CENTROID BODIES AND THE CONVEXITY OF AREA FUNCTIONALS

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Abstract

We introduce a new volume definition on normed vector spaces. We show that the induced k-area functionals are convex for all k. In the particular case k=2, our theorem implies that Busemann's 2-volume density is convex, which was recently shown by Burago-Ivanov. We also show how the new volume definition is related to the centroid body and prove some affine isoperimetric inequalities.

1. Introduction and statement of main results

In a finite-dimensional Euclidean space, there is only one natural way to measure volumes of k-dimensional manifolds. Similarly, there is basically only one natural volume definition on a Riemannian manifold. In contrast to this, measuring volumes of submanifolds in a finite-dimensional normed space (or more generally on Finsler manifolds) is a more subtle subject. Different aspects of the Euclidean volume give rise to different volume measurements.

One natural way of defining volumes is to consider submanifolds in a normed space as metric spaces and to take the corresponding Hausdorff measure. This gives rise to Busemann's definition of volume. Many basic questions, like minimality of flat submanifolds, are still open. Recently, some progress was made by Burago and Ivanov [11] who have shown that flat 2-dimensional regions are minimal (see Corollary 1.4 for the precise statement).

A second well-known volume measurement is Holmes-Thompson volume, which equals the symplectic volume of the disc bundle. The use of symplectic geometry gives rise to a number of interesting results. It was shown recently by Ludwig [23] that the Holmes-Thompson surface area can be uniquely characterized by a valuation property. However, Holmes-Thompson volume lacks some basic convexity properties.

In geometric measure theory it is common to use Gromov's mass*, which has very strong convexity properties, but seems less natural from the point of view of convex geometry.

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In this paper, we propose a new natural definition of volume which is based on a version of the well-known centroid body and was inspired by a recent result of Burago-Ivanov [11]. We show that our definition of volume has strong convexity properties. More precisely, it induces convex k-densities for all k. Since the 2-volume density induced by our definition of volume equals the Busemann 2-volume density, we obtain as a corollary Burago-Ivanov's theorem that 2-planes are minimal with respect to Busemann volume.

Let us describe our results in more detail. References for this section are [3] and [33]. We let $\Lambda^k V$ denote the k-th exterior power of V and $\Lambda^k_s V$ the cone of simple k-vectors.

Definition 1.1 (Definition of volume). A definition of volume μ assigns to each normed vector space $(V, \| \cdot \|)$ a norm μ_V on $\Lambda^n V$ (where $n = \dim V$) such that the following two conditions are satisfied:

- i) If V is Euclidean, then μ_V is induced by the usual Lebesgue measure.
- ii) If $f:(V,\|\cdot\|) \to (W,\|\cdot\|)$ is a linear map that does not increase distances, then the induced map $\Lambda^n f:(\Lambda^n V,\mu_V) \to (\Lambda^n W,\mu_W)$ does not increase distances.

If we want to stress the dependence on the norm, we will write μ_B instead of μ_V , where B is the unit ball in $(V, \|\cdot\|)$.

From i) and ii) it follows that the map $(V, \|\cdot\|) \mapsto (\Lambda^n V, \mu_V)$ is continuous with respect to the Banach-Mazur distance.

An equivalent definition is as follows. Let \mathcal{K}_0^s be the space of centrally symmetric compact convex bodies with non-empty interior.

Given a definition of volume definition μ on V, define the functional $\mathcal{V}: \mathcal{K}_0^s \to \mathbb{R}_+$ by

$$\mathcal{V}(B) := \mu_B(B).$$

The functional \mathcal{V} satisfies the following properties:

- i) \mathcal{V} is invariant under linear maps, i.e. $\mathcal{V}(gB) = \mathcal{V}(B)$ for all $g \in \mathrm{GL}(V)$.
- ii) $V(E) = \omega_n$ (the usual volume of the Euclidean unit ball) if E is an ellipsoid.
- iii) If $B \subset B'$, then

$$\frac{\mathcal{V}(B)}{\text{vol }B} \ge \frac{\mathcal{V}(B')}{\text{vol }B'}$$

where vol denotes any Lebesgue measure on V.

Conversely, any functional with these properties defines a definition of volume.

We call V the associated affine invariant.

Definition 1.2 (Main examples of definitions of volume).

i) The Busemann definition of volume [12] has the associated affine invariant

$$\mathcal{V}^b(B) \equiv \omega_n$$
.

It equals the Hausdorff measure of B with respect to the metric induced by B.

ii) Holmes-Thompson definition of volume [20] has associated affine invariant

$$\mathcal{V}^{ht}(B) := \frac{1}{\omega_n} \operatorname{svol}(B \times B^\circ).$$

Here svol denotes the symplectic volume on $V \times V^*$ and $B^{\circ} \subset V^*$ is the polar body of B.

iii) The Benson definition of volume (also called Gromov's mass*, see [6, 19]) has associated affine invariant

$$\mathcal{V}^{m*}(B) := 2^n \frac{\operatorname{vol} B}{\inf_{P \supset B} \operatorname{vol} P}.$$

Here P ranges over all parallelotopes circumscribed to B and vol is any choice of Lebesgue measure on V.

iv) Ivanov's definition of volume [22] has associated affine invariant

$$\mathcal{V}^i(B) := \omega_n \frac{\operatorname{vol} B}{\operatorname{vol} E},$$

where E is the maximal volume ellipsoid inscribed in B (i.e. the John ellipsoid).

Each definition of volume on V induces k-volume densities, i.e. 1-homogeneous, continuous, positive functions on the set of simple k-vectors in V, where $0 \le k \le \dim V$. More precisely, given a simple k-vector a, we put

$$\mu_k(a) := \mu_{\langle a \rangle}(a),$$

where $\langle a \rangle$ is the k-dimensional space spanned by a with the induced norm.

Definition 1.3. A k-volume density μ_k is called *extendibly convex* if it is the restriction of a norm on $\Lambda^k V$.

There are other notions of convexity for k-volume densities. The k-volume density μ_k is called totally convex if for each k-subspace in V, there exists a μ_k -decreasing linear projection onto that subspace. It is called semi-elliptic, if a plane k-disc has minimal μ_k -area among all Lipschitz chains with the same boundary. Semi-ellipticity depends in a subtle way on the choice of the coefficient ring. Semi-ellipticity over \mathbb{R} is equivalent to extendible convexity [10]. This notion is important in geometric measure theory, in particular in the solution of the Plateau problem in normed or metric spaces [1, 4, 19, 34].

In codimension 1, these notions coincide. In general, total convexity implies extendible convexity. We refer to [3] for more details and other notions of convexity.

The k-density induced by the Holmes-Thompson volume is extendibly convex for $k = \dim V - 1$. Busemann-Ewald-Shephard [14] and later Burago and Ivanov [9] gave examples showing that for 1 < k < n - 1, it is not necessarily extendibly convex.

Busemann's volume is also convex in codimension 1, but this is more difficult to show (in fact this is equivalent to Busemann's intersection theorem [13]). An open conjecture (which appears as problem number 10 on Busemann-Petty's list [15] of problems in convex geometry) states that Busemann's definition of volume induces extendibly convex k-volume densities for all k. The case k = 2 of this conjecture was recently confirmed by Burago and Ivanov [11].

Gromov's mass* and Ivanov's definition of volume have the best convexity properties, as the induced k-volume densities are totally convex for all k [6, 19, 22].

For closely related results on the minimality of totally geodesic submanifolds of Finsler manifolds we refer to [2, 7, 21, 31].

The aim of the present paper is to introduce a new definition of volume which has strong convexity properties. For simplicity, we will use a fixed Lebesgue measure vol on V. Let $V(K_1, \ldots, K_n)$ denote the associated mixed volume of the compact convex bodies K_1, \ldots, K_n . We will follow the usual notation and write

$$V_i(K,L) := V(K[n-i], L[i]) = V(\underbrace{K, \dots, K}_{n-i}, \underbrace{L, \dots, L}_{i}).$$

The projection body of a compact convex body $K \subset V$ will be denoted by $\Pi K \subset V^*$, see the next section for the definition and some properties. Our main theorem is the following.

Theorem 1. Let

(1)
$$\mathcal{V}(B) := \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \sup_{L \in \mathcal{K}(V)} \left\{ \operatorname{svol}(B \times \Pi L) | V_1(L, B) = 1 \right\}.$$

Then V is the associated affine invariant of a definition of volume. The induced k-volume densities are extendibly convex for all k. Moreover,

$$\mathcal{V}(B) \ge \mathcal{V}^{ht}(B)$$

for all unit balls B, with equality precisely for ellipsoids.

To the best of our knowledge, only two other definitions of volume with extendibly convex densities were known previously, namely Gromov's mass* and Ivanov's definition of volume.

Theorem 1 implies a recent result by Burago and Ivanov.

Corollary 1.4 (Burago-Ivanov, [11]). The 2-volume density induced by Busemann's definition of volume is extendibly convex.

We will also show (Proposition 6.4) that the stronger inequality $\mathcal{V}(B) \geq \mathcal{V}^b(B)$ is equivalent to Petty's conjectured projection inequality (Conjecture 2.2).

Our second main theorem establishes a link between our new definition of volume, the centroid body and random simplices.

Recall that the support function of a convex body $K \subset V$ is the function $h(K,\cdot): V^* \to \mathbb{R}, \xi \mapsto \sup_{x \in K} \langle \xi, x \rangle$.

Theorem 2 (Alternative description of \mathcal{V}). Let $B \subset V$ be the unit ball of some norm. Let ν be a probability measure on B° . Define a convex body $\Gamma_{\nu}B^{\circ} \subset V^{*}$ by

$$h(\Gamma_{\nu}B^{\circ}, u) := \int_{B^{\circ}} |\langle \xi, u \rangle| d\nu(\xi), \quad u \in V.$$

i) We have

$$\mathcal{V}(B) = \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \left(\frac{n}{2}\right)^n \sup_{\nu \in \operatorname{Prob}(B^\circ)} \operatorname{svol}(B \times \Gamma_{\nu} B^\circ).$$

- ii) Let $[0, \xi_1, \dots, \xi_n]$ be the simplex spanned by $\xi_1, \dots, \xi_n \in V^*$. Then $\operatorname{vol}(\Gamma_{\nu}B^{\circ}) = 2^n \int_{B^{\circ}} \dots \int_{B^{\circ}} \operatorname{vol}[0, \xi_1, \dots, \xi_n] d\nu(\xi_1) \dots d\nu(\xi_n)$.
- iii) There exists a unique even probability measure on B° which maximizes vol $\Gamma_{\nu}B^{\circ}$. It is supported in the set Ext B° of extremal points of B° .

Remark: if ν is the uniform measure on B° , then $\Gamma_{\nu}B^{\circ} = \Gamma B^{\circ}$, the well-known centroid body [18, 24, 25]. In general, we call $\Gamma_{\nu}B^{\circ}$ the centroid body with respect to ν .

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2. Notations and background

We refer to the books by Schneider [30] and Gardner [18] for information on convexity and the Brunn-Minkowski theory. Let us recall some notions and theorems which will be used later on.

Let V be a real vector space of dimension n. The space of compact convex bodies in V is denoted by $\mathcal{K}(V)$. The space of symmetric compact convex bodies with non-empty interior will be denoted by $\mathcal{K}_0^s(V)$. The convex hull of a set $X \subset V$ will be denoted by conv X.

A set $B \subset \mathcal{K}_0^s(V)$ is the unit ball of some norm on V and vice versa. If B = E is an ellipsoid, then the corresponding norm is Euclidean.

Each $K \in \mathcal{K}(V)$ may be described by its support function $h(K, \xi) := \sup_{x \in K} \xi(x), \xi \in V^*$. For $B \in \mathcal{K}_0^s$, the radial function is defined by $\rho(B, v) := \sup\{\lambda \geq 0, \lambda v \in B\}, v \in V, v \neq 0$. Note that h is 1-homogeneous, while ρ is (-1)-homogeneous.

The polar body of $B \in \mathcal{K}_0^s(V)$ is defined by

$$B^{\circ} := \{ \xi \in V^* : \xi(x) \le 1, \forall x \in B \} \subset V^*.$$

We have

$$h(B,\xi) = \frac{1}{\rho(B^{\circ},\xi)}, \xi \in V^*, \xi \neq 0.$$

The mixed volume of compact convex bodies will be denoted by $V(K_1, \ldots, K_n)$ and we will abbreviate $V_i(K, L) := V(K[n-i], L[i])$. We will use the following inequality of Minkowski, which is a special case of the Alexandrov-Fenchel inequality:

$$V_1(K, L)^n \ge \operatorname{vol}(K)^{n-1} \operatorname{vol}(L).$$

If K, L contain inner points, then equality holds if and only if K and L are homothetic.

Let us also recall the Brunn-Minkowski inequality:

$$\operatorname{vol}(\lambda K + (1 - \lambda)L)^{\frac{1}{n}} \ge \lambda \operatorname{vol}(K)^{\frac{1}{n}} + (1 - \lambda)\operatorname{vol}(L)^{\frac{1}{n}}, \quad 0 \le \lambda \le 1.$$

If K and L contain interior points and $0 < \lambda < 1$, then equality holds if and only if K and L are homothetic.

The space $V \times V^*$ admits a symplectic volume form svol [17]. If vol is any choice of Lebesgue measure on V and vol* is the dual Lebesgue measure on V^* , then svol = vol × vol*.

Let V be a vector space, $\Omega \in \Lambda^n V^*$ a volume form and $K \in \mathcal{K}(V)$. The projection body [18] $\Pi K \in \mathcal{K}(V^*)$ is defined as follows. Let $v \in V, v \neq 0$. Then $i_v \Omega := \Omega(v, \cdot)$ is a volume form on the quotient space $V/\mathbb{R} \cdot v$ and $h(\Pi K, v) := \operatorname{vol}(\pi_v K, i_v \Omega)$, where $\pi_v : V \to V/\mathbb{R} \cdot v$ is the quotient map, defines the support function of ΠK . We will write $\Pi^{\circ} K := (\Pi K)^{\circ}$ for the polar body of ΠK .

Let us recall a well-known geometric inequality related to the projection body.

Theorem 2.1 (Petty's projection inequality, [29]). Let $K \subset V$ be a compact convex body and $E \subset V$ an ellipsoid. Then

$$\operatorname{vol}(K)^{n-1}\operatorname{vol}\Pi^{\circ}K \leq \operatorname{vol}(E)^{n-1}\operatorname{vol}\Pi^{\circ}E$$

with equality precisely for ellipsoids.

The following conjecture is a strengthening of Petty's projection inequality. We refer to [16, 26, 28, 29] for more information and equivalent formulations.

Conjecture 2.2 (Petty's conjectured projection inequality). Let K be a compact convex body in V and $E \subset V$ an ellipsoid. Then

$$\operatorname{vol}(\Pi K)\operatorname{vol}(K)^{1-n} \ge \operatorname{vol}(\Pi E)\operatorname{vol}(E)^{1-n}$$

with equality precisely for ellipsoids.

The centroid body $\Gamma K \in \mathcal{K}(V)$ of a compact convex K with non-empty interior is defined by

$$h(\Gamma K, \xi) = \frac{1}{\operatorname{vol} K} \int_K |\langle \xi, u \rangle| du, \quad \xi \in V^*.$$

It satisfies the Busemann-Petty centroid inequality [18, 27, 32]

(2)
$$\operatorname{vol}(\Gamma K) \ge \left(\frac{2\omega_{n-1}}{(n+1)\omega_n}\right)^n \operatorname{vol} K,$$

with equality precisely for ellipsoids centered at the origin.

Let V be a Euclidean vector space with unit sphere S^{n-1} . The *cosine* transform is defined by

$$Cf(v) := \int_{S^{n-1}} |\langle u, v \rangle| f(u) d\sigma(u), \quad f \in C(S^{n-1}).$$

where $d\sigma$ denotes the spherical Lebesgue measure. On the space of even, smooth functions, the cosine transform is a bijection. The cosine transform extends to measures on the sphere by

$$C\nu(v) := \int_{S^{n-1}} |\langle u, v \rangle| d\nu(u).$$

The cosine transform is injective on the space of even measures on S^{n-1} ([18], Appendix C.2).

The space of probability measures on a topological space X will be denoted by Prob(X).

3. Proof of Theorem 2

Let $B \subset V$ be the unit ball of some norm. By ([30], 5.3.38),

(3)
$$\operatorname{vol}(\Gamma_{\nu}B^{\circ}) = 2^{n} \int_{B^{\circ}} \cdots \int_{B^{\circ}} \operatorname{vol}[0, \xi_{1}, \dots, \xi_{n}] d\nu(\xi_{1}) \dots d\nu(\xi_{n}).$$

Proposition 3.1. There exists a unique even probability measure ν on B° which maximizes $\operatorname{vol}(\Gamma_{\nu}B^{\circ})$.

Proof. By Prokhorov's theorem (see e.g. [8], Thm. 5.1), the space of probability measures on B° is sequentially compact with respect to weak convergence. Since the functional $\nu \mapsto \text{vol}(\Gamma_{\nu}B^{\circ})$ is continuous with respect to weak topology, it follows that the supremum is attained.

If the measure of the interior of B° is positive, then radial projection from B° onto ∂B° (with the origin mapped to an arbitrary boundary point) of ν will increase our functional, hence each optimal measure ν

must be concentrated on the boundary. Moreover, replacing ν by its even part ν^{ev} does not change Γ_{ν} , hence we may assume that ν is even, i.e. invariant under central symmetry.

Let $\nu, \tau \in \text{Prob}(\partial B^{\circ})$ be even measures and $0 < \lambda < 1$. Then $\Gamma_{(1-\lambda)\nu+\lambda\tau}B^{\circ} = (1-\lambda)\Gamma_{\nu}B^{\circ} + \lambda\Gamma_{\tau}B^{\circ}$. By the Brunn-Minkowski inequality, it follows that

$$\left(\operatorname{vol}\Gamma_{(1-\lambda)\nu+\lambda\tau}B^{\circ}\right)^{\frac{1}{n}} \geq (1-\lambda)\operatorname{vol}(\Gamma_{\nu}B^{\circ})^{\frac{1}{n}} + \lambda\operatorname{vol}(\Gamma_{\tau}B^{\circ})^{\frac{1}{n}}.$$

This shows that the function $\nu \mapsto \operatorname{vol}(\Gamma_{\nu}B^{\circ})^{\frac{1}{n}}$ is concave on the space of even measures on ∂B° . If $\operatorname{vol}\Gamma_{\nu}B^{\circ} > 0$, then equality in the above inequality holds if and only if $\Gamma_{\nu}B^{\circ}$ is homothetic to $\Gamma_{\tau}B^{\circ}$, i.e. $\Gamma_{\nu}B^{\circ} = t\Gamma_{\tau}B^{\circ} + v$ for $t > 0, v \in V$.

We claim that this is possible only if $\nu = \tau$. Indeed, since $\Gamma_{\nu}B^{\circ}$ and $\Gamma_{\tau}B^{\circ}$ are centrally symmetric, v=0. Choose a Euclidean scalar product on V^* with unit sphere S^{n-1} . Let $\tilde{\nu}, \tilde{\tau}$ be the push-forwards of ν and τ under the radial projection $\partial B^{\circ} \to S^{n-1}$. From $\Gamma_{\nu}B^{\circ} = t\Gamma_{\tau}B^{\circ}$ and from the injectivity of the cosine transform on even measures we deduce that $d\tilde{\nu} = td\tilde{\tau}$ and hence $\nu = t\tau$. Since ν and τ are probability measures, t=1.

From this the uniqueness of the maximum follows easily. q.e.d.

Recall that a point x in a compact convex body K is called an *extreme* point if it cannot be written as $x = \frac{a+b}{2}$ with $a, b \in K, a \neq b$. The set of extremal points is denoted by Ext K. We refer to [5] for more information.

Proposition 3.2. Let B be a unit ball. The even measure ν such that $\operatorname{vol} \Gamma_{\nu} B^{\circ}$ is maximal is concentrated in the set $\operatorname{Ext} B^{\circ}$ of extremal points.

Proof. Let

$$\Delta := \left\{ (\lambda_1, \dots, \lambda_{n+1}) \in \mathbb{R}^{n+1} | \lambda_i \ge 0, \sum_i \lambda_i = 1 \right\}$$

be the standard simplex. By Minkowski's theorem ([5], Thm. II.3.3), $B^{\circ} = \text{conv Ext } B^{\circ}$. Carathéodory's theorem ([5], Thm. I.2.3) implies that the continuous map

$$(\operatorname{Ext} B^{\circ})^{n+1} \times \Delta \to B^{\circ}$$
$$(\eta_1, \dots, \eta_{n+1}, \lambda_1, \dots, \lambda_{n+1}) \mapsto \sum_i \lambda_i \eta_i$$

is onto.

We fix a measurable right inverse $\xi \mapsto (\eta_1(\xi), \dots, \eta_{n+1}(\xi), \lambda_1(\xi), \dots, \lambda_{n+1}(\xi))$ of this map. Then each $\lambda_i : B^{\circ} \to \mathbb{R}$ is a non-negative measurable function and each $\eta_i : B^{\circ} \to \operatorname{Ext} B^{\circ}$ is a measurable map.

Let $\nu_i := \nu \perp \lambda_i$ be the measure on B° with density function λ_i with respect to ν . Define a probability measure $\tilde{\nu}$ on Ext $B^{\circ} \subset B^{\circ}$ by

$$\tilde{\nu} := \sum_{i=1}^{n+1} (\eta_i)_* \nu_i,$$

where $(\eta_i)_*$ denotes the push-forward.

If $f: B^{\circ} \to \mathbb{R}$ is a convex function, then

$$\int_{B^{\circ}} f(\xi) d\nu(\xi) = \int_{B^{\circ}} f\left(\sum_{i} \lambda_{i}(\xi) \eta_{i}(\xi)\right) d\nu(\xi)$$

$$\leq \int_{B^{\circ}} \sum_{i} \lambda_{i}(\xi) f(\eta_{i}(\xi)) d\nu(\xi)$$

$$= \int_{B^{\circ}} \sum_{i} f(\eta_{i}(\xi)) d\nu_{i}(\xi)$$

$$= \int_{B^{\circ}} f(\xi) d\tilde{\nu}(\xi).$$

Since the function $\operatorname{vol}[0, \xi_1, \dots, \xi_n]$ is convex in each variable ξ_i , it follows from (3) that

$$\operatorname{vol} \Gamma_{\nu} B^{\circ} \leq \operatorname{vol} \Gamma_{\tilde{\nu}} B^{\circ}.$$

By the uniqueness of the optimal measure, ν equals the even part of $\tilde{\nu}$ and is therefore concentrated on Ext B° .

Proposition 3.3. We have

$$\sup_{\nu \in \operatorname{Prob}(B^{\circ})} \operatorname{vol} \Gamma_{\nu} B^{\circ} = \left(\frac{2}{n}\right)^{n} \sup \left\{ \operatorname{vol} \Pi L : L \in \mathcal{K}(V), V_{1}(L, B) = 1 \right\}.$$

Proof. We will use an auxiliary scalar product on V, which allows us to identify V and V^* . Let $\nu \in \operatorname{Prob}(B^{\circ})$ maximize $\operatorname{vol} \Gamma_{\nu} B^{\circ}$. We may assume that ν is concentrated on the boundary of B° and even.

Let $\tilde{\nu}$ be the push-forward of ν under the radial projection $\partial K^{\circ} \to S^{n-1}$.

By the solution of Minkowski's problem applied to $\tilde{\nu}$, $\Gamma_{\nu}B^{\circ}$ is a projection body, say $\Gamma_{\nu}B^{\circ} = \Pi \tilde{L}$ for some centrally symmetric convex body $\tilde{L} \subset V$.

Then for $u \in V$

$$\begin{split} h(\Gamma_{\nu}B^{\circ},u) &= \int_{\partial B^{\circ}} |\langle \xi,u\rangle| d\nu(\xi) \\ &= \int_{S^{n-1}} \rho(B^{\circ},\xi) |\langle \xi,u\rangle| d\tilde{\nu}(\xi). \end{split}$$

On the other hand,

$$h(\Pi \tilde{L}, u) = \frac{1}{2} \int_{S^{n-1}} |\langle \xi, u \rangle| dS_{n-1}(\tilde{L}, \xi),$$

where $S_{n-1}(\tilde{L},\cdot)$ is the surface area measure of \tilde{L} .

Using the injectivity of the cosine transform on even measures on the sphere, we find

$$d\tilde{\nu} = \frac{1}{2}\rho(B^{\circ}, \cdot)^{-1} \cdot dS_{n-1}(\tilde{L}, \cdot) = \frac{1}{2}h(B, \cdot)dS_{n-1}(\tilde{L}, \cdot).$$

Since $\tilde{\nu}$ is a probability measure, we must have

$$1 = \int_{S^{n-1}} d\tilde{\nu}(\xi) = \frac{1}{2} \int_{S^{n-1}} h(B, \xi) dS_{n-1}(\tilde{L}, \xi) = \frac{n}{2} V_1(\tilde{L}, B).$$

Let $L := \left(\frac{n}{2}\right)^{\frac{1}{n-1}} \tilde{L}$. Then $V_1(L,B) = 1$ and $\operatorname{vol} \Gamma_{\nu} B^{\circ} = \operatorname{vol} \Pi \tilde{L} = \left(\frac{2}{n}\right)^n \operatorname{vol} \Pi L$. Thus we have the inequality

$$\sup_{\nu \in \operatorname{Prob}(B^{\circ})} \operatorname{vol} \Gamma_{\nu} B^{\circ} \leq \left(\frac{2}{n}\right)^{n} \sup \left\{ \operatorname{vol} \Pi L : L \in \mathcal{K}(V), V_{1}(L, B) = 1 \right\}.$$

To prove the inverse inequality, take L with $V_1(L,B)=1$ and set $\tilde{L}:=\left(\frac{2}{n}\right)^{\frac{1}{n-1}}L$. We define $d\tilde{\nu}:=\frac{1}{2}h(B,\cdot)dS(\tilde{L},\cdot)$, which is a probability measure on S^{n-1} . If ν is the push-forward of $\tilde{\nu}$ under the radial projection $S^{n-1}\to\partial B^\circ$, then $\Gamma_{\nu}B^\circ=\Pi\tilde{L}$ and $\mathrm{vol}\,\Gamma_{\nu}B^\circ=\left(\frac{2}{n}\right)^n\mathrm{vol}\,\Pi L$. q.e.d.

4. Proof of Theorem 1

Lemma 4.1. The functional V defined by (1) satisfies the conditions (i)-(iii), hence it is an associated affine invariant of a definition of volume.

Proof. It is easy to check that \mathcal{V} is invariant under $\mathrm{GL}(V)$. Let us compute $\mathcal{V}(B)$ for an ellipsoid B. Since we already know that \mathcal{V} is invariant under $\mathrm{GL}(V)$, we may choose a Euclidean scalar product and take B as its unit ball. By Proposition 3.1, the optimal body L in Theorem 1 is $\mathrm{SO}(n)$ -invariant, hence a multiple of B, say $L=\lambda B$. The condition on the mixed volumes translates to $\lambda^{n-1}\omega_n=1$. The projection body operator is homogeneous of degree n-1, and $\Pi B=\omega_{n-1}B^{\circ}$ hence

$$\mathcal{V}(B) = \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \lambda^{n(n-1)} \operatorname{svol}(B \times \Pi B) = \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \frac{1}{\omega_n^n} \operatorname{vol}(B) \omega_{n-1}^n \operatorname{vol}(B^\circ) = \omega_n.$$

Next, suppose that $B \subset B'$, which implies that $B'^{\circ} \subset B^{\circ}$. Any probability measure ν on B'° can be considered as a probability measure on B° and $\Gamma_{\nu}B^{\circ} = \Gamma_{\nu}B'^{\circ}$. Taking the maximum over such measures

gives

$$\frac{\mathcal{V}(B)}{\operatorname{vol} B} = \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \left(\frac{n}{2}\right)^n \max_{\nu \in \operatorname{Prob}(B^\circ)} \operatorname{vol} \Gamma_{\nu} B^\circ$$

$$\geq \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \left(\frac{n}{2}\right)^n \max_{\nu \in \operatorname{Prob}(B'^\circ)} \operatorname{vol} \Gamma_{\nu} B'^\circ$$

$$= \frac{\mathcal{V}(B')}{\operatorname{vol} B'}.$$

q.e.d.

In order to finish the proof of Theorem 1, it remains to show that the corresponding definition of volume is convex.

Proposition 4.2. The definition of volume μ with associated affine functional V defined by (1) is extendibly convex.

Proof. Recall first that the definition of volume μ induces on each normed vector space (V, B) a k-volume density $\mu_k : \Lambda_s^k V \to \mathbb{R}$ by the formula

$$\mu_k(v_1 \wedge \ldots \wedge v_k) := \mu_W(v_1 \wedge \ldots \wedge v_k),$$

where $W \subset V$ is the k-plane spanned by v_1, \ldots, v_k , endowed with the induced norm.

Using Theorem 2, we obtain the following explicit formula for μ_k :

$$\mu_k(v_1 \wedge \ldots \wedge v_k) = \frac{\omega_k^{k-1}}{\omega_{k-1}^k} \frac{k^k}{k!} \max_{\nu \in \operatorname{Prob}((W \cap B)^\circ)} \left\{ \int_{(W \cap B)^\circ} \ldots \int_{(W \cap B)^\circ} |\langle \eta_1 \wedge \ldots \wedge \eta_k, v_1 \wedge \ldots \wedge v_k \rangle| \, d\nu(\eta_1) \ldots d\nu(\eta_k) \right\}.$$

We define a function $\tilde{\mu}_k$ on $\Lambda^k V$ by

$$\tilde{\mu}_{k}(\tau) := \frac{\omega_{k}^{k-1}}{\omega_{k-1}^{k}} \frac{k^{k}}{k!}
(4) \max_{\nu \in \operatorname{Prob}(B^{\circ})} \left\{ \int_{B^{\circ}} \cdots \int_{B^{\circ}} |\langle \xi_{1} \wedge \ldots \wedge \xi_{k}, \tau \rangle| \, d\nu(\xi_{1}) \ldots d\nu(\xi_{k}) \right\},$$

where $\tau \in \Lambda^k V$. Clearly it is convex. It remains to show that the restriction of $\tilde{\mu}_k$ to the Grassmann cone of simple k-vectors equals μ_k .

Let $0 \neq \tau := v_1 \wedge \ldots \wedge v_k \in \Lambda_s^k V$ and $W := \langle v_1, \ldots, v_k \rangle$. Let $\iota : W \to V$ be the inclusion. The dual map $\iota^* : V^* \to W^*$ is onto. Let $B' := W \cap B \subset W$ and $B'^{\circ} \subset W^*$ its polar. Then

$$B'^{\circ} = \iota^*(B^{\circ}).$$

We may consider τ as an element of $\Lambda^k W$. Then

$$\begin{split} \tilde{\mu}_{k}(\tau) &= \frac{\omega_{k}^{k-1}}{\omega_{k-1}^{k}} \frac{k^{k}}{k!} \\ &\max_{\nu \in \operatorname{Prob}(B^{\circ})} \left\{ \int_{B^{\circ}} \cdots \int_{B^{\circ}} \left| \langle \xi_{1} \wedge \ldots \wedge \xi_{k}, \iota_{*}(\tau) \rangle \right| d\nu(\xi_{1}) \ldots d\nu(\xi_{k}) \right\} \\ &= \frac{\omega_{k}^{k-1}}{\omega_{k-1}^{k}} \frac{k^{k}}{k!} \\ &\max_{\nu \in \operatorname{Prob}(B^{\circ})} \left\{ \int_{B^{\circ}} \cdots \int_{B^{\circ}} \left| \langle \iota^{*}\xi_{1} \wedge \ldots \wedge \iota^{*}\xi_{k}, \tau \rangle \right| d\nu(\xi_{1}) \ldots d\nu(\xi_{k}) \right\} \\ &= \frac{\omega_{k}^{k-1}}{\omega_{k-1}^{k}} \frac{k^{k}}{k!} \\ &\max_{\nu \in \operatorname{Prob}(B^{\circ})} \left\{ \int_{B'^{\circ}} \cdots \int_{B'^{\circ}} \left| \langle \eta_{1} \wedge \ldots \wedge \eta_{k}, \tau \rangle \right| d(\iota^{*})_{*} \nu(\eta_{1}) \ldots d(\iota^{*})_{*} \nu(\eta_{k}) \right\} \\ &= \frac{\omega_{k}^{k-1}}{\omega_{k-1}^{k}} \frac{k^{k}}{k!} \\ &\max_{\nu \in \operatorname{Prob}(B'^{\circ})} \left\{ \int_{B'^{\circ}} \cdots \int_{B'^{\circ}} \left| \langle \eta_{1} \wedge \ldots \wedge \eta_{k}, \tau \rangle \right| d\nu(\eta_{1}) \ldots d\nu(\eta_{k}) \right\} \\ &= \mu_{k}(\tau), \end{split}$$

where the equality in the second to last line follows from the fact that the push-forward map $(\iota^*)_* : \operatorname{Prob}(B^\circ) \to \operatorname{Prob}(B'^\circ)$ is onto. q.e.d.

5. The isoperimetrix

In this section, we will describe the isoperimetrix for the new definition of volume μ . Let us first recall the definition and construction of the isoperimetrix in general, referring to [3, 33] for more information.

Let μ be a definition of volume, (V, B) a normed vector space of dimension n and suppose that the induced (n-1)-volume density μ_{n-1} is convex. We can integrate μ_{n-1} over (n-1)-dimensional submanifolds in V, in particular over the boundary of a compact convex body K (this makes sense even if ∂K is not smooth). In this way we obtain the surface area $A_{\mu}(K)$ with respect to μ . The isoperimetrix $\mathbb{I}_{\mu}B$ is the unique centrally symmetric compact convex body in V such that

$$A_{\mu}(K) = nV_1(K, \mathbb{I}_{\mu}B)$$

for all K

Let us recall the construction of the isoperimetrix. The function $\mu_{n-1}: \Lambda^{n-1}V \to \mathbb{R}$ is convex and 1-homogeneous by assumption. The volume form on V induces an isomorphism $\Lambda^{n-1}V \cong V^*$. We thus

get a convex and 1-homogeneous function on V^* , which is the support function of the isoperimetrix.

In the case of Busemann's definition of volume, the isoperimetrix is (up to a scalar) the polar of the intersection body of B. The isoperimetrix of the Holmes-Thompson definition of volume is (again up to a scalar) the projection body of the polar of the unit ball.

For a finite positive measure τ on a vector space V, we define the convex body $\Gamma \tau \subset V$ by

$$h(\Gamma \tau, \xi) := \int_{V} |\langle \xi, u \rangle| d\tau(u)$$

and call it the *centroid body of* τ . If τ is the normalized volume measure of a compact convex body K, then $\Gamma \tau = \Gamma K$ is the usual centroid body of K.

Proposition 5.1. The isoperimetrix of the definition of volume μ from Theorem 1 is given by the following: for each probability measure ν on V^* , let $\nu^{\#} \in \text{Prob}(V)$ be the push-forward of $\nu \times \cdots \times \nu$ under the map

$$\underbrace{V^* \times \cdots \times V^*}_{n-1} \to \Lambda^{n-1} V^* \cong V,$$
$$\xi_1, \dots, \xi_{n-1} \mapsto \xi_1 \wedge \dots \wedge \xi_{n-1}.$$

Then the isoperimetrix of B with respect to μ is given by

$$\mathbb{I}_{\mu}B = c_n \operatorname{conv} \bigcup_{\nu \in \operatorname{Prob}(B^{\circ})} \Gamma \nu^{\#},$$

where

$$c_n := \frac{\omega_{n-1}^{n-2}}{\omega_{n-2}^{n-1}} \frac{(n-1)^{n-1}}{(n-1)!}.$$

Proof. By (4), $\mu_{n-1} = \tilde{\mu}_{n-1}$ is c_n times the maximum of the support functions of the $\Gamma \hat{\nu}$, where $\hat{\nu}$ is the push-forward of $\nu \in \text{Prob}(B^{\circ})$ under the map $(V^*)^{n-1} \to \Lambda^{n-1}V^*$.

Using the identification $\Lambda^{n-1}V^* \cong V$, we get that the support function of $\mathbb{I}_{\mu}B$ is c_n times the maximum of the support functions of the $\Gamma\nu^{\#}$, where $\nu \in \operatorname{Prob}(B^{\circ})$. The proof is finished by noting that the support function of the convex hull of a union of compact convex sets is the supremum of the support functions.

6. Affine inequalities

Proposition 6.1. Let A be a compact convex body. Then

$$\mathcal{V}(\Pi A) \le \frac{\omega_n^{n-1}}{\omega_n^n} \operatorname{vol} \Pi A (\operatorname{vol} A)^{1-n}.$$

Equality holds if and only if A is homothetic to a projection body.

Proof. For each L with $V_1(L, \Pi A) = 1$ we find, using a well-known symmetry property of the projection body operator ([24], Lemma 6)

$$vol(\Pi L) vol(A)^{n-1} \le V_1(A, \Pi L)^n = V_1(L, \Pi A)^n = 1.$$

Equality holds if and only if ΠL and A are homothetic. Taking the supremum (which is actually a maximum by Theorem 2) over all such L gives

$$\mathcal{V}(\Pi A) \le \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \operatorname{vol}(\Pi A) (\operatorname{vol} A)^{1-n}$$

with equality if and only if A is homothetic to a projection body. q.e.d.

Corollary 6.2. If n = 2, then

$$\mathcal{V}(B) = \omega_2 = \pi$$

for all unit balls B. In particular, the 2-volume density induced by V is Busemann's 2-density.

Proof. In the two-dimensional case, every centrally symmetric body is the projection body of some compact convex body. We may thus write $B = \Pi A$ with A centrally symmetric. Since $\Pi A = 2JA$, where J is rotation by $\frac{\pi}{2}$, it follows that

$$\mathcal{V}(B) = \frac{\pi}{4} \frac{\text{vol}(2JA)}{\text{vol } A} = \pi.$$

q.e.d.

Proposition 6.3. For all unit balls B,

$$\mathcal{V}(B) \ge \mathcal{V}^{ht}(B)$$

with equality precisely for ellipsoids.

Proof. Recall that the curvature image of B is the unique (up to translations) compact convex body ΛB with surface area measure

$$dS_{n-1}(\Lambda B, \cdot) = \frac{\operatorname{vol}(B)}{\operatorname{vol}(B^{\circ})} h(B, \cdot)^{-n-1} d\sigma,$$

where σ is the spherical Lebesgue measure.

Let

$$L := \frac{1}{(\operatorname{vol} B)^{\frac{1}{n-1}}} \Lambda B.$$

Using ([24], Lemmas 3 and 5),

$$V_1(L, B) = \frac{1}{\operatorname{vol} B} V_1(\Lambda B, B) = 1$$

and

$$\Pi L = \frac{1}{\operatorname{vol} B} \Pi \Lambda B = \frac{n+1}{2} \Gamma B^{\circ}.$$

Using the Busemann-Petty centroid inequality (2) we get

$$\mathcal{V}(B) \ge \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \operatorname{svol}(B \times \Pi L) \ge \frac{1}{\omega_n} \operatorname{svol}(B \times B^\circ) = \mathcal{V}^{ht}(B).$$

q.e.d.

Proposition 6.4. The assertion $\mathcal{V}(B) \geq \mathcal{V}^b(B) = \omega_n$ for all B is equivalent to Petty's conjectured projection inequality 2.2.

Proof. Set $L := (\operatorname{vol} B)^{-\frac{1}{n-1}} B$. Then $V_1(L, B) = 1$ and hence

$$\mathcal{V}(B) \ge \frac{\omega_n^{n-1}}{\omega_{n-1}^n} \operatorname{svol}(B \times \Pi L) = \frac{\omega_n^{n-1}}{\omega_{n-1}^n} (\operatorname{vol} B)^{1-n} \operatorname{vol} \Pi B.$$

Assuming Petty's conjectured projection inequality, the right hand side is bounded from below by ω_n .

Conversely, let A be a compact convex body. Assuming $\mathcal{V}(\Pi A) \geq \omega_n$, Proposition 6.1 implies that

$$\frac{\omega_n^{n-1}}{\omega_{n-1}^n} \frac{\operatorname{vol}(\Pi A)}{(\operatorname{vol} A)^{n-1}} \ge \mathcal{V}(\Pi A) \ge \omega_n,$$

with equality for ellipsoids. This is Petty's conjectured projection inequality. q.e.d.

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CENTROID BODIES AND THE CONVEXITY OF AREA FUNCTIONALS 373

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