128. On Certain Reduction Theorems for Systems of Differential Equations which Contain a Turning Point

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1. Introductions. In this paper we consider a system of linear ordinary differential equations

(1.1)
$$\varepsilon dx/dt = A(t, \varepsilon)x,$$

where x is an n-vector: $A(t, \epsilon)$ is a matrix of type (n, n), which admits a uniformly asymptotic expansion

(1.2)
$$A(t, \varepsilon) = \sum_{j=0}^{\infty} A_j(t) \varepsilon^{j}$$

for $|t| < t_0$, as ε tends to zero through a domain $|\arg \varepsilon - \theta| < \varepsilon_0$. The coefficients of this expansion, $A_j(t)$ are holomorphic functions of t in the domain $|t| < t_0$.

The system has a turning point at the origin, if $A_0(t)$ has a set of eigenvalues: $\lambda_{j_1}(t), \dots, \lambda_{j_p}(t) (p \le n)$, which are zero for t=0, but at least a pair of eigenvalues are not identically equal, where, by a theorem due to Sibuya, (cf. Sibuya, Y. [3]), we may assume p=n.

Though a general method to treat such a system is not yet known, all the known results are obtained by reducing the coefficient matrix $A(t, \varepsilon)$ to a matrix, whose elements are polynomials in the independent variable. Moreover, if there is a formal transformation

(1.3)
$$y = P(t, \varepsilon)x \quad P(t, \varepsilon) \sim \sum_{j=0}^{\infty} P_j(t)\varepsilon^j$$

such that

(1.4) det $P_0(0) \neq 0$, $P_i(t)$: holomorphic for $|t| < t_0$

which reduces the system (1.1) to a system with polynomial coefficients, then, in a sectorial domain, there is a matrix $Q(t, \varepsilon)$ which has the same asymptotic expansion as $P(t, \varepsilon)$. (cf. Sibuya, Y. [4]). We shall call a formal transformation (1.3) with the properties (1.4), a formal admissible transformation.

Our results are stated in two theorems:

Theorem 1. If in (1.2) $A_0(t)$ is in the form

(1.5.1)
$$A_{0}(t) = \begin{pmatrix} 0 \ 1 \ 0 \cdots 0 \\ 0 \ 0 \ 1 \cdots 0 \\ \vdots \\ 0 \ 0 \ 0 \cdots 1 \\ t \ 0 \ 0 \cdots 0 \end{pmatrix},$$

then there is a formal admissible series (1.3) such that $\varepsilon dy/dt = A_0(t)y.$