# On Integral Invariants and Betti Numbers of Symmetric Riemannian Manifolds, II. 

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## Chapter III.

Formation of invariant differentials and the Schubert varieties.

## I.

1. We have already seen that the manifold $S(n)$ can be considered as the set of all null-systems $x \rightarrow y=S x$ such that the skew matrix $S$ is at the same time orthogonal. Let us show that this manifold can also be considered as the set of all isotropic $m$-planes in $P_{n}$.

In order that a subspace $\mathfrak{M} \in P$ be isotropic, it is neccesary and sufficient that $(x, y)=0$ for all $x, y \in \mathfrak{M}$. For any $\mathfrak{M}$ there exists the conjugate $\overline{\mathfrak{M}}$ of $\mathfrak{M}$. $\overline{\mathfrak{M}}$ is namely the set of vectors $\bar{x}$, where $x \in \mathfrak{M}$. The correspondence $\mathfrak{M} \rightarrow \overline{\mathfrak{M}}$ is invariant under the group $O(n)$. In $\mathfrak{M}$ we take $m$ vectors $x_{1}, \ldots \ldots, x_{m}$ such that $\left(x_{i} \bar{x}_{j}\right)=\delta_{i j}$. The vectors $e_{1}, \ldots \ldots, e_{n}$ with

$$
\begin{equation*}
e_{i}=\left(x_{i}+\bar{x}_{i}\right) / \sqrt{2}, e_{m+i}=\left(x_{i}-\bar{x}_{i}\right) / \sqrt{-2} \tag{1}
\end{equation*}
$$

constitute a real coordinate system such that ( $e_{i} c_{j}$ ) $=\boldsymbol{\delta}$ (ij). This shows at once that the manifold $\tilde{\Sigma}(n)$ is tronsformed transitively by the group $O L(n$.$) Now the manifold \tilde{\Sigma}(n)$ consists of two different continuous families, each being transformed transitively by the group $O(n)$. We denote one of them by $\Sigma(n)$. Then there exists a one to one correspondence between the elements of the manifolds $S(n)$ and $\Sigma(n)$ invariant with respect to the group $O(n)$. In fact, let $S$ be an element of $S(n)$. We consider a set $\mathfrak{M}$ of all complex vectors of the form

$$
\mathfrak{x}=x+\sqrt{-1} S_{x} \quad x \in R_{n} .
$$

The vector $x$ is isotropic. To show that $\mathfrak{M}$ is isotropic $m$-dimensional we take a special coordinate system such that $S=I . \mathfrak{M}$ is then the set of all vectors of the form $\left(z_{1}, \ldots \ldots, z_{m}, \sqrt{-1} z_{1}, \ldots \ldots, \sqrt{-1} z_{m}\right)$, where $z_{i} \in K$.

[^0]
[^0]:    The group of desplacements of $S(n)$ is $S \rightarrow T S^{*} T, T \in O(n)$. We denote by $\Sigma(n)$ the set of all isotropic $m$-planes of $P_{n}$, where $n=2 m$.

