## TRANSFORMATIONS ON TENSOR SPACES

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In this paper we consider those linear transformations from one tensor product of vector spaces to another which carry nonzero decomposable tensors into nonzero decomposable tensors. We obtain a general decomposition theorem for such transformations. If we suppose further that the transformation maps the space into itself then we have a complete structure theorem in the following two cases: (1) the transformation is onto, and (2) the field is algebraically closed and the tensor space is a product of finite dimensional vector spaces. The main results are contained in Theorems 3.5 and 3.8 which state that the transformation $T: U_{1} \otimes \cdots \otimes U_{n} \rightarrow U_{1} \otimes \cdots \otimes U_{n}$ has the form $T\left(x_{1} \otimes \cdots \otimes x_{n}\right)=T_{1}\left(x_{\pi(1)}\right) \otimes \cdots \otimes T_{n}\left(x_{\pi(n)}\right)$ where $T_{i}: U_{\pi(i)} \rightarrow U_{i}$ are nonsingular and $\pi$ is a permutation. Case (2) generalizes a theorem of Marcus and Moyls.

Let $F$ be a field and $\left\{U_{a}: a \in A\right\}$ be a finite set of vector spaces over $F$. Let $(U, t)=\left(\otimes\left(U_{a}: a \in A\right), t\right)$ be a tensor product. Then $U$ is a vector space over $F, t: \Pi\left(U_{a}: a \in A\right) \rightarrow U$ is multilinear and, for any vector space $V$ over $F$ and multilinear map $f: \Pi\left(U_{a}: a \in A\right) \rightarrow V$, there is a unique linear transformation $g: U \rightarrow V$ such that $g \cdot t=f$. The decomposable tensors of $U$ are defined to be the vectors $t\left(\Pi\left(u_{a}: a \in A\right)\right)$, denoted by $\otimes\left(u_{a}: a \in A\right)$, where $u_{a} \in U_{a}$ for $a \in A$.

The proofs of the main theorems are based on the purely combinatorial results of the following section.
2. Adjacency preserving functions. In this section we define the adjacency preserving functions and find a decomposition theorem for them.

Let $A$ be a nonempty finite set and for each $a \in A$ let $S_{a}$ be a nonempty set. If $J$ is a nonempty subset of $A$ we let $p_{J}$ denote the projection of $\Pi\left(S_{a}: a \in A\right)$ onto $\Pi\left(S_{a}: a \in J\right)$. If $J=\{a\}$ we write $p_{a}$ for $p_{J}$.

For each $J \subseteq A$ we define an equivalence relation, denoted by $\equiv(\bmod J)$, on $\Pi\left(S_{a}: a \in A\right)$ by setting $x \equiv y(\bmod J)$ if and only if $p_{a}(x)=p_{a}(y)$ for all $a \in A \backslash J$. If $X \subseteq \Pi\left(S_{a}: a \in A\right)$ is a nonempty subset of equivalent elements relative to $\equiv(\bmod J)$ then we call $X$ a $J$-subset. If $J=\{a\}$ is a singleton we use $a$-subset for $J$-subset. We note the following
2.1. Lemma. $A$ subset $X \subseteq \Pi\left(S_{a}: a \in A\right)$ is an equivalence class relative to $\equiv(\bmod J)$ if and only if $p_{J}(X)=\Pi\left(S_{a}: a \in J\right)$ and $p_{a}(X)$

