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OSCILLATION RESULTS FOR LINEAR MATRIX HAMILTONIAN SYSTEMS

YUAN GONG SUN AND FANWEI MENG

ABSTRACT. In this paper we present new oscillation criteria in terms of the coefficient functions for the matrix linear Hamiltonian systems X' = A(t)X + B(t)Y, $Y' = C(t)X - A^*(t)Y$, which are not contained in our recent paper [15], and improve the main results in [15] to some extent.

1. Introduction. Consider the linear Hamiltonian system

(1.1)
$$\begin{cases} X' = A(t)X + B(t)Y \\ Y' = C(t)X - A^*(t)Y, \end{cases} \quad t \ge t_0$$

where X(t), Y(t), A(t), B(t), C(t) are $n \times n$ real continuous matrix functions such that B(t) and C(t) are symmetric and B(t) is positive definite, i.e., B(t) > 0 for $t \ge t_0$. By M^* we mean the transpose of the matrix M.

For any two solutions $X_1(t)$, $Y_1(t)$ and $X_2(t)$, $Y_2(t)$ of (1.1) the Wronskian $X_1^*(t) Y_2(t) - Y_1^*(t)X_2(t)$ is a constant matrix. In particular, for any solution X(t), Y(t) of (1.1), $X^*(t)Y(t) - Y^*(t)X(t)$ is a constant matrix. We now recall for the sake of convenience of reference the following definitions from the earlier literature.

Definition 1.1. A solution X(t), Y(t) of (1.1) is said to be nontrivial if det $X(t) \neq 0$ for at least one $t \in [t_0, \infty)$.

Definition 1.2. A nontrivial solution X(t), Y(t) of (1.1) is said to be prepared if, for every $t \in [t_0, \infty)$,

(1.2)
$$X^*(t)Y(t) - Y^*(t)X(t) = 0.$$

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