

4. Asymptotic Equivalence of Dynamical Systems

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In [1] the author generalizes the notion of asymptotic equivalence and attempts to prove theorems which are related to results in [2, Chapter IX, Section 4]. Unfortunately, this definition of asymptotic equivalence is inadequate to guarantee the stated results. (This is not noted in the review of [1] in *Mathematical Reviews*, MR 45 #7211.) In this paper we present a counter example to two of the theorems in [1] and redefine "asymptotic equivalence" in such a manner as to validate the theorems to which we provide a counter example. In fact, stronger results, as would be expected by a more restrictive definition, are proved.

Throughout this paper X will denote a locally compact metric space with metric d , R the reals, and R^+ the nonnegative reals. If $M \subset X$ and $a > 0$, then $K(M, a)$ will denote the set $\{x : d(x, M) < a\}$.

A dynamical system on X is a continuous mapping $\pi : X \times R \rightarrow X$ such that

- (i) $\pi(x, 0) = x$ for all $x \in X$,
- (ii) $\pi(\pi(x, s), t) = \pi(x, s + t)$ for all $x \in X$ and $s, t \in R$.

Let π_i ($i=1, 2$) be dynamical systems on X and $x \in X$. Then $L_i(x)$ and $J_i(x)$ will denote the positive limit set of x and the positive prolongational limit set of x , respectively, with respect to π_i . A compact subset M of X is called

- (i) a weak attractor of π_i , if there exists an $a > 0$ such that $L_i(x) \cap M \neq \emptyset$ for every $x \in K(M, a)$,
- (ii) an attractor of π_i , if there exists an $a > 0$ such that $\phi \neq L_i(x) \subset M$ for every $x \in K(M, a)$,
- (iii) a uniform attractor of π_i , if there exists an $a > 0$ such that $\phi \neq J_i(x) \subset M$ for every $x \in K(M, a)$,
- (iv) stable with respect to π_i , if for any $a > 0$ there exists $b > 0$ such that $\pi_i(K(M, b), R^+) \subset K(M, a)$,
- (v) eventually stable with respect to π_i , if for any $a > 0$ there exist $b > 0$ and $T > 0$ such that $\pi_i(K(M, b), [T, \infty)) \subset K(M, a)$,
- (vi) weakly asymptotically stable with respect to π_i , if M is eventually stable and a weak attractor with respect to π_i ,
- (vii) asymptotically stable with respect to π_i , if M is stable and an attractor with respect to π_i ,