

7. On the Relations between the Stability of Linear Systems and the Characteristic Roots of the Coefficient Matrix

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1. Introduction. Consider the homogeneous linear differential equation

$$(1) \quad \dot{x} = A(t)x \quad (x: n\text{-vector})$$

where the coefficient $n \times n$ matrix $A(t)$ is continuously differentiable in an interval $I = [0, +\infty)$. In this paper, we shall study the relations between the stability of the system (1) and the characteristic roots of the time-variant coefficient matrix $A(t)$, of which all characteristic roots are constant.

Throughout this paper, we use the vector Euclidean norm $\|x\| = \sqrt{\sum_{i=1}^n |x_i|^2}$ and the induced matrix norm $\|A\| = \sup_{\|x\|=1} \|Ax\|$.

Moreover, the definitions of stability, asymptotic stability and instability are the same as given in W. A. Coppel [1].

2. Theorem. We shall give a theorem, which was proved by the second author [3].

Theorem 1. *The homogeneous linear equation*

$$(1) \quad \dot{x} = A(t)x$$

is reduced to the homogeneous linear equation

$$(2) \quad \dot{y} = B(t)y$$

under the transformation

$$(3) \quad x = e^{St}y$$

if and only if there exists a constant matrix S satisfying the equations

$$(4) \quad \dot{A}(t) = SA(t) - A(t)S - e^{St} \cdot \dot{B}(t) \cdot e^{-St}$$

$$(5) \quad A(0) = S + B(0).$$

3. Relations between the stability and the characteristic roots of $A(t)$. In the above Theorem 1, if we can choose a constant matrix B , we can express the fundamental matrix of the system (1) by the form

$$(6) \quad \Phi(t) = e^{St} \cdot e^{Bt}.$$

In this case, the stability of the system (1) is completely decided by the characteristic roots of S and B , therefore is independent of ones of $A(t)$.

Let the coefficient matrix $A(t)$ be given in the following form: