

## 21. Nonlinear Singular First Order Partial Differential Equations of Briot-Bouquet Type

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In this paper we will present a generalization of the Briot-Bouquet ordinary differential equation to partial differential equations.

§ 1. Briot-Bouquet equation. First let us recall the theory of nonlinear ordinary differential equations of the form

$$(1.1) \quad t \frac{du}{dt} = f(t, u), \quad f(0, 0) = 0$$

which was first studied by Briot-Bouquet [1]. Nowadays it is called the Briot-Bouquet equation and the structure of solutions of (1.1) near the origin of  $C_t$  is well-known (see Hille [3], Hukuhara-Kimura-Matuda [4], Kimura [5], Gérard [2] etc.). In particular, when

$$\rho = \frac{\partial f}{\partial u}(0, 0)$$

is in a generic position, we know the following:

**Theorem 1.** Assume that  $f(t, u)$  is a holomorphic function defined near the origin of  $C_t \times C_u$ . Then we have:

(1) (Holomorphic solutions). If  $\rho \in N^*(=\{1, 2, 3, \dots\})$ , the equation (1.1) has a unique solution  $u_0(t)$  holomorphic near the origin of  $C_t$  satisfying  $u_0(0) = 0$ .

(2) (Singular solutions). If  $\rho \in N^* \cup \{a \in \mathbf{R}; a \leq 0\}$ , the general solution  $u(t)$  of (1.1) near the origin of  $C_t$  is given by

$$(1.2) \quad u(t) = ct^\rho + a_{1,0}t + \sum_{i+j \geq 2} a_{i,j}t^i(ct^\rho)^j,$$

where  $c \in C$  is arbitrary, the coefficients  $a_{i,j} \in C$  are uniquely determined by the equation (1.1), and the series

$$w + a_{1,0}t + \sum_{i+j \geq 2} a_{i,j}t^i w^j$$

is a convergent power series in  $\{t, w\}$ . The holomorphic solution  $u_0(t)$  in (1) is given by the case  $c=0$ .

§ 2. Generalization of (1.1) to partial differential equations. Let us consider

$$(2.1) \quad t \frac{\partial u}{\partial t} = F\left(t, x, u, \frac{\partial u}{\partial x}\right),$$

where  $(t, x) \in C_t \times C_x^n$ ,  $x = (x_1, \dots, x_n)$ ,  $\frac{\partial u}{\partial x} = \left(\frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n}\right)$  and  $F(t, x, u, v)$

with  $v = (v_1, \dots, v_n)$  is a function defined in a polydisk  $\Delta$  centered at the

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