# 103. On Certain Numerical Invariants of Mappings over Finite Fields. III 

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Introduction. This is again a continuation of my two preceding papers*) [3]. We shall be concerned with algebras with involution and Hopf maps.
§ 1. Algebras with involution. Let $K=\boldsymbol{F}_{q}$ ( $q$ : odd) and let $A$ be an associative algebra with involution $\alpha$. (See [1] for basic facts on such algebras). Take an invertible element $\theta \in A$ such that
(1.1) $\quad \theta^{\alpha}=\varepsilon \theta, \quad \varepsilon= \pm 1$
and consider the mapping $F: A \rightarrow A$ given by
(1.2) $\quad F(x)=x^{\alpha} \theta x, \quad x \in A$.

Clearly, $F$ is a quadratic mapping of the underlying vector space of $A$ into itself. In this section, we shall determine invariants $\rho_{F}, \sigma_{F}$ for this mapping when the algebra ( $A, \alpha$ ) is simple. Since all finite division rings are commutative, there are 4 types of such algebras, up to the change of ground fields:
(i) $A=K_{r} \oplus K_{r}, \quad(x, y)^{\alpha}=\left({ }^{t} y,{ }^{t} x\right), \quad \tau(x, y)=\operatorname{tr}(x)+\operatorname{tr}(y)$,
(ii) $A=K_{r}, \quad x^{\alpha}=S^{-1 t} x S, \quad{ }^{t} S=S, \quad \tau(x)=\operatorname{tr}(x)$,
(iii) $A=K_{2 s}, \quad x^{\alpha}=J^{-1} t x J, \quad J=\left(\begin{array}{cc}0 & 1_{s} \\ -1_{s} & 0\end{array}\right), \quad \tau(x)=\operatorname{tr}(x)$,
(iv) $\quad A=L_{r}, \quad L=F_{q^{2}}, \quad x^{\alpha}=S^{-1}{ }^{t} \bar{x} S, \quad{ }^{t} \bar{S}=S, \quad \tau(x)=\operatorname{tr}(x)+\overline{\operatorname{tr}(x)}$.
(Here $\tau$ means the reduced trace of the algebra $A$ over $K, \operatorname{tr}(x)$ means the trace of the matrix $x$ and the bar means the conjugation of the quadratic extension $L / K$.) Note that the trace has the properties:
(1.3) $\tau\left(x^{\alpha}\right)=\tau(x), \tau(x y)=\tau(y x)$, the mapping $(x, y) \mapsto \tau(x, y)$ is a non-degenerate symmetric bilinear form on $A$.
Therefore, to each $\lambda \in A^{*}$, the dual space of $A$, there corresponds uniquely an element $a=a_{\lambda} \in A$ such that $\lambda(x)=\tau(a x)$. Conversely, any $a \in A$ defines a linear form $\lambda=\lambda_{a}$ by $\lambda(x)=\tau(a x)$. We have
(1.4) $\quad F_{\lambda}(x)=\lambda(F(x))=\tau\left(a x^{\alpha} \theta x\right)$.

Put

$$
\begin{equation*}
\langle x, y\rangle_{\lambda}=\frac{1}{2}\left(F_{\lambda}(x+y)-F_{\lambda}(x)-F_{\lambda}(y)\right) . \tag{1.5}
\end{equation*}
$$

Then, we have

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[^0]:    *) As in my former paper (II), (I. 2.3) will mean (2.3) in (I).

