

8. A Counterexample in the Theory of Prehomogeneous Vector Spaces

By Akihiko GYOJA

College of General Education, Osaka University

(Communicated by Shokichi IYANAGA, M. J. A., Jan. 12, 1990)

1. Let G be a linear algebraic group defined over the complex number field \mathbb{C} , (G, ρ, V) a prehomogeneous vector space and Ω the open dense G -orbit in V . (See below for the definitions.) If G is reductive and (G, ρ, V) is regular, then the open subvariety Ω of V is an affine variety [2]. Here the regularity condition is known to be essential, but it seems that the reductivity of G was expected not to be essential. The purpose of this note is to give a counterexample to this expectation.

2. *Prehomogeneous vector spaces.* Let G be as above, $V = \mathbb{C}^k$, and $\rho: G \rightarrow GL(V)$ a rational representation of G . Such a triplet (G, ρ, V) is called a *prehomogeneous vector space* if V has an open dense G -orbit. (Here and below, we exclusively consider the Zariski topology.) Such an orbit is unique and we shall denote it by Ω . A prehomogeneous vector space (G, ρ, V) is called *regular* if there exists a polynomial function $f(x) = f(x_1, \dots, x_k)$ on V which satisfies the following two conditions:

(R1) There exists a rational character ϕ of G such that $f(\rho(g)v) = \phi(g)f(v)$ for any $g \in G$ and $v \in V$.

$$(R2) \quad \det \left(\frac{\partial^2 \log f}{\partial x_i \partial x_j} \right)_{1 \leq i, j \leq k} \neq 0 \quad \text{on } \Omega.$$

3. *Tits system.* Let $G = GL_n(\mathbb{C})$, B be the Borel subgroup of G consisting of upper triangular matrices, T the maximal torus of B consisting of diagonal matrices, $N = N_o(T)$ the normalizer of T in G and $W = N/T$ the Weyl group. Let \mathfrak{S}_n be the symmetric group acting on $\{1, 2, \dots, n\}$ and \dot{W} the group of permutation matrices in $GL_n(\mathbb{C})$. Then we have natural isomorphisms $\mathfrak{S}_n \simeq \dot{W} \simeq W$, by which we shall identify these three groups. Let S be the set of transpositions $\{(1, 2), (2, 3), \dots, (n-1, n)\}$ and

$$w_0 = \begin{pmatrix} 1 & 2 & \cdots & n \\ n & n-1 & \cdots & 1 \end{pmatrix}.$$

Then (G, B, N, S) is a Tits system [1; chapter 4, section 2]. For a subset X of S , let W_X be the subgroup of W generated by X and $G_X = BW_XB$. Every element $w \in W$ can be expressed as $w = s_1 s_2 \cdots s_a$ ($s_i \in S$). Define the length $l(w)$ of w to be the minimum of the length a of such an expression. It is known that $l(w) = \dim BwB - \dim B$. If $x, y \in W$ can be expressed as

$$x = s_1 s_2 \cdots s_a \quad (s_i \in S, a = l(x)),$$

and

$$y = s_{i_1} s_{i_2} \cdots s_{i_b} \quad (1 \leq i_1 < i_2 < \cdots < i_b \leq a),$$