## **WEB GEOMETRY**

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Introduction. Poincaré published two papers on surfaces of translation [10, 11].<sup>2</sup> They were among his lesser known papers. In the following pages I wish to show that the subject he touched is an exciting one and deserves further investigation.

1. Lie's theorem on surfaces of double translation and its developments. A surface M of translation in  $R^3$  is defined by the parametric equations

(1) 
$$x^{\lambda} = f^{\lambda}(u) + g^{\lambda}(v), \quad 1 \leq \lambda \leq 3,$$

where  $x^{\lambda}$  are the coordinates in  $R^3$  and  $f^{\lambda}$ ,  $g^{\lambda}$  are arbitrary smooth functions. It is immediately seen that the tangent lines to the *u*-curves (respectively the *v* curves) are independent of *v* (resp. *u*) and define a curve  $C_u$  (resp.  $C_v$ ) in the plane at infinity.

M is called a *surface of double translation* if it is a surface of translation in a second way, i.e., given also by the equations

(2) 
$$x^{\lambda} = h^{\lambda}(s) + k^{\lambda}(t), \quad 1 \leq \lambda \leq 3,$$

such that exactly two of the equations

(3) 
$$f^{\lambda}(u) + g^{\lambda}(v) - h^{\lambda}(s) - k^{\lambda}(t) = 0, \quad 1 \leq \lambda \leq 3,$$

are independent. In 1882 Sophus Lie proved the remarkable theorem [7]:

If M is a surface of double translation in  $\mathbb{R}^3$ , the four curves  $C_u$ ,  $C_v$ ,  $C_s$ ,  $C_t$  in the plane at infinity defined by the tangent lines to the four families of parametric curves belong to the same algebraic curve of degree four.

The theorem means that the solutions of the functional equations (3) on a surface arise from an algebraic structure. Lie's proof makes use of the integrability conditions of over-determined systems of partial differential equations. In fact, from (1) we have

(4) 
$$\frac{\partial^2 x^{\lambda}}{\partial u \partial v} = 0,$$

which means that the parametric curves form a conjugate net, i.e., their tangent directions separate harmonically the asymptotic directions at each point. If the surface M is given in the nonparametric form

$$(5) z = z(x, y),$$

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