

# The quasi-sure existence of solutions for differential equations on Wiener space

By

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## 1. Introduction

A.B. Cruzeiro [3] proved the almost-sure existence of solutions for differential equations on the Wiener space. In this paper, we extend the almost-sure existence to the *quasi-sure existence*, that is, the existence of solutions for all initial values except in a set of  $(r, p)$ -capacity 0 for all  $r \geq 0$  and  $p > 1$ . Here the capacity is associated with the Ornstein-Uhlenbeck operator. To show the quasi-sure existence we use the notion of Sobolev spaces of Banach valued functions (see Shigekawa [13] and Denis [4]). To be precise, let  $(X, H, \mu)$  be an abstract Wiener space and  $A$  be a vector field on  $X$  which is a smooth mapping from  $X$  into  $H$  in the sense of Malliavin. Then under some conditions for  $A$ , which will be stated precisely in Theorem 5.5 below, the solutions  $V_t(x)$  of the following differential equation exist for all  $t \in \mathbf{R}$ , quasi everywhere  $x$  (q.e.  $x$ ).

$$(1.1) \quad \begin{cases} (dV_t/dt)(x) = A(V_t(x) + x), \\ V_0(x) = 0. \end{cases}$$

We first consider (1.1) in finite dimensional case. We show that for any  $k \in \mathbf{N}$ ,  $(L^k V_t)$  exists for all  $t \in \mathbf{R}$ ,  $\mu$ -a.e.  $x$  and thereby  $(V_t)$  admits a quasi-continuous modification as a  $C([0, T] \rightarrow X)$ -valued function for any  $T > 0$ . In finite dimensional case, one point has a positive  $(r, p)$ -capacity for sufficiently large  $r$  and  $p$ . Therefore we can show that a solution to (1.1) exists for every initial value  $x \in X$ . To deal with  $(L V_t)$ , for example, we have to consider the following differential equation:

$$(1.2) \quad \frac{d}{dt} V_t(x) = B(V_t(x) + x),$$

$$(1.3) \quad \frac{d}{dt} \nabla V_t(x) = \nabla B(V_t(x) + x) \cdot \nabla V_t(x) + \nabla B(V_t(x) + x),$$