

## 209. Hypersurfaces of a Euclidean Space $R^{4m}$

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**Introduction.** K. Yano and M. Okumura [5] have shown that the existence of the so called  $(f, g, u, v, \lambda)$ -structure on hypersurfaces of an almost contact manifold and on submanifolds of codimension 2 of an almost Hermitian manifold.

D. E. Blair, G. D. Ludden and K. Yano [1] have studied complete hypersurfaces immersed in  $S^{2n+1}$  and showed that (1) if the Weingarten map of the immersion and  $f$  commute then the hypersurface is a sphere, and (2) if the Weingarten map  $K$  of the immersion and  $f$  satisfy  $fK + Kf = 0$  and the hypersurface is of constant scalar curvature, then it is a great sphere or  $S^n \times S^n$ .

On the other hand, Y. Y. Kuo [2] has shown the existence of an almost contact 3-structure on  $R^{4m+3}$  and that of a Sasakian 3-structure on  $S^{4m+3}$  and on the real projective space  $P^{4m+3}$ .

The main purpose of this paper is, after showing that an orientable hypersurface of a Hermitian manifold with quaternion structure admits an almost contact 3-structure  $(\phi_i, \xi_i, \eta_i)$ ,  $i=1, 2, 3$ , to classify complete hypersurfaces of  $R^{4m}$  satisfying  $\phi_i H - H\phi_i = 0$ ,  $i=1, 2, 3$  and those satisfying  $\phi_i H + H\phi_i = 0$ ,  $i=1, 2, 3$ . The results are:

**Theorem 1.** *Let  $N$  be a complete hypersurface of  $R^{4m}$  ( $m \geq 2$ ). If the Weingarten map of the immersion and  $\phi_i$ ,  $i=1, 2, 3$  commute, then  $N$  is one of the following*

- (i) a hyperplane,
- (ii) a sphere,
- (iii)  $R^{4t} \times S^{4s+3}$ ,  $t+s=m-1$ ,  $t \geq 1$ ,  $s \geq 0$ .

**Theorem 2.** *Let  $N$  be a complete hypersurface of  $R^{4m}$  ( $m \geq 1$ ). If the Weingarten map  $H$  of the immersion and  $\phi_i$  satisfy  $\phi_i H + H\phi_i = 0$ , then it is a hyperplane.*

For the case  $m=1$  in Theorem 1, we have, as a corollary,

**Corollary.** *Let  $N$  be a complete hypersurface of  $R^4$ . If the Weingarten map of the immersion and  $\phi_i$ ,  $i=1, 2, 3$  commute, then  $N$  is either a hyperplane or a sphere.*

**1. Preliminaries.** First, let  $M = M^{4m}$  be a differentiable manifold with quaternion structure  $(\Phi_1, \Phi_2)$ , where a quaternion structure is, by definition, a pair of two almost complex structures  $\Phi_1, \Phi_2$  such that

$$(1) \quad \Phi_1\Phi_2 + \Phi_2\Phi_1 = 0.$$