

## ISOMETRIC IMMERSIONS OF MANIFOLDS WITH PLANE GEODESICS INTO EUCLIDEAN SPACE

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### 1. The main theorems

The object of this note is to prove the following

**Theorem 1.** Assume that (a)  $M$  is an  $n$ -dimensional ( $n \geq 2$ ) connected Riemannian manifold, (b)  $f: M \rightarrow R^{n+p}$  is an isometric immersion of  $M$  into an  $(n+p)$ -dimensional Euclidean space  $R^{n+p}$ ,  $p > 0$ , and (c) every geodesic on  $M$  is locally a plane curve, that is, if  $\sigma: (\alpha, \beta) \rightarrow M$  is a geodesic on  $M$ , then for every  $t \in (\alpha, \beta)$ , there exists an open interval  $I$  in  $(\alpha, \beta)$  containing  $t$  such that  $f \circ \sigma(I)$  lies on a certain plane  $E_t$ . Then either  $f(M)$  is an open subset of an  $n$ -dimensional plane or  $M$  is  $\frac{1}{4}$ -pinched, i.e., its sectional curvature  $K$  satisfies

$$\frac{1}{4}A \leq K \leq A$$

for some positive number  $A$ .

If  $M$  is also  $\frac{1}{4}$ -pinched, then we have

**Theorem 2.** Assume that (a), (b), (c) of Theorem 1 hold, and that  $M$  is  $\frac{1}{4}$ -pinched. Then  $M$  has positive constant sectional curvature, if one of the following conditions also holds:

(1)  $1 \leq p < \frac{1}{2}n + 2$ ,

(2)  $n$  is prime,

(3) there is  $m \in M$  such that the sectional curvature  $K$  of  $M$  at  $m$  satisfies  $\frac{1}{4}A' < K \leq A'$  for some positive  $A'$ .

Let  $\langle, \rangle$  denote the metric tensor in  $R^{n+p}$ . Let  $X_i, B(X_i, X_i), 2B(X_i, X_j) = 2B(X_j, X_i)$ ,  $1 \leq i \neq j \leq n$ , be unit vectors in  $R^{n+p}$  with the following properties:

(i) if  $1 \leq i \neq j \leq n$ , then  $\{X_1, \dots, X_n, B(X_i, X_i), 2B(X_i, X_j) = 2B(X_j, X_i)\}$  is orthonormal;

(ii) for every  $i \neq j$ ,  $1 \leq i, j \leq n$ ,  $\langle B(X_i, X_i), B(X_j, X_j) \rangle = \frac{1}{2}$ ;

(iii)  $\langle B(X_i, X_j), B(X_h, X_k) \rangle = 0$ , for  $i, j, h, k$  different and  $1 \leq i, j, h, k \leq n$ .

Let  $c$  be a fixed positive real number, and  $m$  be a fixed point of  $R^{n+p}$ . By identifying points of  $R^{n+p}$  with their position vectors, the set of all points  $\varphi(x_1, \dots, x_n)$  defined by