# OSCILLATION RESULTS FOR LINEAR MATRIX HAMILTONIAN SYSTEMS 

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#### Abstract

In this paper we present new oscillation criteria in terms of the coefficient functions for the matrix linear Hamiltonian systems $X^{\prime}=A(t) X+B(t) Y, Y^{\prime}=C(t) X-$ $A^{*}(t) Y$, which are not contained in our recent paper [15], and improve the main results in [15] to some extent.


1. Introduction. Consider the linear Hamiltonian system

$$
\left\{\begin{array}{l}
X^{\prime}=A(t) X+B(t) Y  \tag{1.1}\\
Y^{\prime}=C(t) X-A^{*}(t) Y,
\end{array} \quad t \geq t_{0}\right.
$$

where $X(t), Y(t), A(t), B(t), C(t)$ are $n \times n$ real continuous matrix functions such that $B(t)$ and $C(t)$ are symmetric and $B(t)$ is positive definite, i.e., $B(t)>0$ for $t \geq t_{0}$. By $M^{*}$ we mean the transpose of the matrix $M$.

For any two solutions $X_{1}(t), Y_{1}(t)$ and $X_{2}(t), Y_{2}(t)$ of (1.1) the Wronskian $X_{1}^{*}(t) Y_{2}(t)-Y_{1}^{*}(t) X_{2}(t)$ is a constant matrix. In particular, for any solution $X(t), Y(t)$ of $(1.1), X^{*}(t) Y(t)-Y^{*}(t) X(t)$ is a constant matrix. We now recall for the sake of convenience of reference the following definitions from the earlier literature.

Definition 1.1. A solution $X(t), Y(t)$ of (1.1) is said to be nontrivial if $\operatorname{det} X(t) \neq 0$ for at least one $t \in\left[t_{0}, \infty\right)$.

Definition 1.2. A nontrivial solution $X(t), Y(t)$ of (1.1) is said to be prepared if, for every $t \in\left[t_{0}, \infty\right)$,

$$
\begin{equation*}
X^{*}(t) Y(t)-Y^{*}(t) X(t)=0 \tag{1.2}
\end{equation*}
$$

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