# 57. On Two Properties of the Curvature of Continuous Parametric Curves 

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1. Introduction. In the present continuation of his recent papers [1] to [5] the author proceeds to establish two noteworthy properties of the curvature of continuous parametric curves. They generalize certain well-known results in classical differential geometry of curves.

Let $\boldsymbol{R}^{m}$ be a Euclidean space of any dimension $m \geqq 2$ throughout this note. Let us consider in this space a parametric curve $\varphi(t)$ of the class $\mathrm{C}^{2}$, defined and regular on the real line $\boldsymbol{R}$. In other words, we suppose that the coordinate-functions $x_{i}(t)$ of $\varphi$ are all twice continuously differentiable ( $i=1,2, \cdots, m$ ) and that, furthermore, the derivative of $\varphi$, given by $\varphi^{\prime}(t)=\left\langle x_{1}^{\prime}(t), \cdots, x_{m}^{\prime}(t)\right\rangle$ for all $t$, never vanishes. Let $s(t)$ denote a length-function for the curve $\varphi$, so that $s(t)$ increases strictly and for every closed interval $[a, b]$ the arc-length of $\varphi$ over $[a, b]$ is equal to the increment $s(b)-s(a)$. We write further $\gamma(t)$ for the spheric representation of $\varphi$, given by $\gamma(t)=\left|\varphi^{\prime}(t)\right|^{-1} \varphi^{\prime}(t)$ for each $t$. Then everybody knows that the curvature of $\varphi$ at any point $t$ of $\boldsymbol{R}$ is expressed by the absolute value of the $s$-derivative $(s) \gamma^{\prime}(t)$ of the curve $\gamma$. Indeed this is often adopted as the definition of curvature.

Now the extension of this statement to curves more general than $\varphi$ considered above is the concern of our first theorem (§3). It should be noted that in our paper [4] we defined curvature in a way different from the aforesaid standard definition and that therefore the propounded extension is not a definition but a theorem requiring a regular proof. As for our second theorem (§5), we must omit the explanation of its origin owing to space limitation.
2. Direction-curves. Consider in $\boldsymbol{R}^{\boldsymbol{m}}$ a continuous light curve $\varphi(t)=\left\langle x_{1}(t), \cdots, x_{m}(t)\right\rangle$, defined on $\boldsymbol{R}$ and locally straightenable (see [4]§2). Then $\varphi$ is necessarily locally rectifiable by [1]§64. As in [4], the length and bend of $\varphi$ over an interval $I$ (of any type) will be denoted by $S(I)$ and $\Omega(I)$ respectively, and the induced measurelength and measure-bend by $S_{*}$ and $\Omega_{*}$ respectively. Further, we shall continue using the symbol $\rho(t)$ of [4] to denote the curvature (in our sense) of $\varphi$ at a point $t$ of $\boldsymbol{R}$. We remark in passing that, as easily seen, the definition of bend adopted in [4] is compatible

