

## COMPARISON OF THE STATES OF CLOSED LINEAR TRANSFORMATIONS

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Let  $X$  and  $Y$  be Banach spaces and  $T$ , respectively  $S$ , be a bounded linear transformation mapping  $X$  into  $Y$ , respectively  $Y$  into  $X$ . It is well-known that a nonzero complex number  $\lambda$  belongs to the spectrum of  $ST$  precisely when  $\lambda$  belongs to the spectrum of  $TS$ . The main result of §2 shows that for  $\lambda \neq 0$  the states of the operators  $ST - \lambda I_X$ ,  $TS - \lambda I_Y$  agree.

Sufficient conditions are obtained for this same result to hold when  $T$  and  $S$  are unbounded closed linear transformations from  $X$  into  $Y$  and  $Y$  into  $X$  respectively. Section 4 compares spectral decompositions of  $ST$  and  $TS$  when these sufficient conditions are satisfied.

Throughout this paper  $D(A)$  and  $R(A)$  will denote the domain and range of  $A$ . The resolvent of  $A$  will be denoted  $\rho(A)$ , the spectrum  $\sigma(A)$ , the point spectrum  $p(A)$  and the approximate point spectrum  $a(A)$ .  $[X, Y]$  will denote the set of all bounded linear transformations, defined on the Banach space  $X$  into the Banach space  $Y$ . Any other notation used will agree with that of [3]. When no confusion will arise the identity operator will be denoted by  $I$  regardless of the space. The following preliminary result can be easily verified.

PROPOSITION 1.1. *If  $T: D(T) \subset X \rightarrow Y$ ,  $S: D(S) \subset Y \rightarrow X$  and  $\lambda \neq 0$ , then  $\lambda \in p(TS)$  if and only if  $\lambda \in p(ST)$ .*

### 2. Continuous transformations.

PROPOSITION 2.1. *If  $\lambda \neq 0$  then  $\overline{R(ST - \lambda I)} = X$  precisely when  $\overline{R(TS - \lambda I)} = Y$ .*

*Proof.*  $\overline{R(ST - \lambda I)} \neq X$  implies that there exists an  $x' \in X'$ ,  $x' \neq 0$  such that  $x'((ST - \lambda I)(x)) = 0$  for all  $x \in X$ . Consequently for all  $x \in X$ ,  $0 = (ST - \lambda I)'(x'(x)) = (T'S' - \lambda I)(x'(x))$  and  $\lambda \in p(T'S')$ . By Proposition 1.1,  $\lambda \in p(S'T')$  so  $y' \in Y'$ ,  $y' \neq 0$  exists with the property that for each  $y \in Y$ ,  $0 = (S'T' - \lambda I)(y'(y)) = y'((TS - \lambda I)(y))$ . Thus  $\overline{R(TS - \lambda I)} \neq Y$ .

The following is a construction of a "generalized" Banach space in the manner of that of Berberian [2].

Denote by  $\text{glim}$  a fixed "generalized Banach limit" defined for all

bounded sequences of complex numbers and having properties: ([1] — page 34)

- (i)  $\text{glim}(\lambda_n + \mu_n) = \text{glim} \lambda_n + \text{glim} \mu_n$ ;
- (ii)  $\text{glim}(\lambda \lambda_n) = \lambda \text{glim} \lambda_n$ ;
- (iii)  $\text{glim} \lambda_n = \lim \lambda_n$  if  $\{\lambda_n\}$  converges;
- (iv)  $\text{glim} \lambda_n \geq 0$  whenever  $\lambda_n \geq 0$  for each  $n$ .

For a Banach space  $X$ , denote by  $\mathcal{B}(X)$  the set of all sequences  $\{x_n\}$  of elements of  $X$  for which  $\sup \|x_n\| < \infty$ . If for  $s = \{x_n\}$  and  $t = \{y_n\}$  in  $\mathcal{B}(X)$  and complex  $\lambda$  we define  $s + t = \{x_n + y_n\}$ ,  $\lambda s = \{\lambda x_n\}$  and  $\|s\|_1 = \text{glim} \|x_n\|$  it is clear that  $\mathcal{B}(X)$  is a prenormed space. If  $\mathcal{N}(X) = \{s \in \mathcal{B}(X) : \|s\|_1 = 0\}$  then  $\mathcal{P}(X) = \mathcal{B}(X)/\mathcal{N}(X)$  is a normed vector space whose completion will be denoted by  $\mathcal{X}(X)$ . Since  $x \mapsto \{x\} + \mathcal{N}(X)$  is an isomorphism of  $X$  into a closed linear subspace  $X'$  of the Banach space  $\mathcal{X}(X)$ ,  $X$  can be identified with this subspace and  $X'$  is called the generalized extension of  $X$ .

For  $T \in [X, Y]$  define  $\mathcal{B}(T) : \mathcal{B}(X) \rightarrow \mathcal{B}(Y)$  as  $\mathcal{B}(T) : s = \{x_n\} \mapsto \{Tx_n\}$ .  $T$  is bounded so  $\mathcal{B}(T)$  is bounded and  $\|\mathcal{B}(T)\|_1 = \|T\|$ . Moreover,  $\mathcal{B}(T) : \mathcal{N}(X) \rightarrow \mathcal{N}(Y)$  so  $\mathcal{B}(T)$  may be extended to  $\mathcal{P}(X)$  and consequently to  $X'$  to obtain a unique extension  $T' \in [X', Y']$  of  $T$  with  $\|T'\| = \|T\|$ .

For  $T_1, T_2 \in [X, Y]$  and  $S \in [Y, X]$  the following properties can be verified directly:

- (i)  $(T_1 + T_2)' = T_1' + T_2'$ ;
- (ii)  $(\lambda T_1)' = \lambda T_1'$ ;
- (iii)  $(ST_1)' = S'T_1'$ .

The next proposition gives the results which necessitated the preceding construction. For the Hilbert space analogue of this proposition, see Berberian [2], Theorem 1.

**PROPOSITION 2.2.** *Let  $A \in [X, X]$  then  $a(A) = a(A') = p(A)$ .*

*Proof.*  $\lambda \in a(A')$  implies that for each  $\varepsilon > 0$  an  $s \in X'$  exists with  $\|(A' - \lambda I)s\| < \varepsilon \|s\|$ . Since  $\mathcal{P}(X)$  is dense in  $X'$ , it may be assumed that  $s = \{x_n\} \in \mathcal{P}(X)$ . Thus  $\|(A' - \lambda I)s\| = \text{glim} \|(A - \lambda I)x_n\| < \varepsilon \text{glim} \|x_n\|$  so  $0 > \text{glim} [\varepsilon \|x_n\| - \|(A - \lambda I)x_n\|]$ . By property (iv) of  $\text{glim}$  it must be true that for at least one  $n$ ,  $0 < \varepsilon \|x_n\| - \|(A - \lambda I)x_n\|$  and hence for some  $x_n \in X$ ,  $\|(A - \lambda I)x_n\| < \varepsilon \|x_n\|$ , which implies  $\lambda \in a(A)$ .

To complete the proof of this proposition, it suffices to show that  $a(A) \subset p(A')$ . For  $\lambda \in a(A)$ , a sequence  $\{x_n\}$  in  $X$  exists with  $\|x_n\| = 1$  for all  $n$  and  $\|(A - \lambda I)x_n\| \rightarrow 0$ .  $\{x_n\}$  is bounded in norm so  $s = \{x_n\} \in X'$ ,  $\|s\| = 1$  and  $\|(A' - \lambda I)s\| = \text{glim} \|(A - \lambda I)x_n\| = 0$ . Hence  $\lambda \in p(A')$ .

Considering  $T \in [X, Y]$  and  $S \in [Y, X]$  we obtain:

**COROLLARY 2.1.** *If  $\lambda \neq 0$  then  $\lambda \in a(TS)$  if and only if  $\lambda \in a(ST)$ .*

*Proof.* By Proposition 2.2,  $\lambda \in a(TS)$  implies  $\lambda \in p((TS)') = p(T'S')$ . Hence by Proposition 1.1,  $\lambda \in p(S'T') = a(ST)$ .

The preceding corollary together with the result of Propositions 1.1 and 2.1 prove the following theorem. The classification of states of a linear operator may be found in [5].

**THEOREM 2.1.** *If  $T \in [X, Y]$ ,  $S \in [Y, X]$  and  $\lambda \neq 0$ , then the states of  $TS - \lambda I$  and  $ST - \lambda I$  agree.*

*Proof.* To show that one of the operators cannot be in state  $I_3$  while the other is in state  $II_3$ , a theorem of Goldberg [4], Theorem II 4.4, is used which in our case states:

- (i)  $T$  has a bounded inverse if and only if  $R(T^*) = X^*$ .
- (ii)  $T^*$  has a bounded inverse if and only if  $R(T) = Y$ .

**3. Closed transformations.** Let  $T$  be a closed linear transformation with  $D(T)$  and  $R(T)$  both contained in the Banach space  $X$ . Suppose further that  $\rho(T) \neq \phi$ , that  $\alpha \in \rho(T)$  is fixed and  $A \in [X, X]$  is defined by  $A = (T - \alpha I)^{-1}$ . The following theorems are due to Taylor [6].

**THEOREM 3.1.** *Suppose  $\mu$  and  $\lambda$  are complex numbers satisfying  $(\lambda - \alpha)\mu = 1$ :*

- (i) *If  $x \in X$  and  $(\mu I - A)x = y$  then  $(T - \lambda I)(\mu x - y) = \mu^{-1}y$ ;*
- (ii) *If  $x \in D(T)$  and  $(T - \lambda I)x = y$  then  $(\mu I - A)x = \mu Ay$ .*

*Furthermore,  $\mu I - A$  is 1-1 precisely when  $T - \lambda I$  is 1-1 and on the common domain of their inverses  $(\mu I - A)^{-1} = \mu^{-2}[\mu I + (T - \lambda I)^{-1}]$  and  $(T - \lambda I)^{-1} = \mu(\mu I - A)^{-1}A = \mu A(\mu I - A)^{-1}$ .*

**THEOREM 3.2.** *Let  $\lambda$  and  $\mu$  satisfy  $(\lambda - \alpha)\mu = 1$ . Then  $\lambda$  belongs to  $\rho(T)$  if and only if  $\mu$  belongs to  $\rho(A)$ .*

The following lemma follows from the closed graph theorem and will be needed often in our development:

**LEMMA 3.1.** *If  $P: D(P) \subset Y \rightarrow Z$  is a closed linear transformation and  $Q \in [X, Y]$  where  $X, Y, Z$  are Banach spaces, then  $PQ$  is closed and if  $R(Q) \subset D(P)$  then  $PQ \in [X, Z]$ .*

For  $T$  closed with  $D(T)$  and  $R(T)$  both in  $X$  and  $0 \neq \alpha \in \rho(T)$  we define  $A = (T - \alpha I)^{-1}$  and  $B = T(T - \alpha I)^{-1}(T - \alpha I^{-1})$ . (By Lemma 3.1,  $B \in [X, X]$ .)

The next three propositions give the substance for a method of referring a pair of closed operators to a pair which are continuous and everywhere defined.

**PROPOSITION 3.1.** *Consider  $T$ ,  $A$ , and  $B$  as defined above and  $0 \neq \alpha \in \rho(T)$ . For  $0 \neq \lambda \neq \alpha$ , let  $\nu = (\lambda/(\lambda - \alpha)^2)$ ,  $\mu = (1/(\lambda - \alpha))$ . Then  $R(B - \nu I) \subset R(T - \lambda I)$ .*

*Proof.* Suppose  $y = (B - \nu I)x$ . Then  $y + \nu x = (T - \alpha I)^{-1}[x + \alpha(T - \alpha I)^{-1}x] \in D(T - \alpha I) = D(T - \lambda I)$  and  $(T - \lambda I)(y + \nu x) + (\lambda - \alpha)(y + \nu x) = x + \alpha(T - \alpha I)^{-1}x$ ; so  $-1/\alpha[(T - \lambda I)(y + \nu x) + (\lambda - \alpha)y] = \mu x - Ax$ . If Theorem 3.1, part (i), is applied, we obtain that  $1/\alpha[(T - \lambda I)(y + \nu x) + (\lambda - \alpha)y] \in R(T - \lambda I)$  so that

$$(1) \quad \begin{aligned} & (T - \lambda I) \left\{ \mu x + \frac{1}{\alpha} [(T - \lambda I)(y + \nu x) + (\lambda - \alpha)y] \right. \\ & \left. + \frac{1}{\mu\alpha} (y + \nu x) \right\} = \frac{-1}{\alpha\nu\mu} y \in R(T - \lambda I). \end{aligned}$$

**PROPOSITION 3.2.** *If  $\lambda \neq 0$  is such that for some  $0 \neq \alpha \in \rho(T)$ ,  $\alpha^2/\lambda \in \rho(T)$  also, then  $R(T - \lambda I) \subset R(B - \nu I)$ .*

*Proof.* We may assume, without loss of generality, that  $\lambda \neq \alpha$ , for if  $0 \neq \alpha \in \rho(T)$  there exists some  $a > 0$  with  $0 \notin \{\mu \mid |\mu - \lambda| < a\} \subset \rho(T)$  and  $\lambda = \alpha + (a/2)e^{i\theta}$ , where  $\theta$  is the argument of  $\alpha$ , will satisfy our hypothesis.

For  $x \in D(T)$ ,  $BTx = x + \alpha Ax + \alpha Bx$ . Consequently, if  $(T - \lambda I)x = y$ , then  $(y - \alpha)Bx = x + \alpha Ax - By$ . Theorem 3.1, part (ii), implies  $(\mu I - A)x = \mu Ay$  so  $(\lambda - \alpha)Bx = \lambda \mu x - \alpha \mu Ay - By$ . Thus

$$\begin{aligned} (B - \nu I)(x + \mu y) &= -\frac{\alpha\nu}{\lambda} Ay - \nu \mu y \\ &= -\frac{\alpha\nu}{\lambda} \left[ A - \frac{1}{(\alpha^2/\lambda - \alpha)} I \right] y. \end{aligned}$$

By hypothesis,  $\alpha^2/\lambda \in \rho(T)$ , so Theorem 3.2 may be used to obtain

$$\frac{1}{(\alpha^2/\lambda - \alpha)} \in \rho(A)$$

and

$$-\frac{\alpha\nu}{\lambda} y = \left[ A - \frac{\lambda}{(\alpha^2 - \alpha\lambda)} I \right]^{-1} (B - \nu I)(x + \mu y).$$

Since  $\left[ A - \frac{\lambda}{(\alpha^2 - \alpha\lambda)} I \right]^{-1}$  and  $B - \nu I$  commute,

$$(2) \quad -\frac{\alpha\nu}{\lambda}y = (B - \nu I)\left[A - \frac{1}{(\alpha^2/\lambda - \alpha)}I\right]^{-1}(x + \mu y) \in R(B - \nu I).$$

The following proposition follows easily by considering equations (1) and (2), together with the result of Theorem 3.2.

**PROPOSITION 3.3.** *Suppose  $\lambda \neq 0$  and for some  $\alpha \neq 0$  in  $\rho(T)$ ,  $\alpha^2/\lambda \in \rho(T)$  also. Then  $T - \lambda I$  is 1-1 precisely when  $B - \nu I$  is 1-1.*

The following theorem is an immediate consequence of the Propositions 3.1, 3.2, 3.3, and the closed graph theorem.

**THEOREM 3.3.** *Let  $T$  be a closed linear operator with  $D(T)$  and  $R(T)$  both contained in the Banach space  $X$ . Suppose  $\lambda \neq 0$  is a complex number with the property that for some  $\alpha \in \rho(T)$ ,  $\alpha^2/\lambda \in \rho(T)$  also, then the state of  $T - \lambda I$  is the same as the state of  $B - \nu I$ .*

For the remainder of this section, we consider a pair of closed linear transformations,  $T: D(T) \subset X \rightarrow Y$  and  $S: D(S) \subset Y \rightarrow X$ , with the property that  $ST$  and  $TS$  are both closed on their respective domains. We assume moreover that  $\rho(TS) \cap \rho(ST) \neq \varnothing$  and for  $\alpha \in \rho(TS) \cap \rho(ST)$  fixed we define:

$$A(ST) = (ST - \alpha I)^{-1}, \quad A(TS) = (TS - \alpha I)^{-1}$$

and

$$B(ST) = ST(ST - \alpha I)^{-1}(ST - \alpha I)^{-1}$$

$$B(TS) = TS(TS - \alpha I)^{-1}(TS - \alpha I)^{-1}.$$

When  $x \in D(T)$ ,  $TA(ST)x = A(TS)Tx$ ; thus  $B(ST)$  and  $B(TS)$  may be rewritten:

$$B(ST) = S(TS - \alpha I)^{-1}T(ST - \alpha I)^{-1} = SA(TS)TA(ST)$$

$$B(TS) = T(ST - \alpha I)^{-1}S(TS - \alpha I)^{-1} = TA(ST)SA(TS).$$

Since  $R(A(ST)) \subset D(T)$  and  $R(A(TS)) \subset D(S)$ , Lemma 3.1 shows that  $TA(ST) \in [X, Y]$  and  $SA(TS) \in [Y, X]$ . By Theorem 2.1, whenever  $\nu \neq 0$ , the state of  $B(TS) - \nu I$  is the same as the state of  $B(ST) - \nu I$ , which gives the main result in this section:

**THEOREM 3.4.** *If  $\lambda \neq 0$  is such that for some  $\alpha \in \rho(ST) \cap \rho(TS)$ ,  $\alpha^2/\lambda \in \rho(ST) \cap \rho(TS)$  also, the state of  $ST - \lambda I$  is the same as the state of  $TS - \lambda I$ .*

It is conjectured that the hypothesis of Theorem 3.4 can be

weakened to simply requiring that  $\rho(ST) \cap \rho(TS) \neq \{0\}$ . A different method of proof would likely be needed, however.

In the remainder of this section we consider conditions on the transformations  $S$  and  $T$  which will ensure that the hypotheses of Theorem 3.4 are fulfilled. We first need the following propositions:

**PROPOSITION 3.4.** *If  $T, S, TS,$  and  $ST$  are closed and  $\lambda \neq 0$  is such that  $\lambda \in \sigma(TS) \cap \rho(ST)$ , then whenever  $\alpha \in \rho(TS) \cap \rho(ST)$ ,*

$$\frac{\alpha^2}{\lambda} \in \sigma(ST).$$

*Proof.* Since  $\lambda \in \rho(ST)$ ,  $ST - \lambda I$  is 1-1; so by Theorem 3.4,  $TS - \lambda I$  is also 1-1, and  $\lambda \in \sigma(TS)$  implies  $\overline{R(TS - \lambda I)} \neq Y$ . For  $0 \neq \alpha \in \rho(TS)$  and  $\nu = \lambda/(\lambda - \alpha)^2$  we have by Proposition 3.1

$$R(B(TS) - \nu I) \subset R(TS - \lambda I)$$

and consequently

$$\overline{R(B(TS) - \nu I)} \neq Y.$$

By Theorem 3.3  $R(B(ST) - \nu I) \neq X$ . If  $\alpha^2/\lambda \in \rho(ST)$ , then

$$R(ST - \lambda I) \subset R(B(ST) - \nu I),$$

so

$$\overline{R(ST - \lambda I)} \neq X.$$

This clearly contradicts our assumption of  $\lambda \in \rho(ST)$ .

**PROPOSITION 3.5.** *If  $T, S, TS,$  and  $ST$  are closed and  $\rho_1,$  respectively  $\rho_2,$  are connected components of  $\rho(ST)$ , respectively  $\rho(TS)$ , then  $(\rho_1 - \rho_2) \cup (\rho_2 - \rho_1) \subset \{0\}$ .*

*Proof.* It suffices to show that both  $\rho_1 \cap \partial\rho_2 \subset \{0\}$ , where  $\partial\rho_2$  denotes the boundary of  $\rho_2$ , and  $\rho_2 \cap \partial\rho_1 \subset \{0\}$ .

To prove the former, suppose  $0 \neq \lambda \in \rho_1 \cap \partial\rho_2$ . Then  $\lambda \in \sigma(TS)$  and there is an open set  $N$  with  $\lambda \in N \subset \rho_1$ . We may therefore construct a sequence  $\lambda_n \in \rho_1 \cap \rho_2$  for all  $n$  with the property that  $\lambda_n$  converges to  $\lambda$ . By Proposition 3.4  $\mu^2/\lambda \in \sigma(ST)$  whenever  $\mu \in \rho(ST) \cap \rho(TS)$ . In particular  $(\lambda_n)^2/\lambda \in \sigma(ST)$  for all  $n$ . This is clearly impossible since  $(\lambda_n)^2/\lambda$  converges to  $\lambda$  and eventually  $(\lambda_n)^2/\lambda \in N$ .

The next two propositions give sufficient conditions for the hypothesis of Theorem 3.4 to be fulfilled.

**PROPOSITION 3.6.** *If  $T, S, TS,$  and  $ST$  are closed and such that there exists a neighborhood of zero intersected with an open half plane about the origin which is a subset of  $\rho(ST) \cap \rho(TS)$  then the state of  $TS - \lambda I$  is the same as the state of  $ST - \lambda I$  whenever  $\mu \neq 0$ .*

*Proof.* Suppose  $D = \{\mu \mid |\mu| < r\} \subset U$  is contained in  $\rho(ST) \cap \rho(TS)$ , where  $U$  denotes the open upper half plane.

Given  $\lambda \neq 0$ , choose  $\alpha$  satisfying

- (i)  $0 < |\alpha| < \min\{r, |\lambda|\}$ ;
- (ii) argument of  $\alpha$ ,  $\arg \alpha$ , is as follows:
  - (a)  $\pi/4$  if  $\arg \lambda = 0$ ;
  - (b)  $\arg \lambda$  if  $0 < \arg \lambda < \pi$ ;
  - (c)  $3\pi/4$  if  $\arg \lambda = \pi$ ;
  - (d)  $\pi/2 + \arg \lambda/4$  if  $\pi < \arg \lambda < 2\pi$ .

By direct calculation, it can be shown that both  $\alpha$  and  $\alpha^2/\lambda$  belong to  $D \subset \rho(ST) \cap \rho(TS)$  and consequently by Theorem 3.4, the states of  $TS - \lambda I$  and  $ST - \lambda I$  agree. It is clear, by the method in which  $\alpha$  was chosen, that our assumption of  $U$  being the open upper half plane involves no loss of generality. Any other open half plane about the origin would simply introduce a change in  $\arg \alpha$ .

Note that if  $S, T, ST,$  and  $TS$  are closed operators in a Hilbert space with both  $ST$  and  $TS$  self-adjoint, the hypotheses of Proposition 3.6 hold.

**PROPOSITION 3.7.** *Let  $T, S, TS,$  and  $ST$  be closed and such that there exists a half plane entirely contained in  $\rho(ST) \cap \rho(TS)$ . Then the state of  $ST - \lambda I$  is the same as the state of  $TS - \lambda I$  whenever  $\lambda \neq 0$ .*

*Proof.* Suppose that  $U$  is a half plane contained in  $\rho(ST) \cap \rho(TS)$ . We may assume, without loss of generality, that

$$U = \{\mu \mid \operatorname{Im}(\mu) > R\} \text{ where } R > 1.$$

For  $\lambda \neq 0$  we choose  $\alpha$  as follows:

- (i) If  $\arg \lambda = 0$ , then  $\arg \alpha = \pi/4$  and  $|\alpha| = \max\{\alpha R, |\lambda|\}$ ;
- (ii) If  $\arg \lambda = \pi$ , then  $\arg \alpha = 3\pi/4$  and  $|\alpha| = \max\{\alpha R, |\lambda|\}$ ;
- (iii) If  $0 < \arg \lambda < \pi$ , then  $\arg \alpha = \arg \lambda$  and

$$|\alpha| = \max\left\{|\lambda|, \frac{\alpha R}{\sin(\arg \lambda)}\right\};$$

- (iv) If  $\pi < \arg \lambda < 2\pi$ , then  $\arg \alpha = \arg \lambda - \pi$  and

$$|\alpha| = \max\left\{|\lambda|, \frac{R}{\sin(\arg \lambda - \pi)}\right\}.$$

It can be demonstrated in a straight forward manner that both  $\alpha$  and  $\alpha^2/\lambda$  are in  $\rho(ST) \cap \rho(TS)$  in each case.

4. Spectral decompositions. The notation in the following discussion is full explained in [5].

**THEOREM 4.1.** *If  $D$  is a bounded Cauchy domain satisfying*

$$\partial D \subset \rho(ST) \cap \rho(TS)$$

*then there exists a pair of closed subspaces  $(X_1, X_2)$  of  $X$  and  $(Y_1, Y_2)$  of  $Y$  such that*

- (i)  $(X_1, X_2)$  completely reduces  $ST$ ;
- (ii)  $(Y_1, Y_2)$  completely reduces  $TS$ ;
- (iii)  $(ST)_1 = ST|_{X_1}$  and  $(TS)_1 = TS|_{Y_1}$  are continuous with domains  $X_1, Y_1$  respectively;
- (iv)  $T: X_i \rightarrow Y_i, S: Y_i \rightarrow X_i, i = 1, 2$ .

*Proof.* Let

$$\begin{aligned}\sigma_1 &= D \cap \sigma_e(ST), \\ \sigma_2 &= D \cap \sigma_e(TS),\end{aligned}$$

where  $\sigma_e$  denotes the extended spectrum of the transformation.  $\sigma_1$  and  $\sigma_2$  are bounded spectral sets for  $ST$  and  $TS$  respectively. Let  $\tau_1 = \sigma_e(ST) - \sigma_1$  and  $\tau_2 = \sigma_e(TS) - \sigma_2$  be their complementary spectral sets.

If  $E(\sigma_1), E(\sigma_2), E(\tau_1)$ , and  $E(\tau_2)$  are the projections associated with these spectral sets with ranges  $X_1, Y_1, X_2$ , and  $Y_2$  respectively, it is well-known, see [5], that statements (i), (ii), and (iii) are satisfied.

For  $x \in X, E(\sigma_1)x \in X_1$  and

$$\begin{aligned}TE(\sigma_1)x &= T \left[ -\frac{1}{2\pi i} \int_{+\partial D} (ST - \lambda I)^{-1} d\lambda \right] x \\ &= \left[ -\frac{1}{2\pi i} \int_{+\partial D} T(ST - \lambda I)^{-1} d\lambda \right] x \\ &= \left[ -\frac{1}{2\pi i} \int_{+\partial D} (TS - \lambda I)^{-1} d\lambda \right] Tx \\ &= E(\sigma_2)Tx.\end{aligned}$$

so  $T: X_1 \rightarrow Y_1$ .

Similarly, if  $x \in X, E(\tau_1)x \in X_2$  and

$$\begin{aligned}TE(\tau_1)x &= T(I - E(\sigma_1))x = Tx - TE(\sigma_1)x \\ &= (I - E(\sigma_2))Tx = E(\tau_2)Tx.\end{aligned}$$

So  $T: X_2 \rightarrow Y_2$ .

In a similar manner  $S: Y_1 \rightarrow X_1$ ,  $S: Y_2 \rightarrow X_2$  which completes the proof of the theorem.

**THEOREM 4.2.** *If  $D$  is a bounded Cauchy domain with*

$$\partial D \subset \rho(ST) \cap \rho(TS)$$

and

$$\sigma_1 = D \cap \sigma_s(ST), \quad \sigma_2 = D \cap \sigma_s(TS),$$

then

$$(\sigma_1 - \sigma_2) \cup (\sigma_2 - \sigma_1) \subset \{0\}.$$

*If in addition  $0 \in D$ , then*

- (i) *the complementary spectral sets  $\tau_1$  and  $\tau_2$  are equal;*
- (ii) *the state of  $ST - \lambda I$  is the same as the state of  $TS - \lambda I$ , whenever  $\lambda \neq 0$ .*

*Proof.* Using the notation of Theorem 4.1, let  $T_i = T|X_i$ ,  $S_i = S|Y_i$ ,  $i = 1, 2$ . Since  $T_i$ ,  $S_i$ ,  $T_i S_i$ , and  $S_i T_i$ ,  $i = 1, 2$ , are restrictions of closed operators to closed subspaces, they are closed. Furthermore,  $S_i T_i = (ST)_i$ ,  $T_i S_i = (TS)_i$  for  $i = 1, 2$ .

By Theorem 4.1,  $S_1 T_1 \in [X_1, X_1]$  and  $T_1 S_1 \in [Y_1, Y_1]$  and therefore satisfy the hypotheses of Theorem 1.1. Thus for  $\lambda \neq 0$ , the state of  $S_1 T_1 - \lambda E(\sigma_1)$  agrees with the state of  $T_1 S_1 - \lambda E(\sigma_2)$ .

When  $0 \in D$  the sets  $\sigma(S_2 T_2) = \tau_1$  and  $\sigma(T_2 S_2) = \tau_2$  are bounded away from zero. Consequently by Proposition 3.6, the state of  $S_2 T_2 - \lambda E(\tau_1)$  agrees with the state of  $T_2 S_2 - \lambda E(\tau_2)$  whenever  $\lambda \neq 0$ .

It can be seen that the above is both necessary and sufficient for the state of  $ST - \lambda I$  to be the same as the state of  $TS - \lambda I$ .

From the preceding theorems we obtain the final results:

**THEOREM 4.3.** *Suppose  $0 \in \rho(TS) \cap \sigma(ST)$  and a bounded Cauchy domain  $D$  exists satisfying:*

- (i)  $\partial D \subset \rho(ST) \cap \rho(TS)$ ;
- (ii)  $0 \in D$ .

*If  $\sigma_1, \dots, \sigma_n$  is a spectral decomposition of  $\sigma_s(ST)$  then  $\sigma_0, \sigma_1, \dots, \sigma_n$  is a spectral decomposition of  $\sigma_s(TS)$  where*

$$\sigma_0 = \{0\}$$

*whenever  $0 \in \sigma(TS) \cap \rho(ST)$ , and is empty otherwise.*

*Moreover, if  $E_i(ST)$  and  $E_i(TS)$  are the projections associated with these spectral sets with ranges  $X_i$  and  $Y_i$  respectively, then*

$$T: X_i \longrightarrow Y_i ;$$

$$S: Y_i \longrightarrow X_i$$

where  $i = 1, \dots, n$ , and when  $0 \in \sigma(TS) \cap \rho(ST)$ ,

$$S: Y_0 \longrightarrow \{0\} .$$

*Proof.* First note that by Theorem 4.2,

$$(\sigma_e(ST) - \sigma_e(TS)) \cup (\sigma_e(TS) - \sigma_e(ST)) \subset \{0\}$$

and since  $\sigma_e(ST)$  and  $\sigma_e(TS)$  are both closed subsets of the complex plane, if  $0 \in \sigma(TS) \cap \rho(ST)$  it must be an isolated point in  $\sigma(TS)$ . This demonstrates that the spectral decomposition  $\sigma_1, \dots, \sigma_n$  of  $\sigma_e(ST)$  gives rise to the spectral decomposition  $\sigma_0, \sigma_1, \dots, \sigma_n$  of  $\sigma_e(TS)$ .

If  $\infty \in \sigma_e(ST)$ , i.e., if  $ST \notin [X, X]$ , assume that  $\infty \in \sigma_n$ . Then  $\sigma_1, \dots, \sigma_{n-1}$  are bounded spectral sets for both  $ST$  and  $TS$ .

Let  $D_i$  be an admissible domain for  $\sigma_i$ ,  $i = 1, \dots, n-1$ . Then

$$E_i(ST) = -\frac{1}{2\pi i} \int_{+\partial D_i} (ST - \lambda I)^{-1} d\lambda$$

and

$$E_i(TS) = -\frac{1}{2\pi i} \int_{+\partial D_i} (TS - \lambda I)^{-1} d\lambda .$$

By Theorem 4.1,

$$T: X_i \longrightarrow Y_i ,$$

$$S: Y_i \longrightarrow X_i ,$$

$i = 1, \dots, n-1$ , moreover  $T, S$  are continuous and everywhere defined on these subspaces.

Further, if  $0 \in \sigma(TS) \cap \rho(ST)$  and  $D_0$  is an admissible domain for  $\sigma_0$ , let  $y \in Y_0$ . By Theorem 4.1,  $y \in D(S)$  and

$$\begin{aligned} Sy &= SE_0(TS)y \\ &= S\left(-\frac{1}{2\pi i} \int_{+\partial D_0} (TS - \lambda I)^{-1} d\lambda\right)y \\ &= \left(-\frac{1}{2\pi i} \int_{+\partial D_0} (ST - \lambda I)^{-1} d\lambda\right)Sy \\ &= 0 . \end{aligned}$$

To show that  $T: X_n \rightarrow Y_n, S: Y_n \rightarrow X_n$  observe that

$$E_n(ST) = I - \sum_{i=1}^{n-1} E_i(ST)$$

and

$$E_n(TS) = I - \sum_{i=0}^{n-1} E_i(TS)$$

where  $E_0(TS) = 0$  if  $0 \in \rho(TS)$ .

When  $T \in [X, Y]$ ,  $S \in [Y, X]$  we clearly have a bounded Cauchy domain

$$D = \{\mu \mid |\mu| < \max(\|ST\|, \|TS\|) + 1\}$$

which satisfies the conditions of Theorem 4.3. Hence:

**COROLLARY 4.1.** *If  $T \in [X, Y]$ ,  $S \in [Y, X]$  and  $0 \notin \rho(TS) \cap \sigma(ST)$  then a spectral decomposition  $\sigma_1, \dots, \sigma_n$  of  $\sigma(ST)$  gives a spectral decomposition  $\sigma_0, \sigma_1, \dots, \sigma_n$  of  $\sigma(TS)$  where*

$$\sigma_0 = \begin{cases} \{0\} & \text{whenever } 0 \in \sigma(TS) \cap \rho(ST) \\ \phi & \text{otherwise.} \end{cases}$$

Moreover, if  $E_i(ST)$  and  $E_i(TS)$  are the projections associated with the spectral sets with ranges  $X_i$  and  $Y_i$  respectively, then  $T: X_i \rightarrow Y_i$ ,  $S: Y_i \rightarrow X_i$ ,  $i = 1, \dots, n$  and when  $0 \in \sigma(TS) \cap \rho(ST)$ ,  $S: Y_0 \rightarrow \{0\}$ .

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