

TRACES OF INTERTWINERS FOR QUANTUM GROUPS AND DIFFERENCE EQUATIONS, I

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0. Introduction. This paper begins a series of papers whose goal is to establish a representation-theoretic interpretation of the quantum Knizhnik-Zamolodchikov-Bernard (qKZB) equations and to use this interpretation to study solutions of these equations. It was motivated by the recent work on the qKZB equations in [Fe], [FeTV1], [FeTV2], [MuV], [FeV2]–[FeV5] and by the theory of “quantum conformal blocks” that began with the classical paper [FR].

0.1. The qKZB equations in [Fe] are difference equations with respect to an unknown function $f(z_1, \dots, z_N, \lambda, \tau, \mu, p)$ with values in $V_1 \otimes \dots \otimes V_N \otimes V_N^* \otimes \dots \otimes V_1^*$, where V_i are suitable finite-dimensional representations of the quantum group $U_q(\mathfrak{g})$ (\mathfrak{g} is a simple Lie algebra), $z_i, p, \tau \in \mathbb{C}$, and λ, μ are weights for \mathfrak{g} .

The qKZB equations are a q -deformation of the Knizhnik-Zamolodchikov-Bernard (KZB) differential equations and an elliptic analogue of the quantum Knizhnik-Zamolodchikov (qKZ) difference equations, which are, in turn, generalizations of the usual (trigonometric) Knizhnik-Zamolodchikov (KZ) equations.

It is proved in [FeTV2] (using an integral representation of solutions) that for $\mathfrak{g} = \mathfrak{sl}_2$ the monodromy of the qKZB equations is given by the dual qKZB equations, which are obtained from the qKZB equations by interchanging (λ, τ) with (μ, p) . This fact generalizes the monodromy theorems for the KZB and qKZ equations: the monodromy of the KZB differential equations is the trigonometric degeneration of the qKZB equations (which involves dynamical R -matrices without spectral parameter) (see, e.g., [K3]), and the monodromy of the qKZ equations is given by elliptic dynamical R -matrices (but there is no difference equation) (see [TV1], [TV2]; see also [FR]).

The self-duality of the qKZB equations leads one to expect that they should have symmetric solutions $u_{V_1, \dots, V_N}(z, \lambda, \tau, \mu, p)$, that is, such that $u_{V_1, \dots, V_N}(z, \lambda, \tau, \mu, p) = u_{V_N^*, \dots, V_1^*}(z, \mu, p, \lambda, \tau)$, where u^* is the dual of u (considered as an endomorphism of $V_1 \otimes \dots \otimes V_N$). Such a solution u (for $\mathfrak{g} = \mathfrak{sl}_2$) was constructed in [FeV3] and [FeTV2] by an explicit integral formula. It is called the universal hypergeometric function. This function has many interesting properties, in particular the $SL(3, \mathbb{Z})$ -symmetry (see [FeV2], [FeV4], and [FeV5]), where the group $SL(3, \mathbb{Z})$ acts on the lattice \mathbb{Z}^3 generated by the periods $1, \tau, p$. A consequence of this symmetry

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