

1. On the Degenerate Oblique Derivative Problems

By Akira KAJI

Department of Mathematics, University of Tokyo

(Comm. by Kôzaku YOSIDA, M. J. A., Jan. 12, 1974)

§ 1. Introduction and results. In this note we give *a priori* estimates and existence theorems for the degenerate oblique derivative problems, which will be formulated below. We first reduce the given boundary value problems to the pseudo-differential equations on the boundary with the aid of suitable boundary value problems which are well studied, and next apply Melin's theorem (see [5], Theorem 3.1) to the pseudo-differential equations on the boundary.

Let Ω be a bounded domain in R^n , and we assume that $\Omega \cup \partial\Omega$ is a C^∞ -manifold with boundary. Let $a(x)$, $b(x)$ and $c(x)$ be real-valued functions $\in C^\infty(\partial\Omega)$, \mathbf{n} be the unit exterior normal to $\partial\Omega$ and ν be a real C^∞ -vector field on $\partial\Omega$.

Now we consider, for $\lambda > 0$, the degenerate oblique derivative problem:

$$(I) \quad \begin{cases} (\lambda - \Delta)u = f & \text{in } \Omega, \\ a(x) \frac{\partial u}{\partial \mathbf{n}} + b(x) \frac{\partial u}{\partial \nu} + c(x)u = 0 & \text{on } \partial\Omega, \end{cases}$$

under the following assumptions:

- (1) $a(x) \geq 0$.
- (2) The set $S = \{x \in \partial\Omega; a(x) = 0\}$ is an $(n-2)$ -dimensional C^∞ -manifold.
- (3) ν is transversal to S in $\partial\Omega$.
- (4) $c(x) > 0$ on the set $\{x \in \partial\Omega; a(x) = 0\}$.
- (5) Along the integral curve $x(t, x_0)$ of ν passing $x_0 \in S$ when $t=0$, $a(x(t, x_0))$ has a zero of finite order k at $t=0$, and $b(x(t, x_0))$ has a zero of finite order l at $t=0$, where k and l are independent of x_0 .

Remark 1. In the case where $b(x) \neq 0$ on S , our problem is the oblique derivative problem which has been already treated by several authors and we can remove the assumption (4) (see [2] and [6]). In the case where $b(x) \equiv 0$, our problem was treated by S. Itô (see [3]) and we can also remove the assumptions (2) and (5) (see the proof below).

For each real s , we denote by $H_s(\Omega)$ and $H_s(\partial\Omega)$ the usual Sobolev spaces on Ω and $\partial\Omega$ respectively, and by $\|\cdot\|_{s,\Omega}$ and $\|\cdot\|_{s,\partial\Omega}$ norms in these spaces.

Theorem 1. Assume that $l \geq k$ and the assumptions (1), (2), (4) and (5) hold. Then there is a positive constant C such that, for $u \in L^2(\Omega)$