# 53. On Solutions of the Poincaré Equation 

By Katsunori Iwasaki<br>Department of Mathematics, Faculty of Science, University of Tokyo<br>(Communicated by Shokichi Iyanaga, m. J. A., June 11, 1991)

1. Introduction and result. Consider a map $F: C^{2} \rightarrow C^{2}$ defined by (1)

$$
F:{ }^{t}(x, y) \longmapsto{ }^{t}(y, a x+p(y)),
$$

where $a$ is a nonzero constant and $p(y)$ is a polynomial of degree $d \geq 2$. The map $F$ is called a twisted elementary map (Kimura [2]). We denote by $F^{k}$ the $k$-times iteration of $F$. Assume that $z_{0}=^{t}\left(x_{0}, y_{0}\right) \in C^{2}$ is a periodic point of $F$ of period $k$, i.e. a fixed point of $F^{k}$. Let $J$ be the Jacobian matrix of $F^{k}$ at $z_{0}$. Let $\rho$ be an eigenvalue of $J, v={ }^{t}\left(v_{1}, v_{2}\right) \in \boldsymbol{C}^{2}$ an eigenvector of $J$ corresponding to the eigenvalue $\rho$. The eigenvalue $\rho$ is said to be unstable (resp. stable) if $|\rho|>1$ (resp. if $|\rho|<1$ ).

Definition (Kimura [2]). Suppose that $\rho$ is unstable (resp. stable). A holomorphic map $E: C \rightarrow C^{2}$ is called an unstable (resp. a stable) curve through $z_{0}$ if the following two conditions hold:

$$
\begin{align*}
\Xi(\rho t) & =F^{k}(\Xi(t)) & & \text { for } t \in C  \tag{2}\\
\Xi(t) & =z_{0}+v t+O\left(t^{2}\right) & & \text { as } t \longrightarrow 0 . \tag{3}
\end{align*}
$$

If none of $\rho^{n}(n=2,3,4, \cdots)$ is an eigenvalue of $J$, it is known that there exists an unstable (a stable) curve through $z_{0}$ ([2]). The functional equation (2) is called the Poincaré equation, since Poincaré [3] was the first to consider this type of functional equation (cf. Dixon-Esterle [1]). In this paper we shall establish the following :

Main theorem. Each component of the (un) stable curve $E(t)$ is an entire function of order $\tau$ and of finite type, where $\tau$ is given by

$$
\tau=\frac{\log d}{\left.|\log | \rho\right|^{1 / k} \mid}
$$

Remark. In a special case $k=1$, the result is already shown in [2]. As we shall see below, however, we require much subtler estimates than those in [2] to establish the theorem for $k>1$.
2. Notation. Throughout this paper we employ the following notation.
(a) Let $\boldsymbol{E}_{m}=^{t}\left(\xi_{m}, \eta_{m}\right): C \rightarrow \boldsymbol{C}^{2}$ be holomorphic maps defined recursively by $\Xi_{0}(t)=\boldsymbol{E}(t)$ and

$$
\begin{equation*}
\Xi_{m}(t)=F\left(\Xi_{m-1}\left(\lambda^{-1} t\right)\right) \quad \text { for } m \in \boldsymbol{Z}, \tag{4}
\end{equation*}
$$

where $\lambda=\rho^{1 / k}$. We put $\xi={ }^{t}\left(\xi_{0}, \cdots, \xi_{k-1}\right)$ and $\eta={ }^{t}\left(\eta_{0}, \cdots, \eta_{k-1}\right)$.
(b) For a $k$-vector $u={ }^{t}\left(u_{0}, \cdots, u_{k-1}\right) \in \boldsymbol{C}^{k}$, we put $\|u\|=\left|u_{0}\right|+\cdots+\left|u_{k-1}\right|$ and $p(u)={ }^{t}\left(p\left(u_{0}\right), \cdots, p\left(u_{k-1}\right)\right)$.
(c) We put for $r>0$,

