

### 47. Symmetries of the Garnier System and of the Associated Polynomial Hamiltonian System

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**Introduction.** The aim of this note is to present a group of symmetries for the Garnier system, which is a system of partial differential equations obtained by monodromy preserving deformations of second order Fuchsian differential equations on  $P^1$ , and for the associated polynomial Hamiltonian system.

Let us consider a Pfaffian system :

$$E(\theta) : \quad dx_i = \sum_{j=1}^n G_{ij}(x, t, \theta) dt_j, \quad i=1, \dots, m,$$

where  $G_{ij}(x, t, \theta)$  are rational functions in  $(x, t) = (x_1, \dots, x_m, t_1, \dots, t_n)$  depending on parameters  $\theta \in C^N$  and  $d$  stands for the exterior differentiation with respect to  $(x, t)$ . For a birational transformation  $S : (x, t) \rightarrow (x', t')$ , we denote by  $S \cdot E(\theta)$  the system of differential equations in the variables  $(x', t')$  obtained from  $E(\theta)$  by the transformation  $S$ .

**Definition.** A group of symmetries for the system  $E$  is a group whose element is a pair  $\sigma = (S, l)$  of a birational transformation  $S : (x, t) \rightarrow (x', t')$  and an affine transformation  $l : C^N \rightarrow C^N$  such that  $S \cdot E(\theta) = E(l(\theta))$ .

Let  $\sigma = (S, l)$  and  $\sigma' = (S', l')$  be symmetries of the system  $E$ . The product  $\sigma \cdot \sigma'$  and the inverse  $\sigma^{-1}$  to  $\sigma$  are defined by  $\sigma \cdot \sigma' := (S \circ S', l \circ l')$  and  $\sigma^{-1} := (S^{-1}, l^{-1})$ , respectively.

**1. Garnier system  $\mathcal{G}_n$  and the associated system  $\mathcal{H}_n$ .** The  $n$ -dimensional Garnier system is the Hamiltonian system

$$\mathcal{G}_n : \quad d\lambda_i = \sum_{j=1}^n \{K_j, \lambda_i\} dt_j, \quad d\mu_i = \sum_{j=1}^n \{K_j, \mu_i\} dt_j,$$

$i=1, \dots, n$ , where  $\{\cdot, \cdot\}$  stands for the Poisson bracket

$$\{f, g\} = \sum_i \left( \frac{\partial f}{\partial \mu_i} \frac{\partial g}{\partial \lambda_i} - \frac{\partial g}{\partial \mu_i} \frac{\partial f}{\partial \lambda_i} \right).$$

The Hamiltonians  $K_i = K_i(\theta, \lambda, \mu, t)$  are given by

$$K_i = M_i \sum_{k=1}^n M^{k,i} \left\{ \mu_k^2 - \sum_{m=1}^{n+2} \frac{\theta_m - \delta_{im}}{\lambda_k - t_m} \mu_k + \frac{\kappa}{\lambda_k(\lambda_k - 1)} \right\},$$

where  $\theta_1, \dots, \theta_{n+2}$ ,  $\kappa := (1/4)(\sum_{i=1}^{n+2} \theta_i - 1)^2 - (1/4)\theta_\infty^2$  are constants,  $t_{n+1} = 0$ ,  $t_{n+2} = 1$ , and

$$M_i = -\frac{A(t_i)}{T'(t_i)}, \quad M^{k,i} = \frac{T(\lambda_k)}{(\lambda_k - t_i)A'(\lambda_k)},$$

( $i, k=1, \dots, n, n+1, n+2$ ) defined by using