boundary value problem (BVP) for planar Hamiltonian systems. Green's function that is needed for representing the solutions is obtained and its properties are listed. The uniqueness of solutions is connected to a Lyapunov type inequality for the corresponding homogeneous BVP.

1. Introduction

The planar Hamiltonian system of 2-linear first-order equations has the form

$$y' = JH(t) y, \quad t \in \mathbb{R}, \tag{1}$$

where

$$H(t) = \begin{bmatrix} c(t) & a(t) \\ a(t) & b(t) \end{bmatrix}$$
 (2)

is a symmetric matrix with piecewise continuous real-valued entries, and

$$J = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \tag{3}$$

is the so called symplectic identity. Setting

$$y_1(t) = x(t), y_2(t) = u(t), (4)$$

the Hamiltonian system can be rewritten in a more convenient way as

$$x' = a(t) x + b(t) u,$$

 $u' = -c(t) x - a(t) u.$ (5)

Our aim in this work is to prove an existence and uniqueness theorem for solutions of the related BVP for

inhomogeneous Hamiltonian system under impulse effect of the form

$$x' = a(t) x + b(t) u + f_1(t),$$

$$u' = -c(t) x - a(t) u + f_2(t),$$

$$t \in (t_1, t_2) \setminus \{\tau_i\},$$
(6a)

$$x(\tau_{i}^{+}) = \alpha_{i}x(\tau_{i}^{-}) + a_{i1},$$

$$u(\tau_{i}^{+}) = -\beta_{i}x(\tau_{i}^{-}) + \alpha_{i}u(\tau_{i}^{-}) + a_{i2},$$

$$i = 1, 2, \dots, p,$$
(6b)

$$x(t_1) = A, \quad x(t_2) = B,$$
 (6c)

where

(i) $\{\tau_i\}$, $\{\alpha_i\}$, $\{\beta_i\}$, $\{a_{i1}\}$, and $\{a_{i2}\}$ are real sequences for $i = 1, 2, \dots, p$ with

$$t_1 < \tau_1 < \tau_2 < \dots < \tau_p < t_2;$$
 (7)

- (ii) $a,b,c,f_1,f_2 \in PLC(J_0)$, where $J_0 = [t_1,t_2]$ and $PLC(J_0) = \{\omega: J_0 \rightarrow \mathbb{R} \text{ is continuous on each interval } (\tau_i,\tau_{i+1}), \text{ the limits } w(\tau_i^{\pm}) \text{ exist and } w(\tau_i^{-}) = w(\tau_i) \text{ for } i=1,2,\ldots,p\};$
- (iii) b(t) > 0 for $t \in (t_1, t_2)$ and $\alpha_i \neq 0$ for i = 1, 2, ..., p; A and B are given real numbers.

We also set $\tau_0 = t_1$ and $\tau_{p+1} = t_2$ for convenience.

By a solution of the impulsive BVP (6a)–(6c), we mean nontrivial functions $x, u \in PLC(J_0)$ such that (x, u) satisfies system (6a)–(6c) for all $t \in J_0$.

The corresponding homogeneous BVP takes the form

$$x' = a(t) x + b(t) u, u' = -c(t) x - a(t) u, (8a)$$

$$t \in (t_1, t_2) \setminus \{\tau_i\}, x(\tau_i^+) = \alpha_i x(\tau_i^-), u(\tau_i^+) = -\beta_i x(\tau_i^-) + \alpha_i u(\tau_i^-), i = 1, 2, \dots, p,$$

$$x(t_1) = 0,$$
 $x(t_2) = 0.$ (8c)

Note that if we take

$$a(t) \equiv 0,$$
 $b(t) = \frac{1}{p(t)},$ $c(t) = q(t),$ (9)
 $f_1(t) \equiv 0,$ $f_2(t) = f(t),$

then we obtain as a special case of (6a), (6b), and (6c) the impulsive BVP for second-order differential equations of the form

$$(p(t)x')' + q(t)x = f(t), t \in (t_1, t_2) \setminus \{\tau_i\},$$
 (10a)

$$x\left(\tau_{i}^{+}\right) = \alpha_{i}x\left(\tau_{i}^{-}\right) + a_{i1},\tag{10b}$$

$$(px')(\tau_i^+) = -\beta_i x (\tau_i^-) + \alpha_i (px')(\tau_i^-)$$

$$+ a_{i2}, \quad i = 1, 2, \dots, p,$$
(10c)

$$x(t_1) = A, x(t_2) = B.$$
 (10d)

To the best of our knowledge although many results have been obtained for linear impulsive boundary value problems by using different techniques, there is little known for the linear 2×2 Hamiltonian systems under impulse effect.

The existence and uniqueness of linear impulsive boundary value problem for the first-order equations are considered in [1–4]. For the second-order case we refer to [5, 6] in which the integral representation of the solution of second order linear impulsive boundary value problems is given by using Green's function and the existence and uniqueness of the solutions are obtained. Variational technique approach for the existence of the solutions of linear and nonlinear impulsive boundary value problems can be found in [7–10]. In [11], the method of upper and lower solutions is employed for the existence of solutions of nonlinear impulsive boundary value problems. For a detailed discussion on boundary value problems for higher-order linear impulsive equations we refer to [12]. Basic theory of impulsive differential equations is contained in the seminal book [13].

Our method of proof is based on Green's function formulation and Lyapunov type inequalities for linear Hamiltonian system under impulse effect. There are many studies on Lyapunov type inequalities and their applications for linear ordinary differential equations [14] and for systems [15–17] as

well as for linear impulsive differential equations and systems [18, 19]. However, the use of a Lyapunov type inequality in connection with BVPs seems to be limited.

2. Preliminaries

2.1. Lyapunov Type Inequality for Homogeneous Problem. In this section we provide a Lyapunov type inequality to be used for the uniqueness of the inhomogeneous BVP. The obtained inequality is sharper than the one given by the present authors in [20] in the sense that 2|a(t)| is replaced by |a(t)|.

Theorem 1. If the homogeneous BVP (8a), (8b), and (8c) has a real solution (x(t), u(t)) such that $x(t) \not\equiv 0$ on (t_1, t_2) , then one has the Lyapunov type inequality:

$$\exp\left(\int_{t_{1}}^{t_{2}} |a(t)| dt\right) \left[\int_{t_{1}}^{t_{2}} b(t) dt\right] \times \left[\int_{t_{1}}^{t_{2}} c^{+}(t) dt + \sum_{t_{1} \le \tau_{i} < t_{2}} \left(\frac{\beta_{i}}{\alpha_{i}}\right)^{+}\right] \ge 4,$$
(11)

where $c^{+}(t) = \max\{c(t), 0\}$ and $(\beta_i/\alpha_i)^{+} = \max\{\beta_i/\alpha_i, 0\}$.

Proof. Define

(8b)

$$z(t) = \frac{1}{\alpha_1 \alpha_2 \cdots \alpha_i} x(t), \qquad v(t) = \frac{1}{\alpha_1 \alpha_2 \cdots \alpha_i} u(t)$$
 (12)

for $t \in (\tau_i, \tau_{i+1})$ and $i = 0, 1, \ldots, p$, where we put again $\tau_0 = t_1$, $\tau_{p+1} = t_2$ and make a convention that $\alpha_1 \alpha_2 \cdots \alpha_i = 1$ if i = 0.

It is not difficult to see from (8a), (8b), (8c), and (12) that

$$z' = a(t)z + b(t)v, v' = -c(t)z - a(t)v,$$

$$t \in (t_1, t_2) \setminus \{\tau_i\},$$
(13)

$$z\left(\tau_{i}^{+}\right)=z\left(\tau_{i}^{-}\right),$$

$$\nu\left(\tau_{i}^{+}\right) = -\frac{\beta_{i}}{\alpha_{i}}z\left(\tau_{i}^{-}\right) + \nu\left(\tau_{i}^{-}\right),\tag{14}$$

$$i = 1, 2, \ldots, p,$$

$$z(t_1) = 0, z(t_2) = 0.$$
 (15)

Since we assumed that $z(\tau_i) = z(\tau_i^-)$, z(t) is continuous on $[t_1,t_2]$. Moreover, $z' \in PLC(J_0)$, $z(t_1) = z(t_2) = 0$, and $z(t) \not\equiv 0$ for all $t \in (t_1,t_2)$. We may assume without loss of generality that $z(t) \geq 0$ on (t_1,t_2) .

Using (13) and (14) we obtain

$$(vz)' = -c(t)z^2 + b(t)v^2, \quad t \neq \tau_i,$$
 (16)

$$(vz)\left(\tau_{i}^{+}\right)-(vz)\left(\tau_{i}^{-}\right)=-\frac{\beta_{i}}{\alpha_{i}}z^{2}\left(\tau_{i}\right). \tag{17}$$

Integrating (16) from t_1 to t_2 and using (15) and (17) lead to

$$\sum_{t_{1} \leq \tau_{i} < t_{2}} \frac{\beta_{i}}{\alpha_{i}} z^{2} (\tau_{i}) = \int_{t_{1}}^{t_{2}} \left[b(t) v^{2}(t) - c(t) z^{2}(t) \right] dt, \quad (18)$$

from which we have

$$\int_{t_{1}}^{t_{2}} b(t) v^{2}(t) dt \leq \int_{t_{1}}^{t_{2}} c^{+}(t) z^{2}(t) dt + \sum_{t_{1} \leq \tau_{i} \leq t_{2}} \left(\frac{\beta_{i}}{\alpha_{i}}\right)^{+} z^{2}(\tau_{i}).$$
(19)

On the other hand, from the first equation in (13), we have

$$\left[z(t)\exp\left(-\int_{t_1}^t a(u)du\right)\right]' = b(t)v(t)\exp\left(-\int_{t_1}^t a(u)du\right),$$
(20)

$$\left[z(t)\exp\left(\int_{t}^{t_{2}}a(u)du\right)\right]'=b(t)v(t)\exp\left(\int_{t}^{t_{2}}a(u)du\right). \tag{21}$$

Let

$$\max\{|z(t)|: t \in (t_1, t_2)\} = z(t_0) > 0.$$
 (22)

If we integrate (20) from t_1 to t_0 , we see that

$$z(t_0) = \int_{t_1}^{t_0} b(t) v(t) \exp\left(\int_{t}^{t_0} a(u) du\right) dt$$
 (23)

and so

$$z\left(t_{0}\right) \leq \int_{t_{1}}^{t_{0}} b\left(t\right) \left|v\left(t\right)\right| \exp\left(\int_{t}^{t_{0}} \left|a\left(u\right)\right| du\right) dt. \tag{24}$$

Using the obvious estimate

$$\int_{t}^{t_{0}} |a(u)| \, \mathrm{d}u \le \int_{t_{0}}^{t_{0}} |a(u)| \, \mathrm{d}u \tag{25}$$

and then applying Cauchy-Schwarz inequality, we have

$$z^{2}(t_{0}) \leq \exp\left(2\int_{t_{1}}^{t_{0}}|a(u)|\,\mathrm{d}u\right)\left[\int_{t_{1}}^{t_{0}}b(t)\,\mathrm{d}t\right] \times \left[\int_{t_{1}}^{t_{0}}b(t)\,v^{2}(t)\,\mathrm{d}t\right]. \tag{26}$$

Similarly, by integrating (21) from t_0 to t_2 and following the above procedure, we get

$$z^{2}(t_{0}) \leq \exp\left(2\int_{t_{0}}^{t_{2}}|a(u)|\,\mathrm{d}u\right)\left[\int_{t_{0}}^{t_{2}}b(t)\,\mathrm{d}t\right] \times \left[\int_{t_{0}}^{t_{2}}b(t)\,v^{2}(t)\,\mathrm{d}t\right]. \tag{27}$$

Now we recall the elementary inequality:

$$\frac{x^2}{\alpha} + \frac{y^2}{\beta} \ge 4xy, \quad \alpha, \beta > 0, \ \alpha + \beta = 1$$
 (28)

for $x \ge 0$ and $y \ge 0$. In view of (26) and (27) setting

$$\alpha = \frac{\int_{t_1}^{t_0} b(t) dt}{\int_{t_1}^{t_2} b(t) dt}, \qquad \beta = \frac{\int_{t_0}^{t_2} b(t) dt}{\int_{t_1}^{t_2} b(t) dt},$$

$$x = z(t_0) \exp\left(-\int_{t_1}^{t_0} |a(u)| du\right),$$

$$y = z(t_0) \exp\left(-\int_{t_0}^{t_2} |a(u)| du\right)$$
(29)

we have

$$\frac{4z^{2}(t_{0})}{\exp\left(\int_{t_{1}}^{t_{2}}|a(t)|\,\mathrm{d}t\right)} \leq \left[\int_{t_{1}}^{t_{2}}b(t)\,\mathrm{d}t\right]\left[\int_{t_{1}}^{t_{2}}b(t)\,v^{2}(t)\,\mathrm{d}t\right].$$
(30)

Combining (19) and (30) results in

$$\frac{4z^{2}(t_{0})}{\exp\left(\int_{t_{1}}^{t_{2}}|a(t)|dt\right)}$$

$$\leq \left[\int_{t_{1}}^{t_{2}}b(t)dt\right]$$

$$\times \left[\int_{t_{1}}^{t_{2}}c(t)z^{2}(t)dt + \sum_{t_{1}\leq\tau_{i}< t_{2}}\left(\frac{\beta_{i}}{\alpha_{i}}\right)z^{2}(\tau_{i})\right].$$
(31)

Finally, since $z(t_0) \ge z(t)$ for $t \in [t_1, t_2]$, from (31) we obtain the desired inequality:

$$\exp\left(\int_{t_{1}}^{t_{2}}|a(t)|\,\mathrm{d}t\right)\left[\int_{t_{1}}^{t_{2}}b(t)\,\mathrm{d}t\right]$$

$$\times\left[\int_{t_{1}}^{t_{2}}c^{+}(t)\,\mathrm{d}t+\sum_{t_{1}\leq\tau_{i}< t_{2}}\left(\frac{\beta_{i}}{\alpha_{i}}\right)^{+}\right]\geq4.$$
(32)

2.2. Green's Function. Here we derive Green's function to be used for the representation of the solutions of the inhomogeneous BVP.

Let

$$\Phi(t) = \begin{bmatrix} x_1(t) & x_2(t) \\ u_1(t) & u_2(t) \end{bmatrix}, \qquad \Phi(0) = I$$
 (33)

be a fundamental matrix for (8a), (8b) and set

$$M = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \qquad N = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}. \tag{34}$$

Define the rectangles

$$R_{11} = [t_1, \tau_1] \times [t_1, \tau_1],$$

$$R_{i1} = (\tau_{i-1}, \tau_i] \times [t_1, \tau_1], \quad i = 2, 3, ..., p + 1,$$

$$R_{1j} = [t_1, \tau_1] \times (\tau_{j-1}, \tau_j], \quad j = 2, 3, ..., p + 1,$$

$$R_{ii} = (\tau_{i-1}, \tau_i] \times (\tau_{i-1}, \tau_i], \quad i, j = 2, 3, ..., p + 1,$$

$$(35)$$

and the triangles

$$T^{u} = \{(t, s) \in [t_{1}, t_{2}] \times [t_{1}, t_{2}] : s > t\},$$

$$T^{l} = \{(t, s) \in [t_{1}, t_{2}] \times [t_{1}, t_{2}] : s < t\},$$

$$T^{u}_{ii} = \{(t, s) \in R_{ii} : s > t\}, \quad i = 1, 2, 3, ..., p + 1,$$

$$T^{l}_{ii} = \{(t, s) \in R_{ii} : s < t\}, \quad i = 1, 2, 3, ..., p + 1.$$

$$(36)$$

Green's function (pair) and its properties are given in the next theorem.

Theorem 2. Suppose that the homogeneous BVP(8a)–(8c) has only the trivial solution. Let

$$K = -[M\Phi(t_1) + N\Phi(t_2)]^{-1}N\Phi(t_2). \tag{37}$$

Note that the inverse of matrix $M\Phi(t_1)+N\Phi(t_2)$ exists in view of the assumption (see also the proof of Theorem 4).

Then the pair of functions

$$G(t,s) = \begin{cases} \Phi(t) (I+K) \Phi^{-1}(s), & s < t, \\ \Phi(t) K \Phi^{-1}(s), & s \ge t, \end{cases}$$

$$\widetilde{G}(t,\tau_{i}^{+}) = \begin{cases} \Phi(t) (I+K) \Phi^{-1}(\tau_{i}^{+}), & \tau_{i} < t, \\ \Phi(t) K \Phi^{-1}(\tau_{i}^{+}), & \tau_{i} \ge t, \end{cases}$$
(38)

constitutes Green's function for (6a), (6b), and (6c). Moreover, we have the following properties:

- (G1) G(t, s) is continuous and bounded on R_{ij} ,
- (G2) $(\partial G(t,s))/\partial t$ is continuous and bounded on the rectangles R_{ij} with $i \neq j$ and on the triangles T_{ii}^u and T_{ii}^l ,
- (G3) G(t, s) satisfies the following jump conditions:

(a)
$$G(\tau_i^+, \tau_i) - G(\tau_i^-, \tau_i) = B_i + (B_i - I)G(\tau_i^-, \tau_i)$$

where $B_i = \begin{bmatrix} \alpha_i & 0 \\ -\beta_i & \alpha_i \end{bmatrix}$,

(b)
$$G(s^+, s) - G(s^-, s) = I, s \neq \tau_i$$

(c)
$$(\partial G(s^+, s)/\partial t) - (\partial G(s^-, s)/\partial t) = JH(s), s \neq \tau_i$$

(G4) G(t, s), considered as a function of t, is left continuous and satisfies

$$y' = JH(t) y, \quad t \in J_s \setminus \{\tau_i\},$$

$$y(\tau_i^+) = B_i y(\tau_i^-), \quad i \in \{i : \tau_i \in J_s\},$$

$$My(t_1) + Ny(t_2) = 0,$$
(39)

where J_s is any of the intervals $[t_1, s)$ or $(s, t_2]$,

(G5)
$$\Delta|_{t=\tau_i}\widetilde{G}(t,\tau_i^+) = \widetilde{G}(\tau_i^+,\tau_i^+) - \widetilde{G}(\tau_i^-,\tau_i^+) = (B_i - I)\widetilde{G}(\tau_i^-,\tau_i^+),$$

(G6) $\widetilde{G}(t,s)$, considered as a function of t, is left continuous and satisfies (39).

Proof. (G1) and (G2) are trivial. Let us consider (G3)(a) follows from

$$G(\tau_i^+, \tau_i) - G(\tau_i^-, \tau_i)$$

$$= \Phi(\tau_i^+) (I + K) \Phi^{-1}(\tau_i) - \Phi(\tau_i^-) K \Phi^{-1}(\tau_i) \qquad (40)$$

$$= B_i + (B_i - I) G(\tau_i^-, \tau_i).$$

To see (b), we write for $s \neq \tau_i$,

$$G(s^{+},s) - G(s^{-},s) = \Phi(s^{+})(I+K)\Phi^{-1}(s) - \Phi(s^{-})K\Phi^{-1}(s) = I.$$
(41)

For (c), let $t \neq \tau_i$; then

$$\frac{\partial G\left(t,s\right)}{\partial t} = \begin{cases} \Phi'\left(t\right)\left(I+K\right)\Phi^{-1}\left(s\right) \\ = JH\left(t\right)\Phi\left(t\right)\left(I+K\right)\Phi^{-1}\left(s\right), & s < t, \\ \Phi'\left(t\right)K\Phi^{-1}\left(s\right) \\ = JH\left(t\right)\Phi\left(t\right)K\Phi^{-1}\left(s\right), & s \geq t, \end{cases}$$

$$\frac{\partial G\left(s^{+},s\right)}{\partial t} - \frac{\partial G\left(s^{-},s\right)}{\partial t} = JH\left(s\right)\Phi\left(s\right)\left(I+K\right)\Phi^{-1}\left(s\right)$$
$$-JH\left(s\right)\Phi\left(s\right)K\Phi^{-1}\left(s\right)$$
$$=JH\left(s\right). \tag{42}$$

Next, we consider (G4). By definition, it is easy to see that G(t,s) is left continuous function at $t=\tau_i$. Let us consider the interval $[t_1,s)$. The later is similar. The first equation in (39) is direct consequences of (c) and the definition of G(t,s). Clearly,

$$G(\tau_{i}^{+}, s) = \Phi(\tau_{i}^{+}) K \Phi^{-1}(s)$$

$$= B_{i} \Phi(\tau_{i}^{-}) K \Phi^{-1}(s) = B_{i} G(\tau_{i}^{-}, s),$$

$$MG(t_{1}, s) + NG(t_{2}, s)$$

$$= M \Phi(t_{1}) K \Phi^{-1}(s)$$

$$+ N \Phi(t_{2}) (I + K) \Phi^{-1}(s)$$

$$= [M \Phi(t_{1}) + N \Phi(t_{2})] K \Phi^{-1}(s)$$

$$+ N \Phi(t_{2}) \Phi^{-1}(s) = 0.$$
(43)

The proofs of (G5) and (G6) are similar to (a) and (G4), respectively. \Box

Remark 3. One can easily rewrite Green's function (pair) in terms of the solutions of system (8a), (8b). Indeed,

$$K = -\left[M\Phi(t_1) + N\Phi(t_2)\right]^{-1}N\Phi(t_2)$$

$$= \frac{1}{x_1(t_1)x_2(t_2) - x_1(t_2)x_2(t_1)}$$

$$\times \begin{bmatrix} x_1(t_2)x_2(t_1) & x_2(t_1)x_2(t_2) \\ -x_1(t_1)x_1(t_2) & -x_1(t_1)x_2(t_2) \end{bmatrix},$$
(44)

and since

$$\det \Phi(t) = \det \Phi(0) \exp\left(\int_{0}^{t} \operatorname{trace}(JH(s)) \, \mathrm{d}s\right)$$

$$\times \prod_{i=1}^{p} \det B_{i} = \prod_{i=1}^{p} \alpha_{i}^{2},$$
(45)

we may write

$$\Phi^{-1}(t) = \frac{1}{\det \Phi(t)} \begin{bmatrix} u_2(t) & -x_2(t) \\ -u_1(t) & x_1(t) \end{bmatrix}$$

$$= \left(\prod_{i=1}^{p} \alpha_i^{-2} \right) \begin{bmatrix} u_2(t) & -x_2(t) \\ -u_1(t) & x_1(t) \end{bmatrix}.$$
(46)

3. The Main Result

Our main result is the following theorem.

Theorem 4. Let (i)–(iii) hold. If

$$\exp\left(\int_{t_{1}}^{t_{2}}|a(t)|\,dt\right)\left[\int_{t_{1}}^{t_{2}}b(t)\,dt\right] \times \left[\int_{t_{1}}^{t_{2}}c^{+}(t)\,dt + \sum_{t_{1}\leq\tau_{i}< t_{2}}\left(\frac{\beta_{i}}{\alpha_{i}}\right)^{+}\right]$$

$$< 4,$$
(47)

then BVP (6a), (6b), and (6c) has a unique solution (x(t), u(t)). Moreover, y = (x(t), u(t)) is expressible as

$$y(t) = w(t) + \int_{t_1}^{t_2} G(t, s) f(s) ds + \sum_{t_1 < \tau_i < t_n} \widetilde{G}(t, \tau_i^+) a_i,$$
 (48)

where

$$w(t) = \Phi(t) [M\Phi(t_1) + N\Phi(t_2)]^{-1} \eta, \quad \eta = (A, B)^T, \quad (49)$$

and Green's function pair (G, \widetilde{G}) is given by (38).

Proof. We first prove the uniqueness. It suffices to show that the homogeneous BVP (8a)–(8c) has only the trivial solution. Let $x(t) \not\equiv 0$ on (t_1, t_2) . By Theorem 1, we see that Lyapunov type inequality (11) holds contradicting the inequality (47). Thus x(t) = 0 for all $t \in [t_1, t_2]$. Moreover, by (6a), (6b), and (6c) we have

$$b(t) u = 0, \quad t \neq \tau_i, \tag{50}$$

which results in u(t) = 0 for $t \neq \tau_i$. Taking limit we see that $u(\tau_i^{\pm}) = 0$. As a result we obtain (x(t), u(t)) = (0, 0) for all $t \in [t_1, t_2]$. This completes the uniqueness of the solutions.

For the existence, we start with the variation of parameters formula and write the general solution of system (6a), (6b) as

$$y(t) = \Phi(t) c + \int_{t_1}^{t} \Phi(t) \Phi^{-1}(s) f(s) ds + \sum_{t_i < t_i < t} \Phi(t) \Phi^{-1}(\tau_i^+) a_i.$$
 (51)

Clearly, the boundary condition is satisfied if

$$[M\Phi(t_{1}) + N\Phi(t_{2})] c$$

$$= \eta - N\Phi(t_{2})$$

$$\times \left[\int_{t_{1}}^{t_{2}} \Phi^{-1}(s) f(s) ds + \sum_{t_{1} \leq \tau_{i} < t_{2}} \Phi^{-1}(\tau_{i}^{+}) a_{i} \right],$$
(52)

where $\eta = (A, B)^T$.

Since we have the uniqueness of solutions, the matrix $M\Phi(t_1) + N\Phi(t_2)$ must have an inverse. Setting

$$K = -[M\Phi(t_1) + N\Phi(t_2)]^{-1}N\Phi(t_2),$$
 (53)

we may solve c from (52) uniquely:

$$c = [M\Phi(t_1) + N\Phi(t_2)]^{-1}\eta$$

$$+ K \left[\int_{t_1}^{t_2} \Phi^{-1}(s) f(s) ds + \sum_{t_1 \le \tau_i < t_2} \Phi^{-1}(\tau_i^+) a_i \right].$$
(54)

Hence,

$$y(t) = \Phi(t) \left[M\Phi(t_1) + N\Phi(t_2) \right]^{-1} \eta + \Phi(t) (I + K)$$

$$\times \left[\int_{t_1}^t \Phi^{-1}(s) f(s) ds + \sum_{t_1 \le \tau_i < t} \Phi^{-1}(\tau_i^+) a_i \right]$$

$$+ \Phi(t) K \left[\int_t^{t_2} \Phi^{-1}(s) f(s) ds + \sum_{t \le \tau_i < t_2} \Phi^{-1}(\tau_i^+) a_i \right].$$
(55)

Therefore the unique solution of the BVP (6a)–(6c) can be expressed as

$$y(t) = w(t) + \int_{t_1}^{t_2} G(t, s) f(s) ds$$

$$+ \sum_{t_i \le \tau_i < t_2} \widetilde{G}(t, \tau_i^+) a_i.$$
(56)

Let us now consider the BVP (10a), (10b), (10c), and (10d). In this case it is not difficult to see that the corresponding Green's function (pair) becomes

$$G(t,s) = \begin{cases} \psi(t) (I+K) \Psi^{-1}(s) \frac{1}{p(s)} e_2, & s < t, \\ \psi(t) K \Psi^{-1}(s) \frac{1}{p(s)} e_2, & s \ge t, \end{cases}$$

$$\widetilde{G}(t,\tau_i^+) = \begin{cases} \psi(t) (I+K) \Psi^{-1}(\tau_i^+), & \tau_i < t, \\ \psi(t) K \Psi^{-1}(\tau_i^+), & \tau_i \ge t, \end{cases}$$
(57)

where $\psi(t) = [\psi_1, \psi_2]$ is the first row of the (Wronskian) matrix:

$$\Psi(t) = \begin{bmatrix} \psi_{1}(t) & \psi_{2}(t) \\ \psi'_{1}(t) & \psi'_{2}(t) \end{bmatrix},
K = -[M\Psi(t_{1}) + N\Psi(t_{2})]^{-1}N\Psi(t_{2}),
e_{2} = [0, 1]^{T}.$$
(58)

Corollary 5. Suppose that p and c are piece-wise continuous on $[t_1, t_2]$, p(t) > 0, and $\alpha_i \neq 0$ for i = 1, 2, ..., p. If

$$\left[\int_{t_1}^{t_2} \frac{1}{p(t)} dt \right] \left[\int_{t_1}^{t_2} c^+(t) dt + \sum_{t_1 \le \tau_i < t_2} \left(\frac{\beta_i}{\alpha_i} \right)^+ \right] < 4, \quad (59)$$

then the BVP (10a), (10b), (10c), and (10d) has a unique solution x(t) which is expressible as

$$x(t) = w(t) + \int_{t_1}^{t_2} G(t, s) f(s) ds + \sum_{t_1 \le \tau_i < t_2} \widetilde{G}(t, \tau_i^+) a_i, \quad (60)$$

where

$$w\left(t\right)=\psi\left(t\right)\left[M\Psi(t_{1})+N\Psi(t_{2})\right]^{-1}\eta,\tag{61}$$

and Green's function pair (G, \widetilde{G}) is given by (57).

Remark 6. The results in this work are new even if the impulses are absent. The statements of the corresponding theorems are left to the reader.

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