

## 3-MANIFOLDS WITH SUBGROUPS $Z \oplus Z \oplus Z$ IN THEIR FUNDAMENTAL GROUPS

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**In this paper we characterize those 3-manifolds  $M^3$  satisfying  $Z \oplus Z \oplus Z \subseteq \pi_1(M)$ . All such manifolds  $M$  arise in one of the following ways: (I)  $M = M_0 \# R$ , (II)  $M = M_0 \# R^*$ , (III)  $M = M_0 \cup_{\partial} R^*$ . Here  $M_0$  is any 3-manifold in (I), (II) and any 3-manifold having  $P^2$  components in its boundary in (III).  $R$  is a flat space form and  $R^*$  is obtained from  $R$  and some involution  $\iota: R \rightarrow R$  with fixed points, but only finitely many, as follows: if  $C_1, \dots, C_n$  are disjoint 3-cells around the fixed points then  $R^*$  is the 3-manifold obtained from  $(R - \text{int}(C_1 \cup \dots \cup C_n))/\iota$  by identifying some pairs of projective planes in the boundary.**

**1. Introduction.** In [1] it was shown that the only possible finitely generated abelian subgroups of the fundamental groups of 3-manifolds are  $Z_n$ ,  $Z \oplus Z_2$ ,  $Z$ ,  $Z \oplus Z$  and  $Z \oplus Z \oplus Z$ . The purpose of this paper is to characterize all  $M^3$  satisfying  $Z \oplus Z \oplus Z \subseteq \pi_1(M)$ .

To explain this characterization recall that the Bieberbach theorem (see Chapter 3 of [8]) implies that if  $M$  is a closed 3-dimensional flat space form then  $Z \oplus Z \oplus Z \subseteq \pi_1(M)$ . We let  $M_1, \dots, M_6$  denote the 6 compact connected orientable flat space forms in the order given on p. 117 of [8]. Similarly  $N_1, \dots, N_4$  will denote the non-orientable ones. For explicit descriptions see §2. One of the main theorems from [3] is

(1.1) **THEOREM.** *The only space forms from the orientable ones  $M_1, \dots, M_6$  which admit involutions having fixed points, but only finitely many, are  $M_1$ ,  $M_2$ ,  $M_6$ . Moreover these involutions are unique up to conjugacy and have 8, 4, 2 fixed points respectively.*

If  $\iota: M_i \rightarrow M_i$ ,  $i = 1, 2$  or  $6$ , is such an involution and  $x_1, \dots, x_n$  are the fixed points ( $n = 8, 4, 2$ ) then there are disjoint 3-cells  $C_1, \dots, C_n$  so that

$$x_i \in \text{int } C_i \quad \text{and} \quad \iota(C_i) = C_i, \quad 1 \leq i \leq n.$$

We let  $M_i^*$  denote the orbit manifold  $M_i - \text{int}(C_1 \cup \dots \cup C_n)/\iota$ . Thus  $\partial M_1^*$  consists of 8 projective planes,  $\partial M_2^*$  consists of 4 and  $\partial M_6^*$  has 2. Canonical presentations of  $M_i^*$ ,  $i = 1, 2, 6$ , are given in [3]. By making identifications of pairs of such projective planes in  $\partial M_i^*$  we obtain new manifolds still containing  $Z \oplus Z \oplus Z$  in their fundamental groups. We