NEW RESULTS AND OLD PROBLEMS IN FINITE TRANSFORMATION GROUPS¹

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We shall be concerned with the topology of finite transformation groups on spaces of relatively simple character. This represents a rather small corner in the general theory, but the problems which one finds here seem to be of some interest and difficulty. By disposing of various low-dimensional cases, we shall try to show where the real difficulties begin.

1. **Definitions.** A transformation group (G, X) consists of a group G acting on a topological space X to form a group of homeomorphisms of X onto itself. It will be understood throughout this paper that G is finite. For a given transformation group or "action" (G, X) and subset $H \subset G$, we denote by F(H; G, X) the fixed-point set of H—that is, the points x such that hx = x for $h \in H$. We may of course denote this set simply by F(H) when only one action is being considered. An action (G, X) is g-free if $F(g) = \emptyset$, free if it is g-free when $g \neq 1$, and semi-free if $F(G) = \emptyset$. Let X^r be the union of the fixed-point sets F(g), $g \neq 1$, and let $X^f = X - X^r$. Since $gF(h) = F(ghg^{-1})$, the closed set X^r is invariant under the transformations $x \rightarrow gx$. Hence G acts on X^r (if X^r is not empty) hence also on X^f . The action (G, X^f) is free but the action (G, X^r) is not free. We call X^r the free part of X and X^r the restricted part; (G, X^r) may be called the restricted part of the action (G, X). An action (G, X) is effective if $F(g) \neq X$ when $g \neq 1$. In a given action, the set N of elements g with F(g) = X is a normal subgroup of G and there is induced an action (G/N, X) which is effective.

The sets Gx, $x \in X$, are the *orbits* of (G, X). They form a decomposition of X and the corresponding decomposition space, called the *orbit space* of the action, is denoted by X/G. The *stability group* G_x of x consists of all g such that gx = x.

An action (G, X) is of class C^k if X is a manifold of class C^k and the functions $x \rightarrow gx$ are of class C^k . When k=0 we shall drop the manifold condition on X; every action is then of class C^0 . A differentiable action is a C^1 -action. (G, X) is orthogonal if X is a euclidean sphere or an open submanifold of a euclidean space and the trans-

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