## KENMOTSU TYPE REPRESENTATION FORMULA FOR SPACELIKE SURFACES IN THE DE SITTER 3-SPACE

By

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## Introduction

In [10], Kenmotsu proved that surfaces in the Euclidean 3-space  $E^3$  can be represented by means of the mean curvature and the Gauss map. In [3] and [4], we gave the Kenmotsu type representation formulas for surfaces in the hyperbolic 3-space (cf. [11]) and the Riemannian 3-sphere. For each Riemannian 3-space form  $N^3$  and a surface  $M^2$  in  $N^3$ , we can consider an adapted frame on  $M^2$  as a map from  $M^2$  to the isometry group  $Isom(N^3)$ . The 'Gauss map' of  $M^2$  to  $S^2(=SO(3)/SO(2))$  is defined from the 'rotational part' (i.e., SO(3)-part) of the adapted framing map. (For example,  $Isom(E^3) = R^3 \rtimes SO(3)$ .)

On the other hand, Nishikawa and the second author [8] proved the Lorentzian version of the Kenmotsu representation formula for spacelike surfaces in the Minkowski 3-space  $L^3$  (cf. [12]). Here  $\text{Isom}(L^3) = R^3 \rtimes SO_0(1,2)$  and hence the Gauss map is a map to the upper hyperboloid  $H^2$  (=  $SO_0(1,2)/SO(2)$ ). In this paper, we introduce the Kenmotsu type representation formula for spacelike surfaces in the Lorentzian 3-space form of constant curvature 1, that is, the de Sitter 3-space  $S_1^3$ . A similar formula in the anti-de Sitter 3-space has been already given in [6].

## 1. De Sitter 3-space $S_1^3$

The de Sitter 3-space  $S_1^3$  is defined as the semi-sphere in the Minkowski 4space  $L^4$  of radius 1. As in [9] and [1], it is convenient to use the complex special linear group SL(2; C), which is the double cover of  $SO_0(1,3)$ , as the group of isometries of  $S_1^3$ . Put

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