

## COMPLEX ALMOST CONTACT MANIFOLDS

BY SHIGERU ISHIHARA AND MARIKO KONISHI

### §1. Introduction.

A complex contact manifold is a complex manifold of odd dimensions  $2m+1$  ( $\geq 3$ ) covered by an open covering  $\mathcal{A}=\{O, O', \dots\}$  consisting of coordinate neighborhoods in such a way that

1) In each  $O \in \mathcal{A}$  there is a holomorphic 1-form  $w$  satisfying  $w \wedge (dw)^m \neq 0$  at every point of  $O$ ;

2) If  $O \cap O' \neq \emptyset$  ( $O, O' \in \mathcal{A}$ ), there is a non-vanishing holomorphic function  $\lambda$  in  $O \cap O'$  such that  $w' = \lambda w$  in  $O \cap O'$ , where  $w'$  is the holomorphic 1-form given in  $O'$  (See Kobayashi [3]).

In a previous paper [2] we have studied complex contact structure  $\{(O, w) | O \in \mathcal{A}\}$  which are induced by fiberings of manifolds with (real) normal contact 3-structure and obtained the induced (local) tensor field  $G$  of type  $(1, 1)$  in each  $O \in \mathcal{A}$  such that  $G^2 = -I + w \otimes W$ ,  $w \circ G = 0$ , where  $W$  is the associated vector field of  $w$ . The local structures  $\{(O, G, w, W) | O \in \mathcal{A}\}$  are very useful to study curvature properties in the same way as in the real case (See Gray [1]. and Sasaki [4]). In the present paper we first define a system of local structures  $\{(O, u, G) | O \in \mathcal{A}\}$  which will be called a complex almost contact structure and next show that such a structure induces a complex contact structure defined by Kobayashi [3], when it satisfies a suitable condition, i.e., to be normal.

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### §2. Complex almost contact structure.

Let  $M$  be a complex manifold with complex structure  $F$  and Hermitian metric  $g$  and be covered by an open covering  $\mathcal{A}=\{O, O', \dots\}$  consisting of coordinate neighborhoods. Then  $M$  is called a *Complex almost contact manifold* if the following conditions 1) and 2) are satisfied:

1) In each  $O \in \mathcal{A}$  there are given a 1-form  $u$  and a tensor field  $G$  of type  $(1, 1)$  such that<sup>\*)</sup>

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<sup>\*)</sup> Functions vector fields, tensor fields and geometric objects we consider are assumed to be differentiable and of class  $C^\infty$ , otherwise stated. Throughout this paper,  $X, Y$  and  $Z$  denote arbitrary vector fields in  $M$ .